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Editor's Page

How Much Computer Do You Need?

I was recently asked "What computer should I buy?" and of course, my answer was "What do you want to do with it?" This lead to a long discussion and some time spent looking through the many pages of advertising in Byte and The Computer Shopper. We ended up overwhelmed by the number of choices available in today's market. When I bought my first computer the choice was between Commodore, Radio Shack, Apple, or CP/M, but today there are so many products on the market that it is no longer that simple.

When choosing a computer you should first select the software you need, and then get the system which runs that software. A survey of the current software showed that there were more new programs being released for the IBM-PC and its compatibles than for any other system. In fact, there are probably more releases for the IBM-PC than for all the other systems combined! This means that I'll have to recommend the PC or one of its clones for a non-technical user in a normal business office environment, based on the large number of available programs, user's support, and the general needs of an unsophisticated user.

Helping someone else select a system forced me to think about defining what a computer is, and how much computer is really needed. The usual reaction is to attempt to get one system that is powerful enough to fill all our needs, but the complexity and awkwardness of the system increases rapidly with size, and it can be very difficult to perform simple functions with a large system. There will never be the one "perfect computer" which satisfies all needs for everyone, because we each have different needs. In fact, I'll never be satisfied with just one computer because I have a wide range of applications. Besides, two smaller systems enable me to run two entirely different types of operations at the same time, and will probably cost less than one larger multitasking unit.

A better choice is to define the requirements on as low a level as possible, and then combine these requirements into similar groups in order to determine what type of system or systems are required. Some of us are computer nuts who would like to have one of everything to play with, but the limited funds available for computers force us to take a more realistic view of our needs.

My uses can be roughly divided into two areas, which are the business of running this magazine, and personal projects, with a lot of overlap since the magazine is about computers. The business applications include word-processing and phototypesetting from disk to produce the copy, a data base for maintaining subscription records and mailing lists, and a spreadsheet for financial forecasting. These needs can be served by either the original Apple II + I started with, or the two S-100 Z-80 systems running CP/M. I prefer the CP/M systems for the business because of the higher capacity 8″ disks, the software, and the operating system.

My personal projects involve general hardware and software hacking, lear-
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ning additional languages and improving my programming skills, and applying computers for the measurement and control of real world devices. Most of my time has been spent on the magazine, so I haven't been able to do much with my personal projects, but I want to automate my lathe, build a remote weather station, monitor and control a solar heating system, and experiment with robotics. For this I need an open system with good I/O capabilities, an accessible bus, and a flexible operating system. Both the Apple and the CP/M systems work well here, and it is difficult to choose between them. The Apple has the advantage of having BASIC and a reasonably decent monitor in ROM, high resolution graphics, good low-cost assemblers, and reasonably priced cards for A/D and interfacing. The S-100 CP/M system has a better selection of languages, high capacity disks, a more powerful and flexible operating system, and better I/O capabilities, but interfacing cards are more expensive. I intend to continue working with both systems for program development, and then will use SBC's (such as Davidge) and microcontrollers (such as Basicon) for dedicated controllers.

What Can You Do With An Old Computer?
When you finally decide to get a newer, more powerful computer you are faced with the problem of deciding what to do with the old one. Because of the rapid advances, it isn't worth much on the used computer market if it is more than two or three years old, and yet it is still working and too good to throw away. One answer is to use it to relieve your main system from some low-level, time-consuming operations, such as the print spooler described in Piotrowski's article on "Poor Man's Distributed Processing" in this issue.

I'm satisfied with my two eight bit systems for now because I still have a lot to learn, but I would like to upgrade to a 68000 16 bit system in the future—not because I need it, but just for the challenge of new things. One of the things that I really like about the S-100 system is that I can experiment with the 68000 by building the 68008 board described in Kohler's article in the last issue without replacing the whole system.

Right now I have absolutely no desire for an IBM-PC or one of its clones, but I think that their bringing out the PC was of great benefit to hardware hackers. Not that we'll buy their computers, but rather that all the non-technical users are flocking to the IBM-PC standard and dumping non-conforming equipment on the market at fire sale prices! It enables us to pick up great used equipment for very little cost (watch for Kliber's article on his $500 Superbrain in the next issue). You'll have to be able to help yourself when working with this older equipment because the manufacturer will either be out of business or will refuse to support the obsolete equipment.

That's one of the purposes of this magazine—to help you learn to use an assembler and a debugger to patch the operating system, and to provide the means for you to contact others who have experience or documentation for the older systems. This is your magazine...use it!

A New Look For The Journal
This is our second issue with our new three column format. We made this change for easier readability, to improve the layout with larger illustrations and program listings, and to provide for 19th page ads. In addition to the smaller ads, we are also adding classified ads in order to help individuals and smaller companies reach their markets and to make new developments in specialized fields available to our readers. The classified ads are 25 cents per word, paid in advance, and can be charged to your Visa or Master Charge, but we prefer not to take these ads over the phone because of the chance for errors.

Information Is For Sharing
The most important function of a journal is to provide a place for you to share your thoughts, ideas, problems, and solutions. We need your articles, letters, and comments. If you disagree with one of our authors, tell us. If you can expand on something we publish, tell us. If you need the answer to a problem, tell us. What you send doesn't have to be formal or fancy, just get us the information so that we can share it with others.
Dear Computer Journal:

I am writing in response to the article "The State of the Industry," by Bill Kibler in Issue 15 of The Computer Journal. While Kibler has some good things to say, there are also some points I disagree with. Primarily dealing with the IBM PC: While I realize the IBM PC has several shortcomings for us ideal-computer lovers, I also believe IBM has done much more good than harm to the microcomputer industry.

When IBM introduced their PC "...not compatible with anything" as Kibler puts it. I don't think it was quite the joke that Kibler seems to think it was. Although it is impossible to know all of the reasons why IBM chose the architecture that it did (many were economical, to be sure). there were many very good reasons for deviating from what was already available at the time. Among them is the limited memory space permitted by the 8-bit CPUs common to most of the systems of that time. Using a CPU with the ability to directly address up to one megabyte of main memory allows the PC to run many programs and hold a lot of data that would be impractical or impossible on the typical 8-bit CP/M machines common at the time (and still ubiquitous today).

The interrupt-oriented architecture, DMA capability and standardized hardware expansion slots (that is, its open system architecture) are other positive features of the IBM PC. The expansion slots are one of the most attractive features of the Apple II, in my opinion.

Above all else, IBM did something for the microcomputer industry that needed to be done: they created a standard. The few standards previously established, in particular the Apple II and CP/M, were not sufficient to meet the needs of many businesses and other users. IBM created a standard with an 80 column screen (I never could get used to Apple's 40 columns!), a (reasonably) good keyboard that includes lower case and special function keys, and an open system architecture that allows easy system expansion. IBM also set a standard for the 10 M-byte Winchester drive, helping drop hard-disk prices.

Don't get me wrong. I'm not blind to the shortcomings of the IBM PC. Indeed, I dislike the segmented architecture of the 8086 family (including the PC's 8088). Fortunately, the segmentation problem is transparent to the user in most of the good application software available for the PC. I wish to this day, however, that IBM would have chosen the far-better 68000 family. My opinion concerning the IBM PC family of computers is reflected in an editorial statement by Phil Lemmons, Editor in Chief at Byte magazine, in their 1984 Guide to the IBM Personal Computer: "For the present, it makes more sense to enjoy the benefits of the current IBM standard than to curse it because it could be better. But enjoying the benefits of this standard shouldn't prevent us from keeping an eye open for something really new."

R.C.A.
Michigan

Dear Computer Journal:

Please find my check for a one-year subscription enclosed. I would like to get a copy of the first two sections of your article "Write Your Own Threaded Language." Part three was in your sample copy and I enjoyed it very much. As an old hobbyist (circa 1972) I have become concerned that the hobby (computers) movement is being steamrolled by highly integrated technology on one side and suffocated by the tide of appliance computers on the other. Thus, I fully support your Journal. My interest currently is in the development of a 32 bit microprocessor based single board computer in the low cost style of the "Big Board" marketed by Digital Research of Texas. The board should have the capability of 4 megabytes of memory, floppy and hard disk peripherals, six to eight serial communication ports, and the same number of parallel ports. I feel that hobbyists need an architecture that is unique to their needs such as concurrency of tasks.

W.F.B.
Massachusetts

Dear Computer Journal:

Recently, I renewed my subscription to The Computer Journal. Due to a limited budget, both of money and of time, I try to limit my reading to those magazines that cover the technical aspects of computers. By profession I am a programmer; by avocation I enjoy working with the hardware of computers and electronics.

Recently it has been obvious that the magazine industry has gone on a binge of producing computer magazines aimed at the user only, indeed at the novice user, virtually ignoring the avid hobbyist or interested techie. This tendency has even led to the demise of MicroSystems, which had been my favorite magazine, and Microcomputing which had been reasonably good until it was "commericalized". Fortunately this trend should be self-correcting, and the disappearance of many of these new user magazines is already taking place.

But in the meantime some good magazines are also being lost.

Some people are fighting back by correctly pointing out that the real audience for computer mag's is the sophisticated user, builder, designer, etc.. The nearest analogy is that while almost everyone drives a car there are virtually no magazines that feature articles such as "The Correct Grip on the Steering Wheel", yet there do exist car magazines aimed at the truly interested car enthusiasts, and they survive even while appealing to only a fraction of the car driving public. In fact they survive only by appealing to a limited audience.

I think The Computer Journal is a good, even needed magazine, and I want to see it survive. But I think it needs to find its niche. While reviewing the previous year's issues I am struck by the wide range of articles, going all the way from the most basic (Database Design, for instance), to the esoteric ("Wire Wrap a 68008 CPU"). I am also struck by the thinness of the issues; the whole year takes up only as much shelf space as three issues of Byte. But thinness is relative—better to have a few good pages than a hundred meaningless ones. (continued)
One thing that I enjoyed in other magazines such as MicroSystems was product reviews, especially reviews of products offered as kits. Reviews of kits are helpful to those of us who like to build them and even to the increasingly limited number of suppliers. I like to read kit reviews since I can't build all the kits that are offered (many of them I might not use), and want to know about the ones I would like to build. Reviews and articles about kit building can't but aid the industry, even when they include justified criticism of a particular kit.

Very truly yours,
J.O.
Massachusetts

Dear Computer Journal:

Thank you for a terrific magazine! Just as two other publications, MicroSystems and Microcomputing, disappeared over the horizon, The Computer Journal came into view. MicroSystems was terrific, and so was Microcomputing's predecessor, Kibobaud. I will miss them. I think The Computer Journal will do better than just fill the void.

There is a small group of dedicated microcomputerists in the Los Angeles area called "The Southern California Digital Group Computer Society." We are concerned almost exclusively with the preservation, maintenance, and further development of original Digital Group systems. We address both hardware and software issues. At a recent meeting I spoke about your magazine and almost everyone indicated an interest in subscribing.

Software ranges from operating systems—COM, OASIS, [PHIMON, DISKMON, MOPS (native Digital Group op. sys.)], MCOS, and OPUS; to languages—BASIC, FORTRAN, C, FORTH, Assemblers of all sorts; and applications that run the gamut from terminal emulators to accounting systems and database tools.

Hardware typically is dedicated to the SUDING bus as originally presented by the Digital Group, although there have been many successful adaptations of S-100, Apple and TRS80 components. Recent refinements include 4MHz Z-80 CPU with on-board clock and calendar (with battery for continuous power-off function) and "heart-beat" for interrupt driven multi-user operation with intelligent co-processors provide sophisticated I/O management, terminal emulation, 512K pseudo-disk functions and much more.

Current projects include design and development of multiple concurrent processors (they may be dissimilar) and the related software. The local group meets every two months. There is also a national newsletter. Anyone interested in Digital Group systems may contact me at the address below.

Sincerely,
Fred G. Sutton
Pres., SDCGCS
1230 S. Helberta Avenue
Redondo Beach, CA 90277

Dear Computer Journal:

I enjoyed your articles on "Controlling the Hayes Micromodem II From Assembly Language." As a related question, I wonder if information is available on emulating block mode terminals. I realize that there are several different standards for block mode terminals, but there doesn't appear to be any block mode software available for the Apple II.

As a starting point I'd like to see some general information as to how the data and information codes are packed for transmission. Do you know where I could find some source material?

Sincerely,
F.K.
Los Angeles, CA

Ed: Readers, can you help?

Dear Neil Bungard:

This is to express appreciation for your trouble-shooting/interfacing series in The Computer Journal. I have a file folder at least ¾" thick with references to trouble shooting techniques and circuits. It occurred to me that perhaps an annotated bibliography for The Computer Journal would be worthwhile. One particular device that I have wanted to build, but could never quite dope out from the printed material, was a test circuit described by Bob Cushman in EDN about five years ago, which originated with some Motorola engineers. It's essentially a method of looking at all data lines as latched at a given (thumb-switch selected) address. I have access to a fairly complete file of Wireless World, where a number of devices of varying complexity have been described.

I have looked, unsuccessfully, for a suitable circuit for a pulse injection probe with the versatility of the Hewlett Packard device, which senses whether a point is high or low and pulses it in the appropriate direction. It is (as I recall) somewhat flexible in pulse duration. Any ideas?

Electronics (Australia) in December 1977, published full details on a 40 channel tester in which the condition of up to 40 points was latched and held, under control of a variable time-delayed strobe triggered from a reset (or other 'time zero') system reference. Thus the response of the 40 latched LEDs can be 'walked' through a total time excursion of several milliseconds as the time-delay controlling potentiometer is rotated and the timing sequence thus inferred. It looks as if that will be my next project.

Sincerely,
H.M.
Hinsdale, IL
POOR MAN’S DISTRIBUTED PROCESSING:
Cross Development and Using the H-8 as a Print Buffer
by Walt Piotrowski

I wonder how many computers there are in the world that still compute but have been taken out of service because their owners’ needs have changed? There are the starter machines which were intended to be outgrown (although their purchasers may not have known that), and there are a growing number of very capable machines that have been replaced because of advances in technology. At the same time, there are no other things around the house, or the company, that could be done quite well by a computer but are not being done because the newer models are too expensive or powerful to dedicate to these tasks. Energy control and security come to mind fairly quickly. An old computer can also be put to use as a smart peripheral or a data preprocessor for a new machine. You could, for example, build real world interfaces for the old machine that might void the warranty on your newer machine and then transfer the data between the old one and the new one using a commercially available interface. You could also help advance the state of the art yourself by experimenting with loosely coupled distributed processing.

The old machine that you put to use in this way does not have to be a complete system. It is common to develop software on a fully equipped system and then use that software on another system that does not have a full complement of peripherals. It’s regularly done in the commercial and military worlds (automobiles and missiles both have computers in them) and it can also be done by an individual if he’s willing to substitute some ingenuity for expensive test setups. This article contains a general discussion of the principles of cross development and then shows their application in the development of a printer buffer using a Heathkit H-8 that had no peripherals of its own.

Cross Development

There are two major processes in software development that actually make use of a computer. The first is code generation. Code generation uses an editor for entry of source statements, an assembler or compiler for translation of source statements into an intermediate object code, and a linker or loader for generation of the final object code. The second process is code testing and, for the kind of program that we are considering here, usually requires additional debugging aids of some kind.

The two computers involved in a cross development are called the host and the target. The host is sometimes called the development system and it usually has a disk operation system and a full complement of peripherals. Generally, all parts of the code generation process are done on the host. The target is normally a minimum system and doesn’t have enough hardware to support an operating system. Although some tests must be done on the target, it’s quite common to do at least part of the testing on the host with only a final test on the target. In addition to these two processes, which are done in any software development, cross development also involves an additional step of transporting the object code from the host to the target. Interestingly, I’ve heard people who do a great deal of this kind of work talk about normal programming as a cross development in which the host and the target are the same system.

Code generation is less expensive if the host and the target have the same microprocessor as their base machine. Both may be based on 6502s for example. In this case, you can use the host’s normal compilers, assembler and loader to produce the object code. If the two systems are not based on the same processor, the extra expense comes from the need to buy (or write) a cross development tool like a cross assembler or a cross compiler. Cross assemblers are advertised regularly in most advanced computing magazines and are also available in the public domain. I haven’t seen any cross compilers advertised, but they may be available if you make inquiries in the right places.

The strategy that you adopt for code testing is also influenced greatly by the base processors of the two systems. If they are the same, you test portions of the target’s software on the host, using the host’s normal debug tools and peripherals. If you are careful when you structure the program, you may be able to test a very large percentage of it on the host and leave only the portion that handles the target’s I/O functions for test on the actual target system.

If the two processors are not the same, there are still several test options open to you. One option is the use of an instruction level simulator (ILS) to simulate execution of the target’s instruction set on the host. Instruction level simulators for the simpler processors like the 6502 or 8080 are relatively easy to write, and many people write them in high order languages. Once you have an ILS, you can use it to do the same kind of testing on the host that you would do if the two base processors were the same. (As of this writing, I have not seen any instruction level simulators available commercially or in the public domain.) Another test option, if you are writing part of the target program in a high level language, is the use of two separate compilers. One of these is the cross compiler that you will use to produce the code for the target machine. The other is a compiler to produce code that you will test on the host. If both compilers are of good quality, you can be confident that once the high level language portion of your program works on the host, it will run correctly on the target.

If the target is really a “minimum”
system, testing on the target will probably be at the machine language level. In the professional cross
development world, there are exotic test tools like in-circuit emulators that allow you to use the power of the host
while testing the target, but these require more hardware than you or I
will probably ever have. In our en-
vironment, test aids on the target
system will be sparse. The tools that
are available and the complexity of the
program that you are testing will in-
fluence the amount of work that you will
be able to leave for the target
machine. Testing with no tools at all
might be possible but it would require
either that your program be extremely
simple or that you possessed an in-
credible amount of intuitive reasoning
capability (or luck). A control panel is
the lowest level test tool and the step
beyond that, if you are lucky, is a debug
program, however, would require
that you had a terminal
available to run it. The final problem is
the transmission of object code from
the host to the target. There are
several approaches. Writing a diskette
or a cassette tape on the host and
reading it on the target is certainly the
simplest, but is probably the least
likely since it requires that the systems
have compatible peripherals. For our
minimum target system, a more likely
solution is a communication link. For
most of us who are using old systems,
the available link will be RS-232. The
protocol for the communication that
you do over the link depends on a great
deal on the intelligence level of the
target system when its power is first
turned on. In the best case, the target
has a ROM that will boot from the link.
(In the good old days, we used teletypes
and our mass storage was paper tape,
so this isn’t as far fetched as it sounds.)
The next best case, if the target
machine has a control panel, is to use
the panel to enter a small boot routine
by hand. If you choose this as an option,
you may want to consider a two stage
download. The first stage can be a very
unsophisticated program that will only
download a more sophisticated loader.
This exotic loader can then download
the actual software while doing error
checking on the transmission. As a
bonus, if you do your download via RS-
232, you may be able to run a debug program in the target by using your host, with a modem program, as a dumb terminal.

Once you have your software up and running properly, you may want to consider streamlining the whole process by eliminating the download from the host. The standard approach is to burn the software into a PROM. A good possibility, if your machine has a boot-up ROM, is to replace the existing ROM with your own. This also opens up the possibility of using your old machine as a stand-alone process controller in remote locations.

An Ideal Target Machine

My first home computer was a Heath H-8, which I bought shortly after they were announced. My initial investment in the computer, a terminal, two cassette recorders and a printer destroyed the family budget for a couple of years. When disk drives became available, I was still making the monthly payments on the equipment that I had already bought. For a lot of reasons, I wasn't active in home computing for a few years after the system was paid for and, when I finally got back to it, it was cheaper to buy a whole new system than to buy disk drives and more memory to upgrade my H-8.

My new system has a lot of bottlenecks, but the most annoying is the 30 character per second printer. (The printer, by the way, is the same DecWriter that I bought with my first system.) One night I was reading an article about a printer buffer and I thought about my unused H-8. It has the two serial ports that are required by my hardware. One had been used for the console terminal and the other was used for the DecWriter. Even though my H-8 only has 16K of memory, some quick arithmetic showed that it would hold about nine minutes worth of printing at 30 cps. Not terrific, but not bad either.

It turns out that the H-8 is almost ideally suited to be a target machine. It is based on the 8080 which means that any system that runs CPM-80 can be used as the development system. It was designed before the days of systems with integral keyboards and monitors, which means that it needed to have an RS-232 port to handle an external terminal. Its most important feature,
however, is that it contains a built-in solution to the download and debug problems.

The H-8 ROM contains a program that Heath called the Panel Monitor (PAM). The system boot routine is a part of PAM and the earlier H-8s normally booted from cassette recorders through the Serial I/O and Cassette Board (H8-5). In the early days, Heath was trying to sell systems to people who already had teletypers and paper tape readers and, to accommodate them, they provided a port interface switch on the H8-5 board. When you flip the switch, the board exchanges the addresses of the console port and the cassette port. The ROM, thinking it is still talking to a cassette, is actually handling the RS-232 line. Booting from an intercomputer link requires pushing just one button (as long as the host machine transmits the file using the protocol that PAM expects). PAM also contains complete machine language debugger which takes commands from the front panel keys and displays results on the front panel LEDs. (The system would be perfect except for one small frustration: the panel monitor displays everything in octal, and CP/M’s assembler prints everything in hex.)

An assembly language program that will download from a CP/M system to an H-8 is provided with this article. The program takes the name of the file to be downloaded from the command line and expects to find a file by that name in COM format on the disk. It assumes that the program will load at the normal H-8 start address of 2040H (040 100H in H-8 split octal). Getting the H-8 program into COM format after assembling it at 2040H requires some manipulations. These are given in a note at the end of the article.

My CP/M system is a Commodore 84. In the C-64, handling the RS-232 port from CP/M requires code for both the Z80 CP/M co-processor and the native 8510. Since this code is lengthy and is of interest only to C-64 CP/M users, I have not included it in the listing. Instead, you will find a commented section at the end of the listing that shows you should insert code to handle your host machine’s RS-232 port. The comments also identify what the main program expects the subprograms to do. If you are a C-64 owner, contact me...
and we can make arrangements for giving you a copy of the entire program.

An H-8 Printer Buffer

My main machine, which will transmit to the printer buffer, uses what’s been called an x-line protocol for RS-232 transmission. It responds to Data Terminal Ready (DTR) and Request to Send (RTS) on the RS-232 line. Normally, the DTR signal from the receiving device is controlled by hardware and is asserted whenever the power is on. The RTS line is manipulated dynamically by the receiver to control the data flow. The H-8 program, described later, uses this RTS line to shut off the data flow when the buffer memory is full.

Slight hardware mods were needed to set DTR and RTS signals from the H8-5 board. All of the H-8’s serial devices used a 3 line RS-232 interface, which does not provide control functions between the receiver and the sender. For some unknown reason, a great deal, but not all, of what was required to provide DTR and RTS signals was already on the board. The hardware mods provided at the end of the article will make sense if you have an H-8-5 logic diagram in front of you. In essence, they do the following:
1) Provide pullups for the collectors of the transistors that provide the DTR and RTS signals.
2) Reverse the sense of the DTR signal so that it goes high when power is on.
3) Provide a cable and back panel connector to get the additional RS-232 signals from the H8-5 board onto an RS-232 cable.

Listings for the H-8 print buffer program are provided along with this article. The program is in two parts. The control portion, written in Small C, contains an infinite loop which polls the input line for data and also polls the output line to see if it is ready to transmit another character. Since the input rate is higher than the output rate, the excess characters go into a circular buffer. When the circular buffer is dangerously close to full, the program shuts off the input by dropping the RTS (Request to Send) signal on the input line. It turns the input back on again when there is more room in the buffer. The actual I/O to handle the H-8’s UARTs is done with assembly

```assembly
BUFFFULL(INPTR,OTRTR,INPOFF);)

/* Buffer full check */
BUFFFULL(INPTR,OTRTR,INPOFF)
INT INPTR,OTRTR,INPOFF;

int slotsleft;  /* Number of slots left */
slotsleft = otrtr - inptr;
if (slotsleft <= 0)
  (slotsleft = slotsleft + bufsize);
if ((slotsleft < 20) && (#pinoff == false))
  (#pinoff = true ;
  trnoff();

if ((slotsleft > 20) && (#pinoff == true))
  (#pinoff = false ;
  trnon();

;-----------------------------------------------
; H-8 Print Buffer Subroutines
; Walt Piotrowski
;-----------------------------------------------

; Input USAR Equates
INMOD EQU 116Q
INCMON EQU 064Q
INCMOFF EQU 024Q
INCTRL EQU 371Q
INDATA EQU 370Q
INSTAT EQU 371Q

; Output USAR Equates
OUTMOD EQU 116Q
OUTCMD EQU 1
OUTCTRL EQU 377Q
OUTDATA EQU 376Q
OUTSTAT EQU 377Q
TXREDY EQU 1
RXREDY EQU 2
TRUE EQU 1
FALSE EQU 0

;-------
; Shut input off
OZTRNOF MVI A,INCMOFF
OUT INCTRL
RET

;-------
; Turn input on
OZTRNON MVI A,INCMON
OUT INCTRL
RET
```

The Computer Journal
language subprograms. These are
given in the third listing.

By using Small C, it was possible to
check out the control portion on the
host by INCLUDEing a test library in
place of the actual I/O routine library.
Since I had never written a program in
C before, this was an important con-
sideration for me. When the program
ran satisfactorily on the host, I trans-
mitted it to the target with only the
I/O left to be checked.

H8-5 Hardware Mods

Board Changes:
1) Cut the solder trace from IC122 pin 1
to IC 124 pin 23.
2) Cut the solder trace from IC122 pin 3
to R153.
3) Cut the solder trace from IC122 pin 6
to R155.
4) Connect IC122 pin 6 to IC122 pin 1.
5) Connect IC122 pin 3 to R155 (same
end as step 3).
6) Connect IC124 pin 23 to IC117 pins 12
and 13.
7) Connect IC117 pin 11 to R154 (same
end as step 2).
8) Connect a 2200 ohm ½ watt resistor
between P102 pin 9 and P102 pin 1.
9) Connect a 2200 ohm ½ watt resistor
between P102 pin 9 and P102 pin 2.

Cables:
The following signals at P102 on the
H8-5 board need to be brought out to
the back panel and from there to the
RS-232 cable. The RS-232 connections
shown assume that your host computer
is wired as Data Terminal Equipment
(DTE).

<table>
<thead>
<tr>
<th>Signal</th>
<th>P102</th>
<th>Re-232</th>
</tr>
</thead>
<tbody>
<tr>
<td>RTS</td>
<td>Pin 1</td>
<td>Pin 5</td>
</tr>
<tr>
<td>DTR</td>
<td>Pin 2</td>
<td>Pin 20</td>
</tr>
<tr>
<td>GND</td>
<td>Pin 4</td>
<td>Pin 1</td>
</tr>
<tr>
<td>Data In</td>
<td>Pin 5</td>
<td>Pin 2</td>
</tr>
<tr>
<td>Data Out</td>
<td>Pin 8</td>
<td>Pin 3</td>
</tr>
</tbody>
</table>

Connectors:
The following connectors are those
used by Heath:
S102:
Molex 22-01-2105
G C Electronics 41-130

Back Panel Connectors:
Molex 03-06-2151 (plug)
Molex 03-06-1151 (socket)
Sold as a package by Waldon 1625-15
PRT

Miscellaneous Software
Procedures

To make a COM file from a HEX file
that has been ORGed at 2040H use
DDT with the following commands:
IFN.HEX
rECO
If you are using Small C 1.1, which
generates a file for ASM, you can make
a HEX file for your target machine by
modifying the first few lines of the
ASM file produced by the compiler. In
the ASM file, change the ORG to the
address appropriate for your machine
(2040H in this case) and change the
stack pointer setup to point to the top
of your target's memory.

Listing continued on page 14
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**BASE**

**A Series on How To Design and Write Your Own Database**

**By E.G. Brooner**

We come now to the theoretical means that can be used to 'find' some particular bit of information or some related set of data items. Placing information into some particular order and finding it again involves techniques generally summarized as sorting and searching. We are assuming that the information has been originally stored in some random, un-ordered manner.

Sorting, of course consists of placing the data in some kind of ascending or descending order, alphabetically or numerically. There is actually little difference between the two in computer applications because sorting is based on the ASCII value of the characters — the ASCll value of the numeral '9' is larger than the value of the numeral '8,' and the value of 'B' is greater than 'A.'

As we will probably enter data more or less haphazardly, as it comes to us, this sorting has to be done by the program after the data has been entered. It may have to be done again from time to time as more data is added. There are several interesting programming techniques used to accomplish this end.

Searching is also a diversified concept, and the means used depends on how the information is ordered and stored in the files. One technique we'll discuss is indexing, which is used almost exactly as the index is used in a book or catalog. Another is the apparently magical means of using the data itself as a clue to its location on the disk; this is known as 'hashing.' Binary searching is another method ideally suited to computer use, since it is based on the kind of logic computers use.

The sequential search. Assume a list of names or numbers, which may or may not be in any particular order; assume then that you wish to locate one particular item. Your only choice is to start at the beginning and check each item until you find the correct one. This is O.K. for a single printed page or for a data file of a few dozen items, but it can be time-consuming if the list is long.

Many file programs use the sequential access method; it is simple and for some purposes is perfectly adequate. In some cases it is mandatory — in a database it is often necessary to find several entries that meet the same criteria, which means that the entire file has to be read to make sure none are missed.

**Sorted order.** Next, consider that the list of names has been sorted into alphabetical order (as in a phone directory or dictionary). We open the list and look at an entry; if we are looking for 'Jones' and the list falls open to 'Conrad' we know to look beyond that point. If it falls open to 'Smith' we flip back toward the beginning. Repeating this process narrows the search until we find the entry for which we are looking. This is the basis for the binary search we will discuss later.

**Direct addressing.** Now consider a similar list that is numbered in sequence. If we know that the item we want is entry number 876 we can go directly to it. In effect this is what we frequently do with a data file, if and when we know which relatively numbered record it is that we want. If we are using a so-called
'random access' (or 'relative') file, the operating software keeps track of where each record is located and we simply ask for the record by number.

**Keyed access.** Sorted order and direct addressing can be combined in a very useful way. If the records are numbered we can first sort the 'key' (names, in this example) and rearrange the record numbers in accordance with the alphabetical order of the names. Doing this results in a 'mixed-up' list of record numbers. Now if we read the records in the 'mixed-up' order we will find that the resulting list of names will come out in the sorted order. This will be illustrated when we get to the portion of BASE that does the actual sorting.

This kind of arrangement has a particular advantage for computer use. After the record numbers are listed, we store them as a separate list. This list is then known as a 'key file' or index file. The advantage is that the original list of names has not been altered in any way from its random order. But by referring to the key file we can go directly to the information as if it were in alphabetical order.

**Binary search.** The technique just described does not, by itself, solve all problems. We still might need a quick way of leafing through the key file to find out which record number corresponds to the name 'Jones.' The binary search is one way to do so. A key file that is to be used in this way has to contain the key fields in their sorted order, along with their record numbers in whatever order they happen to be. The binary search process then looks at the key fields and uses the associated record number to find the complete record.

The binary search only needs to know the length of the file, or list, and whether it is in ascending or descending order. It reads the key in the center, and learns whether the desired record is higher or lower in the order of things. It then examines the center of either the upper or lower half, as the case may be, and gets that much closer. About half a dozen 'looks' will find almost any entry in a list of a thousand or so items. Doubling the list's length only adds one more 'look,' and so on. The binary search is blindly fast when using an in-memory array; it is quite impressive even when reading from a disk file. On the average, a binary search will find the desired record in 4 tries for a list of 25, 6 tries for 100, 9 and 10 tries for a 1000 record file. 2000 records needs 11 tries, 5000 about 12 or 13, and 10,000 only one more. Even searches of this magnitude, reading the records from a disk, take only a few seconds.

In our database examples we will probably have to provide for more than one kind of search. We might, for example, sort the records for some kinds of access, and 'find' by relative address for others; at other times we might read the entire file sequentially and check every entry. It's obvious, then, that we will want to provide for more than one way of reading any particular file or set of files. This will be explored more fully when we come to the sections of the program that actually handle these chores.

At this writing we have not added any of the more exotic methods of sorting and searching to the main BASE program, but they are worth describing and considering in the general context of database programming. As a matter of actual fact, the main body of BASE uses a simple sequential search. The options being only to match a key, or find those either larger or smaller. For the latter two conditions a sequential search is a necessity anyway.

The simple sort program that will be shown in another column builds key files consisting only of the record addresses; this permits a file to be printed in ascending order based on any field. Two other programs are in existence that operate on BASE's files. One of these (called MATCH) allows us to match two fields, such as first name and
telephone area code — i.e. Joe who lives in Seattle, area code 206.) The other (called BINARY) sorts selected files, as does the main program, but stores the keys in such a way as to provide a binary search which is part of the same program. If time and space permit, these auxiliary programs will be published at a later date. Keep in mind, though, that the portions of BASE shown to date, even without any sorting, can be very useful for modest-size databases.

In BASE we have kept each field (of any set of records) as a separate file — this makes sequential searching (for a single field) quick and easy and simplifies using any field as 'key.' It also makes each of those mini-files easy to sort into a key file. Whether sorted or unsorted, the individual field in any field-file is inexorably related to the rest of its record by direct-addressing. Thus, we will be able to search such files at least three different ways and retrieve the remainder of the record after the key is located. Since all fields can be 'key' in this system, your searches can be as flexible as you wish to make them.

The actual sorting of files for BASE has been kept a completely separate operation, and in fact an auxiliary program that is 'chained' when we select that option from the main menu. The printing of reports is also a separate, chained program in this package. This was done to keep the program(s) small enough for a small memory, and to make the specialized sections easy to modify and/or experiment with.

If you choose to combine the listings up to this point you will find that the source program runs around 400 lines and takes about 10K of file space. When compiled with CB-80 it results in a machine language file of approximately 18K. The sorting and printing programs are both considerably smaller. If you have to use the CRUN version, though, you will have less memory available because of the presence of the runtime program, so if memory is limited you might consider stopping here for awhile.

How the Searching Goes

Selective searches enable the user to extract different 'sub-sets' of information from a larger collection of data. All zip codes for Montana, for example, begin with 59; if I had several thousand subscribers in a mailing list I could extract those in Montana by asking for any zip beginning with 59. This search could be narrowed to one particular distribution point (sub-area) by asking for 598, or 599, or the exact complete code could be used to pinpoint addresses at a single post office. By the same reasoning one might want to list all customers having a given phone area code. One feature I included in my personal mailing list was a 'code' field. If the code is XC, that address is one to whom I send Christmas cards. Once a year, then, I can extract my card list from the hundreds of addresses I keep for other purposes. In my humble opinion being able to 'key-in' on any field, and to use partial keys, is essential to database operation.

The following section will work with the files that the earlier portions of the program created, regardless of whether the data has been sorted or not. It is a simple sequential search; however, it goes quite rapidly because only one field (of each record) need be read until the sought-for record is found. If we examine the basic sear-
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Several years ago, most home computers were owned by "hackers." These people knew how every integrated circuit in their computer worked and they could explain every byte of the code in their computer's operating system. Although there are probably as many hackers around today, there are a lot more owners of home computers classified as "users." Due to the rapid advancement in software, you no longer have to be a computer genius to use a computer. The most popular uses for home computers now include games, word processing, spreadsheets, education, and graphics. Graphic software packages for home computers like the Commodore 64 are becoming more and more powerful.

To create your own masterpiece of art with a graphic input device such as a joystick, light pen, track-ball, or graphic tablet can take several hours, and the results are highly dependent on your talent as an artist. Suppose you would like to include a more realistic picture of you, a relative, or a pet in a Basic program you are writing. If you lack the artistic talent to draw these pictures, all is not lost. You can input pictures to your computer through an electronic scanning device.

In this article, I'll describe the interface for a machine that can read any picture from a piece of paper and translate the picture to signals that your computer can handle. The machine is a facsimile machine, commonly referred to as FAX.

What is a FAX?
The facsimile machine is quite common in the business world. It is used to transfer a page of information (usually 8½ by 11 inches) over the phone line. At the transmitting end, a sheet of paper with text, graphics, or whatever, is fed into the machine. After a few minutes of whirring sounds, the paper comes back out of the machine. At the receiving end, the page image is reconstituted on a thermal printing device.

The two FAX machines are connected to each other by modems in very much the same way that two computers communicate over phone lines.

FAX machines have been used to transmit both text and graphics. With the advent of low cost computers, however, it is now becoming quicker and cheaper to send text from one point to another by purely digital means. FAX machines are still popular and will always be used for special applications (AT&T still says a FAX is the only way to transmit hand-drawings, signed legal documents, etc.), but more and more companies are replacing their FAX networks with computer networks for text transmission.

The result of this change-over in technology is that businesses are now dumping used FAX machines into the surplus market. These machines, which cost up to $4,000 new, can now be obtained for less than $200. Used FAX's in good working condition are quite a bargain and can be obtained from dealers of used office equipment and large electronic/computer surplus dealers.

Some Facts about FAX
A FAX machine is actually two machines in one. The transmitter feeds in a sheet of paper, scans it, translates the image to an electrical signal, modulates the signal, and sends it over a telephone line. This is the part we're interested in. The receiver takes the telephone signal, demodulates it, and translates the electrical signal to an image on a fresh piece of paper. We are not interested in the receiver end, although it can be used for a very slow, low quality printer. (Note -- in most FAX machines, looping the output signal of the transmitter to the input of the receiver will turn the machine into a copying machine.)

There are probably just as many FAX "standards" as there are companies that make the machines. The signal can be amplitude modulated by a carrier of constant frequency, or it can be frequency modulated, giving a constant amplitude saw-tooth signal in which the frequency varies with brightness level of the scan. The signal can be digital in nature (only two levels: black and white; commonly used for text), or the signal can be analog, in which an infinite variation in gray levels is possible. An analog type signal is required for pictures. Various scan rates are used, from a fast 5 scan lines per second to 2 scans per second. In addition, the vertical resolution can vary from about 80 to over 200 scan lines per inch.

For our purposes, what standard should be used? Since the primary purpose is to digitize pictures, we will need an analog signal. Since most home computers can easily keep up with the scan rates involved by using machine language routines, we should use the fastest scan rate available. Another consideration is deciding between AM versus FM signal modulation. FM will reduce the amount of noise in the picture, but a few pixels of noise are not really noticeable in a digitized picture.

Luckily, the machine I obtained had a multitude of switches that could be used for just about any standard. The machine is a Burroughs DEX 4100, which I currently have set up in the following mode:

<table>
<thead>
<tr>
<th>Machine</th>
<th>DEX mode</th>
</tr>
</thead>
<tbody>
<tr>
<td>Speed</td>
<td>High</td>
</tr>
<tr>
<td>Res</td>
<td>Norm</td>
</tr>
<tr>
<td>ResX2</td>
<td>Off</td>
</tr>
<tr>
<td>TX Level</td>
<td>Norm</td>
</tr>
<tr>
<td>Doc</td>
<td>Photo</td>
</tr>
<tr>
<td>Simplex</td>
<td>On</td>
</tr>
</tbody>
</table>

The resulting output is an amplitude modulated signal with an carrier frequency of 1920 Hz. The peak-to-peak signal varies from approximately 1 volt (black) to nearly 0 volts (white). The scan rate is exactly 5 Hz, giving 88 scan lines per inch. An entire 11 inch long sheet of paper is scanned by approximately 955 lines in a little over
three minutes.

The hardware and software presented in this article will work with a DEX 4100 FAX machine connected to a Commodore 64 computer. Other FAX machines, other transmission standards, and other 6502 computers can be used. However, other equipment will require revisions in the machine language software and possibly in the interface circuitry as well. But the techniques shown can be used as a starting point for any other configuration.

Some Design Considerations

Before jumping into the hardware and software design, let's think about how we will use the machine with our C-64. In the mode I chose to use, the FAX can digitize graphics at a resolution of over 50 dots/inch horizontally (along a scan line) and over 80 dots/inch vertically (from line to line). The most important criteria is that the aspect ratio of a picture is unchanged. A circle on the original should still look like a circle on the digitized image; it should not look like an oval. Another nice-to-have feature is that the picture will not have to be rotated 90 degrees to look at it. Most 8½ by 11 or 8 x 10 pictures are oriented vertically (like the page you are now reading); this means that we would only use about half the page. The C-64's graphic resolution is 320 horizontal, 200 vertical. 320 dots with about 50 dots/inch gives a little over 6 inches out of the total 8 or 8½ inch picture width. This is acceptable because the important picture content is almost always near the center. Due to the C-64 aspect ratio, the height of the digitized image on the original is a little over 4 inches. The FAX's vertical resolution is twice what we need, so we'll plan on using only every other scan line.

If you've been keeping up on the C-64 graphic articles, you know that there are two distinct bit-mapped modes: HIRES with 320 x 200 pixels and two colors, and MULTI with 160 x 200 pixels and four colors. Actually, the two or four color restrictions pertain to an 8 x 8 grid of dots and other 8 x 8 grids can have other color combinations. But since the scanning and digitization will be completely automatic, it is much simpler to restrict our pictures to two colors in HIRES mode and four colors in MULTI mode. However, we won't restrict our colors to black, white, and shades of gray. It is very desirable to be able to choose any color we want for any level of intensity.

Another feature that we would like to have is the ability to control where the top of the picture should be, by use of the keyboard. After the picture has been transferred to the computer and is displayed on the screen, we would like to save it to a disk file in a format that is compatible with other graphic aid and graphic print programs. This way, we can further enhance the pictures and get hard copies of them.

FAX to C-64 Interface

The signal coming out of the FAX is a relatively low voltage modulated analog signal. The interface must amplify the signal, demodulate it, and convert it to a digital signal (D/A converter). The extremely simple circuit I came up with, shown in Figure 1, will do all the required signal conversions. The five volt power supply in the Commodore 64 is used to power the interface. The signal coming from the FAX is divided by a 50Kohm potentiometer. This functions as a brightness control. The reduced signal is amplified by A1, one quarter of a low cost quad op-amp (IC1: LM3900). The output of A1 is inverted by A2. The outputs of both A1 and A2 are summed through diodes by A3, which acts as a full wave rectifier and demodulator. A4 inverts the signal and buffers it. The output of A4 varies from about two to four volts, in direct proportion to the brightness of the FAX scan at that instant.

IC2 (LM 339) is a quad comparator. A5, A6, and A7 are set to switch at about 3.75, 3.12, and 2.5 volts, respectively. The output of A4 is fed to all three comparators, which digitize the signal into four distinct levels from dark black to bright white. The comparator outputs are connected directly to three I/O bits of one of the C-64's CIA chips, through the USER port. (For computers other than the C-64, any PIA type I/O port could be used: 6820, 6821, 6520, 6522, etc.) The software driver will convert the three bits to a two bit binary code to signify gray level. For other computers that can display more gray levels, a more sophisticated analog to digital conversion would be required. But for the C-64 (and most inexpensive home computers), four distinct gray levels are most appropriate.
The capacitor attached to A3 demodulates the signal by filtering out the higher frequency carrier. The value shown results in a good compromise of low noise and acceptable resolution. For other standards, you may desire to change the capacitor values. If the horizontal resolution is found to be less than desired, reduce this value. If the output has too many light to dark transitions, smooth it out by increasing the value of the capacitor.

The required cost of the interface is almost ridiculously low. The connector that attaches to the C-64 is the most expensive part (about $4.00). Any type of layout is probably O.K., since fairly low frequencies are involved. Use shielded cable to the FAX machine (shield grounded). The most desirable configuration is to connect the PC board to the C-64 connector, so that the whole unit can plug into the computer's USER port.

**Synchronization of the Signal**

The translation of the signal from analog to digital was pretty straightforward. But at this point, a good question is "How in the world do you synchronize this signal to the computer?" This proved to be the most difficult aspect of the project. Initially, I used a very stable crystal controlled clock and divider chain. It was impossible to adjust the timing so that the image was stationary on the screen. A vertical line from the FAX would drift as much as 10 to 12 pixels to the left or right on the screen image. Next, I tried a phase lock loop oscillator, synchronized to the power line (60Hz). This was even worse; the vertical line ended up somewhat sinusoidal.

I tried to use the modulation frequency of the FAX itself (1920Hz), but this oddball frequency was not acceptable. It required a conversion to another frequency and a phase locked loop, since on white scenes, the modulated signal dropped to zero. This technique proved to be overkill and needlessly complex.

Another way to do it is to lock onto the picture signal itself with software. A representation of the demodulated signal (the output of A4) is shown in Figure 2. If an 8½ inch piece of paper is centered in the machine, the scan will give black guard bands off the edges. Between these black bands is a white...

---

**Listing 1**

```
00001 0000:  ;XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
00002 0000:  ;FAX DRIVER FOR C-64  
00003 0000:  ;INPUTS THROUGH USER PORT  
00004 0000:  ;
00005 0000:  ;M. J. KERIAN 9-84-84  
00006 0000:  ;XXXXXXXXXXXXXXXXXXXXXXXX
00008 0000:  ;PL = $FD  
00009 0000:  ;PH = $FE  ;PAGE ZERO
00010 0000:  ;TEMP = $FB  ;POINTERS AND
00011 0000:  ;TEMPER = $FC  ;TEMPORARY
00012 0000:  ;REGISTERS
00013 0000:  ;DATAIN = $0001  ;INPUT PORT
00014 0000:  ;ICR = $0080  ;INTER. CONTROL
00015 0000:  ;
00016 0000:  ;LTAB = $4308  ;THIS TABLE IS
00017 0000:  ;LTABA = $4309  ;USED TO
00018 0000:  ;HTAB = $4408  ;CONSTRUCT
00019 0000:  ;HTABA = $4409  ;ADDRESSES
00020 0000:  ;X = $4590  
00021 0000:  ;
00022 0000:  ;
00023 4500:  ;NENM1 SEI
00024 4501:  ;2C 90 DD  ;TURN OFF INTER.  
00025 4504:  ;BIT ICR  
00025 4504:  ;FAX INTERRUPT?
00000 0000:  ;
```

---

**Figure 1: Interface Schematic**
sync pulse. Since the scan rate is constant (1 scan line every 0.2 seconds), the width of the sync pulse is constant. I decided to use the white sync pulse, followed by the black guard band, to sync the picture. This proved to be very stable, the only noticeable by-product being a plus or minus one pixel uncertainty. Since I use the FAX mostly for pictures, this one pixel uncertainty is usually undetectable.

Figure 1: Modulated signal (output of A4)

The dot clock was generated by software. By doing so much in software, we have significantly reduced the complexity and cost of the interface. That's the good news. The bad news is, of course, that the software required to support the hardware is quite complex.

So far, we learned how a facsimile machine (FAX) works and we looked at a simple interface circuit that can be used to connect a FAX machine to a home computer, such as a Commodore 64. Before jumping into the software, an overview of the operation is helpful. The CIA integrated circuit (6528) in the C-64 is used as a parallel input port to accept three bits of digitized information from the interface circuit. In a completely different application, the timer in the CIA is used as a clock signal. The clock is used to generate Non-Maskable Interrupts (NMI) at a frequency of approximately 3000Hz. During a scanning operation, everytime a NMI occurs, data is sampled from the input port, converted to a pixel (picture element), and stored in graphic memory. Since this operation happens in the background, we can have a basic program and even another machine language program running at the same time. This foreground/background mode of operation greatly simplifies the programming.
Machine Language FAX Driver

The assembler code for the machine language program is shown in Listing 1. The first thing to do is save the new NMI routine. The pointers for this routine are poked into memory and activated by a Basic program described later. NEWNMI first checks to see if the NMI actually came from the CIA chip. If so, all registers are saved. The program counts each NMI (each dot) by eight because eight dots make up a byte of screen data.

A flag is used to denote the state of synchronization. If the flag is 0 (initial state), the signal is out of sync. If the flag is between 1 and 127, the program goes into a special phasing mode. If >127, the flag denotes that sync is established. We'll look at each sync mode separately.

If out of sync, the program will look for a string of white bytes that are between 76 to 80 dots wide. This string must be bounded on both sides by black dots. If any dot is out of sequence, this routine will reset and continue to look for this sequence. This white area is the sync pulse described previously. The length (76-80 dots) is dependent on the machine scan speed and software timer period. Any change in these will require a new window size. Once the sync pulse is found, the program changes the sync flag so that operation will go to the special phasing mode (LOCKED). A count of 101 is stored into a counter which is decremented by each NMI (each dot). At this point, the correct phase is established, and we are at the left margin of a picture. The flag is then changed to denote that sync is established and counters are zeroed for the vertical line number, the horizontal count, and the horizontal byte number (column).

If the NMI routine is entered while in sync, it first checks to see if 1200 dots have occurred. If so, then one complete scan line (actually two physical scans since we ignore alternate scan data) is completed and we are then at the end of a line. We use this opportunity to check the keyboard for the 'T' key. T is pressed when you want the picture started at the top again, so the line number is zeroed. At the end of the 200th line, the picture is complete, so the routine kills itself by disabling FAX interrupts (see N3).
During the 'dead' part of the scan, which is the physical scan line that we ignore, the keyboard is looked at again, this time for the 'S' key. On very rare occasions, a glitch may destroy the synchronization. The S key is used to start everything over again to re-establish sync.

If the sync is established, and we are in the active scan area (dots 0 to 319), the program jumps to ACTIVE. Here the data is sampled from the three input lines and converted to a two bit binary code: 00, 01, 10, or 11. Next, the mode of operation is looked at. If we are in HIRES mode, then we only want two levels of intensity for each dot. If the MUL1color mode is desired, then we will look at two consecutive dots, average them, and give the corresponding two-bit code for the average intensity level of the two dots. In either case, two bits are used to update the screen in the active scan area.

The addresses for the bit-map area are determined from a set of lookup tables (see Listing 2). These addresses are constructed based on the vertical line number (0-199) and the horizontal column number (0-39). The new two bits are placed at the correct bit locations into the byte of data. This byte is stored back in the 8K bit map memory area. Since there are four possible places to put these two bits, there are four small routines for this: B0, B1, B4, and B6.

You can see that the NMI routine actually does quite a bit. It handles all the synchronization of the FAX, inputs the scan data, checks the keyboard for S or T keys, keeps track of the screen locations, and handles all the screen writing in either HIRES or MULTI modes.

Other Machine Language Utilities

Listing 1 also shows a few more utility programs. These are not part of the FAX driver but are instead called by SYS statements from our Basic program. First is a routine to clear the 8K bit-map area of memory. Also included are routines to clear the 1K areas for the screen and color memory. Actually, with a POKE from Basic, these routines can change the colors to any desired. A routine (SAVE) is included to move the different memory areas to other areas that are com-
patible with popular graphics programs. Here we move the 8K bit-
map area starting at $2000 to $6000+. 
The 1K screen area starting at $4000 is 
moved to two locations, $5C00 and
$7F40. The 1K color memory starting
at $B800 is moved to $8528, and the 
background color from $D021 to
$7110. The reason for these memory 
move are to prepare for a disk save
routine. The above locations are com-
patible with two packages, “DOODLE”,
a graphics program by Omni Unlimited,
and “Koala Painter”, by Audio Light.
DOODLE is used for HIRES pictures,
and KOALA for MULTIcolor pictures.

The DISKSA routine will create a
file file in either mode, depending on
the state of the mode flag. To use this
routine, the file name and length of the
name have to be previously stored in
memory.

Basic Program for FAX Driver
Listing 3 is a Basic program that is
used to control the machine language
programs. First it reads into memory
the ML part (“FAX64.ML”) and the
table of Listing 2 (“TABLE”). Then the
top of memory is set to avoid conflicts
with the graphics.

The main menu allows four options:
FAX scan, Display last scan, Save scan
to disk, or Quit. Obviously, the F option
is chosen first the time. You are then
given the choice of a HIRES scan (only
two colors) or a MULTIcolor scan (four
colors). Then some other commands are
shown and you are instructed to start
the FAX machine.

POKEs are made to start the inter-
rupt routine (NMI) and the software
timer, as well as to configure the screen
for graphics. At this point, the NMI
routine is active in the background. The
Basic program is in a do-nothing state,
checking the keyboard for Q to quit or
for color change keys.

If MULTI mode is chosen, the colors
be changed either during a scan or
after. The four function keys can be
used to change any of the four colors.
F1 is used for the brightest level
(usually white), F3 for the next, etc.
With these four keys, any color com-
bination is possible. The number keys
are used to select any of 10 preset color
combinations. The '2' key selects
shades of white (gray, black), the '3' key
is used for shades of red, etc. Also, the
'C' key can be used to rotate from 1 to 2

...
to 3, and so on. It should be noted that these color changes can be made while the machine is scanning since the program is running simultaneously with the NMI routine.

The Save option first moves the memory areas, turns on the alpha screen, and asks you for a file name. This name is then configured to be compatible with either KOALA or DOODLE, and the name and its length are POKED into memory. You are then instructed to place a diskette into the disk drive. You can change disks at this point, but be sure you use previously formatted disks. Then the ML Save routine is called and you see the menu again.

What Good is a FAX?

What can you do with the FAX?

Well, actually, it can prove to be the best graphic input device that you can use with your home computer. You can capture an image of any picture into your machine. By creating a disk file of the picture, you can then add text, fill in color areas, or enhance the images with other graphic packages. You can dump these pictures to your printer with an appropriate printer dump program.

And you can do it even if you are not very good at drawing.

Some Helpful Hints

Make sure the picture you feed into the FAX is of sufficient contrast and is not bathed in dark shadows. Do not attempt to use it to read in fine text—the interface is configured to reduce the resolution to that of C-64 graphics capability. Make sure the 'brightness' control is set up right so that the machine is putting out four different levels to your computer. To set it, make yourself a 'test pattern' with different gray levels, and digitize it in MULTI mode.

If you have more questions, suggestions, or have found a unique application for the FAX machine, write to me at 713 Locust Drive, Tallmadge, Ohio 44278. I can supply the C-64 FAX driver programs in Commodore 1541 disk format for $10. A FAX machine as used in this article can be obtained from Computer Products & Peripherals Unlimited, Box 204, Newton, New Hampshire 03858. For approx. $189.
### Listing 2. Table of Offsets for Screen Memory

<table>
<thead>
<tr>
<th>Addr</th>
<th>Data</th>
</tr>
</thead>
<tbody>
<tr>
<td>4380</td>
<td>00  01  02  03  04  05  06  07  48  41  42  43  44  45  46  47</td>
</tr>
<tr>
<td>4380</td>
<td>00  01  02  03  04  05  06  07  c0  c1  c2  c3  c4  c5  c6  c7</td>
</tr>
<tr>
<td>4380</td>
<td>00  01  02  03  04  05  06  07  48  41  42  43  44  45  46  47</td>
</tr>
<tr>
<td>4380</td>
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</tr>
</tbody>
</table>

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We are also interested in reviews of specialized hardware such as A/D and D/A interfaces, EPROM programmers, stepper motor controllers, and kits—but not most new computers or peripherals. Unless there is some technical aspect of special interest to our readers.

We prefer reviews from people who are actually using the product rather than from someone who reviews many different products without using any one of them long enough to become completely familiar with all of its features. The reviews should be truthful and should tell it like it is. But the best reviews are the ones you write about products that you like and want to encourage others to use.

If you are interested in writing reviews, send us a short letter with your background and qualifications, and a phone number where you can be reached in the evening. Include products which you now have available for review, and also items which you would be interested in reviewing if we could obtain a review copy.

### Listing 3. BASIC FAX DRIVER PROGRAM

```basic
10 REMXXXXXXXXXXXXXXXXXXXXXXXXXX
20 REMX
30 REMX FAX-DRIVER M.J.KERYAN X
40 REMX FOR C-64 9-84-84 X
50 REMX
60 REMXXXXXXXXXXXXXXXXXXXXXXXXXX
70 IF A=0 THEN A=1: LOAD "TABLE",8,1
80 IF A=1 THEN A=2: LOAD "FAX64.M",8,1
90 POKE52,32:POKE56,32:POKE644,32:CLR
100 DIM C(9,3): CLR=2
110 FOR I=TOP: FOR J=1TO3: READ C(I,J): NEXT: NEXT
120 C1=18221: C2=18226: C3=18231
130 DATA 1,173,6,15,148,8
140 DATA 1,252,8,1,162,8
150 DATA 3,238,8,2,164,6
160 DATA 1,213,8,1,238,8
170 DATA 1,128,9,1,169,8
180 REM MENU
190 GOSUB 1418
200 PRINT"<RON>FAAX MENU(DWN)<DWN>*"
210 PRINT"<F>" "FAAX SCAN"
220 PRINT"<DWN>"(D) "DISPLAY LAST SCAN"
230 PRINT"<DWN>(S) SAVE SCAN TO DISK"
240 PRINT"<DWN>(G) QUIT*" PRINT
250 PRINT"*"
260 GET K$: IF K$="** THEN 260
270 GET K$: IF K$="** THEN 270
280 IF K$="4" THEN SC=1: GOTO 330
290 IF K$="D" THEN GOTO 1348
300 IF K$="S" THEN GOSUB 860: GOTO 1898
```
320 GOTO 260
330 PRINT*('C(ON)ENTER: (8) FOR HIRES (BLACK/WHITE)*
340 PRINT*('C(ON) OR (1) FOR MULTI (4 COLOR LEVELS)*
350 GETK$: IF K$='**' THEN 358
360 PRINT*('C(ON)

"INPUT MODE: IF MODE(0 OR MODE)1

370 PRINT*('C(ON)"(COND)"(CR)"(ON)"WHILE SCANNING, PRESS:*'
380 PRINT*('C(ON)

"TO START AT TOP*
390 PRINT*('C(ON)"(S) TO Synchronize & RESynchronize*'
400 IF MODE(8 THEN PRINT*('C(ON)"(C) TO ROTATE COLORS*'
410 IF MODE(8 THEN PRINT*('C(ON)"(8-9) TO CHANGE COLORS*'
420 IF MODE(8 THEN PRINT*('C(ON)"(F1-F7) TO CHANGE A
COLOR*'
430 PRINT*('C(ON)"(O) TO QUIT*
440 PRINT*('C(ON)"(COND)"(CR)"(ON)"NOW START THE FAX MACHINE.*'
450 FOR I=1TO10000: NEXTI
460 SYS 18195: REM CLEAR 8K BIT-MAP
470 POKE 61317, MODE
480 POKE C1,C(CR,1); POKE C2,C(CR,2); POKE C3,C(CR,3)
490 IF KC2 THEN POKE C1,CA: POKE C2,CB: POKE C3,CC
500 SYS 18285: REM SET COLORS
510 FOR I=18168TO18176: POKEI;0: NEXTI
520 POKE 53272,(PEEK(53272) OR 8)
530 POKE 53265,(PEEK(53265) OR 32)
540 IF MODE(8 THEN POKE 53270,8
550 IF MODE=1 THEN POKE 53270,24
560 POKE 792,0: POKE 793,49
570 POKE 56591,8: POKE 56579,8: POKE 56589,127
580 POKE 56592,84: POKE 56583,1: POKE 56591,23: POKE 56589,
139
590 REM NOW THE NMI ROUTINE HAS STARTED
600 GET KS: IF KS="**" THEN 600
610 GET KS: IF KS="**" THEN 610
620 IF KS="*" OR KS="*" THEN SYS 18254: GOSUB 868: GOTO
180
630 IF MODE(1 THEN 480
640 IF ASC(K$)>47 AND ASC(K$)<58 THEN KC=1: GOTO 480
650 IF KS="C" THEN KC=2: GOTO 710
660 IF KS="(F1)" OR KS="(F3)" OR KS="(F5)" OR KS="(F7)"
THEN KC=3: GOTO 740
670 GOTO 680
680 CR=VAL(K$)
690 POKE C1,C(CR,1); POKE C2,C(CR,2); POKE C3,C(CR,3)
700 GOTO 850
710 CR=CR+1: IF CR>9 THEN CR=0
720 POKE C1,C(CR,1); POKE C2,C(CR,2); POKE C3,C(CR,3)
730 GOTO 850
740 IF K$="(F1)" THEN 770
750 CA=PEEK(C1)+1: IF CA>15 THEN CA=0
760 POKE C1,Ca: GOTO 850
770 IF K$="(F3)" THEN 880
780 CB=(PEEK(C2)AND256)/16+1: IF CB>15 THEN CB=0
790 POKE C2,(CB+1)X(PEEK(C2)AND15): CB=PEEK(C2): GOTO
850
800 IF K$="(F5)" THEN 830
810 CB=(PEEK(C2)AND15)+1: IF CB>15 THEN CB=0
820 POKE C2,(PEEK(C2)AND240)+CB: CB=PEEK(C2): GOTO 850
830 CC=PEEK(C3)+1: IF CC>15 THEN CC=0
840 POKE C3,CC: GOTO 850
850 SYS 18205: GOTO 680
860 REM RESET SCREEN TO ALPHA
870 POKE 53265,(PEEK(53265) OR 223)
880 POKE 53270,8: POKE 53272,21
890 SYS 64931: SYS 64789
890 SYS 65371
900 GOSUB 1418
910 RETURN
920 RETURN
930 PRINT*('C(ON)"(CR)"WHILE VIEWING, PRESS:*'
940 IF MODE(8 THEN PRINT*('C(ON)"(C) TO ROTATE COLORS*'
950 IF MODE(8 THEN PRINT*('C(ON)"(8-9) TO CHANGE COLORS*'
960 IF MODE(8 THEN PRINT*('C(ON)"(F1-F7) TO CHANGE A
COLOR*'
970 PRINT*('C(ON)"(Q) TO QUIT*
980 FOR I=1TO480: NEXTI
990 POKE 18177, MODE
1000 POKE C1,C(CR,1); POKE C2,C(CR,2); POKE C3,C(CR,3)
1010 IF KC2 THEN POKE C1,CA: POKE C2,CB: POKE C3,CC

continued on page 51

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THE COMPUTER CORNER
A Column by Bill Kibler

Well, so starts a new year and a new column. In the past year of writing for The Computer Journal, I have passed over many little topics and interesting tidbits. My recent articles on "tricks of the trade" were attempts to cover some of these topics, yet far too many words of wisdom never make it into print. Considering too, the many questions I receive from fellow computerists, there seems to be a need for a regular column.

As a contributing editor of The Computer Journal it will be my duty to answer your letters of inquiry when possible, as well as those I receive in some of my other activities. This will not stop the major articles on other topics but will allow you to see how I am doing with a project, and in fact, give you a chance to comment on it before completion. A major problem I face in writing articles about hardware is the long development time needed to prepare an article. I am currently working on a series of articles based around the Superbrain computer. Just gathering and sifting the data has taken several months. It is now possible to actually sit down and get started on writing the articles and making the changes I have in mind.

My primary work is with industrial computers, mainly those controlling process systems. Although these units are different than the normal personal computer, there are many facts and concepts that I come across which will be of interest to readers. One such area is the use of small systems running Forth for control applications. I am currently toying with building the Rockwell Forth system or making a Z80 Forth unit. In either case I am interested in others' experiences and in your comments. Having the Rockwell unit in my hands for one night was fun, but at the time I did not have all the documents I needed to do a write up on it.

Being somewhat of a purist, it has taken me some time to give up my 8" drives. Still, the price of new 5 1/4" drives has dropped so much that I must admit to shifting over to them. Now don't get me wrong - I still have an 8" disk system - but now most of my work is on minis. Is this trend important? I think so. Why? There are many things happening with computers these days, and most of them are not technical. The hardware is becoming the least important aspect of the system, and software is definitively the new challenge on the horizon. This change means a lack of available supplies for older systems. The industry is going where the money is to be made, and the money is in minis, not maxis. It is getting harder to find 8" diskettes for under two dollars, but I can get 5 1/4 for a dollar even.

My Z100 computer has found a new home, and Gerry, the new owner, is finding out about all the little points I never had time to investigate. One complaint of mine was the absence of a configuration program. The problem concerns the ever-increasing size of BIOSs. These started out under 2K in length and now run several "K" long. The Z100's BIOS is in two parts under CP/M 85, and the MSDOS is several inches thick. When adding 8" drives or changing to non-standard units it will be necessary to patch the BIOSs. In the old days this was no problem, but now the Z100 is a nightmare and a half. The problem is not one of bringing out the control values into accessible tables. The sign of a good BIOS is that all of the parameters are located in one place, making patching and configuration programs possible. Users with ZDOS 1.0 will be pleased to see ZDOS 2.0 with a configuration program.

When dealing with different systems, I guess the most common problem for me is that of transferring data. My solution is Modem7 and its file transferring options. Running two systems and doing my work on 5's and then shipping it out on 8's has me using Modem7 all the time. When I was working at Micropro we had a program for our development systems that allowed one unit to be a slave to the other. Similar to BYE, this program caused the slave drives to become "C" and "D" drives. If someone has written such a program, please let me know as I haven't found a copy of the old one.

Reinventing this program for generic CP/M systems is my next project, so let me know if you have any ideas on just such a program.

I spent the other day reading about CPNET and got some ideas on the transfer program. Seems Digital Research uses the BDOS calls to control their headers in packetting the data to transfer. This has got me thinking of doing some pushing of registers to create the data packet, and then just popping them and calling the BDOS entry point. This sounds simple until you sit down and start writing the code, but now I have a point to start from. There is also a HAM radio packet program on SIG/M disks that may shed more light on the subject. As I study the problem more, it appears that getting the data packet or format is the part that can cause the most problems.

The new year is here and with it the return of the swap meets. I went to my first one of the year last weekend, and was rather surprised at the change of products. Prices are down as many companies are going under and unloading their warehouses. Another change I've seen is the absence of S-100 boards, or at least a change in their quantity. In the past, S-100 was the most common product at swap meets, but single boards and hard disks are now taking up most of the spaces. After the weekend meet, I need to change my statement that it is possible to build a system for under $800 - I think it is less than $500 now.

Well that's about it for this month. Next month should contain reports on tying systems together, some $80 minis, and what it is like being the editor of a local computer club newsletter.
Interfacing Tips and Troubles
A Column by Neil Bungard

This month I would like to diverge from my series of articles on interfacing tools to stress a point concerning The Computer Journal, and to show you an easier way to interface your Sinclair ZX81 computer.

There is so much information being generated in the area of computers that it is impossible for one person to keep up with it all. As an example, consider my recent articles on interfacing the Sinclair computers (The Computer Journal, Issues 13 and 14). In part one of this series I made the following statement: “The Sinclair machines do not support MMIO (Memory Mapped I/O).” I made this statement because while investigating the capabilities of the Sinclair machines, I was unable to make the machines respond using MMIO. However, as a result of a letter from LED of Michigan (Issue 14), I must “happily” retract my statement concerning MMIO on the Sinclair ZX81. I say “happily” because using MMIO simplifies the task of interfacing the ZX81 considerably. The interfacing task is simplified because there are no machine language routines required, and the hardware problems associated with AIO do not occur when using MMIO. The only disadvantage of MMIO is that it is slower than AIO on the ZX81, but it is my experience that the speed limitations are not a problem in most applications.

The hardware trick for using MMIO, as explained in LED’s letter, is to direct the MMIO operations into the ZX81’s memory space between addresses 8192(D) and 16383(D) (the D denotes decimal values). In addition, when information is transferred to/from this memory space, a signal (logic 1) must be generated and placed on the ZX81’s ROMCS edge connector (pin 23B). With these details taken care of, information can be transferred to/from an interface circuit using PEEK and POKE instructions directly from BASIC. Using MMIO eliminates the need to write BASIC routines to load machine language programs, allocate space for machine language routines in REM statements, determine how data will be passed from the machine language programs to BASIC, and work around crashes and masked bits, all of which were required when using AIO on the ZX81.

**MMIO Hardware**

The circuit required to accomplish MMIO with the ZX81 is shown in Figure 1. Address lines A13, A14, A15, and 3 gates (two “OR” gates and 1 “INVERTER”) from ICs 1 and 5 are required to decode the memory space which is used for MMIO on the ZX81. The 3 gates from ICs 1 and 5 configure a decoder which outputs a logic 0 on pin 6 of IC 1 any time memory locations 8192 through 16383 are addressed. Pin 6 of IC1 is connected to the output enable (pin 1) of tristate buffer IC6.

Figure 1: Schematic. Numbers in parenthesis denote pin number on ZX81 edge connector.
When pin 1 of IC6 is at a logic 0, the tristate buffer input (a logic 1 at pin 3) is connected through the buffer's output (pin 2) to the ZX81's ROMCS input. A logic 1 on the ROMCS input disables the ZX81's internal ROM, thus allowing MMIO operations to be accomplished into the 8192(D) to 16383(D) memory space.

Two 74LS138s (IC3 and IC4) generate 8 input and 8 output transfer pulses by decoding the ZX81's 3 lowest order address lines A0, A1, and A2. Address lines A0, A1, and A2 are connected to pins 1, 2, and 3 respectively of the 74LS138s and pins 5 and 6 of the 74LS138s additionally decode the address bus by detecting when the 8192(D) to 16383(D) memory space is being accessed. Timing of the transfer pulses is accomplished via a memory write (WR) signal and a memory read (RD) signal connected to pins 4 of ICs 3 and 4 respectively. Figure 2 shows the timing diagrams of the MMIO operations.

Information flows into (and out of) the ZX81 via an octal bus transceiver, IC7 in Figure 1. If address space 8192(D) through 16383(D) is accessed, and a memory read operation is being performed, pin 1 of IC7 will be at a logic 0, allowing data to be transferred into the ZX81. If address space 8192(D) through 16383(D) is accessed, and a memory write operation is being performed, pin 1 of IC7 will be at a logic 1, allowing data to be transferred out of the ZX81. The purpose of this octal bus transceiver is twofold. First of all, the transceiver isolates the ZX81 from the interface circuitry, which would save the ZX81's internal circuitry if something went wrong on the interface circuit.

Secondly, the transceiver will boost the ZX81's fanout. This means that more devices can be placed on the ZX81 data bus without loading the bus and causing current deficit problems.

**MMIO Software**

As mentioned earlier in this article, all information transfer between the ZX81 and an interface circuit can be accomplished from the BASIC language set using PEEK and POKE instructions. To accomplish MMIO using BASIC, you must first know where, within the 8192(D) to 16383(D) memory space, the interface circuit is actually mapped. When using the hardware configuration explained above, the 8 memory locations between 8192(D) and 16383(D) are used for input/output.

Figure 3 shows which output pin on the 74LS138s will supply the correct transfer pulse when each of the 8 memory addresses are accessed. The software instructions which accomplish the MMIO are straightforward. To input data from an interface mapped into memory location 8192(D), you would use the following instruction:

```
LET APEEK (8192)
```

This instruction assigns the value obtained from the interface circuit (which will be a value between 0 and 255) to the variable name A. Likewise, to output data to an interface mapped into memory location 8192(D), you would use the following instruction:

```
POKE 8192, A
```

This instruction transfers the value previously assigned to the variable name A (a value between 0 and 255) to the interface circuit.

**Conclusion**

In conclusion, with memory mapped I/O and accumulator I/O now explained, the Sinclair ZX81 can be a very versatile computer for interfacing. AIO has its place where speed is a critical factor, as in applications where a number of values must be obtained in a second or less. But if your application requires acquisition times on the order of seconds or even greater, then MMIO offers you the simplicity to get your system working quickly and easily. As always, we appreciate your response to articles in *The Computer Journal* and look forward to hearing from you if you have questions or comments.

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ANNOUNCEMENTS

Artificial Intelligence Conference
The premiere Artificial Intelligence and Advanced Computer Technology Conference/Exhibition is scheduled for April 30, May 1 and 2, 1985, at the Long Beach Convention Center, Long Beach, California.

The exhibition showcases commercial and industrial applications of advanced computers and software.

Technical experts will present a conference focusing on AI in automated manufacturing, office automation, medicine, robotics, business, training, microcomputers, aerospace, and graphic simulation. Other topics will be: fifth generation computers, natural language interfaces, expert systems, development systems, speech recognition, image processing, cognitive modeling, knowledge information processing, and AI languages including LISP and PROLOG.

Compete details are available from Tower Conference Management Co., 331 W. Wesley St., Wheaton, IL 60187, phone (312) 668-8100.

Computer Interfacing Workshop
Virginia Tech has announced a workshop on Personal Computer and STD Computer Interfacing for Scientific Instrument Automation. These courses, directed by David E. Larsen and Dr. Paul E. Field, will be held August 22, 23, and 24 in the Washington DC area, and September 19, 20, and 21 in Greensboro, NC. The cost is $450 for the three day session, and details can be obtained from Dr. Linda Leffel, C.E.C, Virginia Polytechnic Institute, Blacksburg, VA 24061, phone (703) 961-4848.

Universal RS-232 Data Acquisition
Elecon has announced their PL-100 intelligent peripheral which interfaces with any computer or terminal via a standard RS-232 serial port. It has 16 channels of 12 bit A/D, 2 channels of 12 bit D/A, 32 bits of digital I/O, 8K of ROM and 8K of RAM, plus provision for internal rechargeable batteries and two additional I/O boards. An on-board microprocessor supports simple ASCII...
commands or internal BASIC interpreter. In addition, internal intelligence makes remote unattended applications possible using only a modem (no computer necessary).

Prices start at $549, and more information is available from Elebor Associates, PO Box 246, Morris Plains, NJ 07950, phone (201) 299-1615.

**DSD80 Debugger**

Soft Advances announces DSD80, a full screen symbolic debugging program for 8080, 8085 and Z80 microcomputers running CP/M-80 and compatible operating systems. The dynamic display has instruction, register, stack and two memory windows. The Z80 instruction set is fully supported using either extended Intel or Zilog mnemonics. DSD80 has on-line help and comes with a fifty page user's manual. The price is $125 plus shipping from Soft Advances, PO Box 49473, Austin, TX 78765, phone (512) 478-4763.

**IBM-PC Data Acquisition Software**

Data Translation has announced a series of application software packages to support its IBM-PC compatible data acquisition and control boards. These packages, intended for such applications as chromatography, physiological and speech research, materials testing, and industrial control, do not require the user to write original programs.

DT/Notebook is an integrated, menu driven software package for real-time data acquisition, process control, data analysis, and graphic display. It performs data acquisition at up to 20,000 samples per second and real-time graphic display of data at up to 600 samples per second.

DT/ILS-PC 1 is an interactive, command driven digital signal processing package which supports continuous data acquisition to disk at up to 27,500 samples per second.

ASYST is a command driven package for real-time data acquisition and control, data analysis, and graphic displays able to acquire data at up to 27,500 samples per second. More information on these products and their analog I/O boards can be obtained from Shari L. Supernault at Data Translation, 100 Locke Drive, Marlboro, MA 01752, phone (617) 481-3700.
Back Issues Available:

Ordering Information: Back issues of The Computer Journal are $3.25 in the U.S. Canada, and $5.50 in other countries (air mail postage included). Send your complete name and address with payment to The Computer Journal, PO Box 1697, Kalispell, MT 59903. Please allow three to four weeks for delivery.

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- Build an "Epram"

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