Fuzzilology 101

The Cyclic Redundancy Check in Forth

The Internetwork Protocol (IP)

Z-System Corner

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TCJ readers are invited to join us in the CP/M SIG on page 685 and the Forth Interest Group SIG on page 710. Meet the authors and editors of The Computer Journal! Enter "M 710" to join the FIG group and "M 685" to join the CP/M and Z-System group.

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Editor's Desk

By Chris McEwen

By necessity, my column in this issue is going to be very brief. My health has not been good the last few months and I have spent several weeks in the hospital. As a result, we have skipped the March/April issue and gone straight to May/June. You will not lose an issue from your subscription, however, as the expiration are set to issue number, not month.

In the meantime, please pardon me if the magazine is not right on time over the next few months. It will take some time for my health to fully recover. Your understanding is appreciated.

A new author joins us. Walter Rottenkolber discusses the cyclic redundancy check and gives us Forth code for it. We also welcome back Frank Sergeant with his Bumbling Mathematician.

Matt Mercola opens a topic we haven’t covered in a while: fuzzy logic. I hope to see more on this. Lee Hart has expressed a desire to write more on it.

Add in Paul Chidley’s work with the Z180 YASBEC and his new column Hardware Hacker, Roger Warren’s work with the NZCOM virtual BIOS, Wayne Sung’s discussion of IP along with Bill Kibler, Jay Sage, Rick Rodman and Bill Tishay and I’d say we have a pretty good way to spend a few evenings. Enjoy!

---

Reader-to-Reader

I noticed a few things in my 6809 assembler article that should be corrected:

a) The table of valid indexed addressing modes (p.8, first column) shows ’‘,” as the “autodecrement by 2” mode indicator; it should be ’‘,” (two minus signs). I think this happened at your end.

b) The Forth fragment on page 12, for the word CODE, should read create here dup 2−−1. The DUP was omitted from the article.

c) You neglected to mention that the source code for the assembler is available on GEInc’s Forth Roundtable as 6809ASM.ZIP. (Tsk, tsk...shame on you.) Also, here is an update on the Super8 article:

WAKE-UP:

The transmit wake-up bit works differently on rev 0 and rev A parts. The difference appears to be when the selected wake-up value—as selected in bit 0 of the UART Mode A (UMA) register—is latched for transmit. It seems that the rev 0 parts have a 9-bit transmit shift register, but only an 8-bit Transmit Holding register, so the transmitted wake-up bit depends on the value of the UMA bit0 when the byte is moved from the holding register to the shift register. The rev A parts seem to have a 9-bit Transmit Holding Register, so the transmitted wake-up bit depends on the value of UMA bit0 when the byte is written to the Transmit_Holding_register (UIO). In other words, in the rev A parts you must set UMA bit 0 before writing the character to UIO; in the rev 0 parts you must do likewise, but you must also leave UMA bit 0 set until the Transmit Buffer Empty signal becomes active.

—Brad Rodriguez

Thanks for the note, Brad. You’re right. The source for the 6809 assembler is available in the Forth Interest Group Roundtable software libraries on GEInc. And here is the big paragraph that we didn’t get to run on your Super8 article.

Doug Fleener is a microcomputer hardware & software specialist serving the entertainment industry. He left the security of full time employment in September 1990 to join the ranks of struggling (but happy) independents. Doug’s current processor of choice is the Zilog Super8, because “it does everything I need...for now”. His extensive work on lighting control multiplex systems earned him the nickname Dr. Mux, which he accepted in “Yankee doodle” style: he has been known to wear a doctor’s lab coat to industry trade shows, with an oscilloscope probe around his neck. Doug can be reached at Doug Fleener Design, 396 Corbett Canyon Rd., Arroyo Grande, CA 93420.

Brad Rodriguez is another veteran of the entertainment lighting industry, whose infatuation with Forth and Forth-supporting processors is well known. Brad was introduced to the Zilog Super8 by Doug Fleener in 1987, and has been enamored of it ever since. Currently Brad is putting the finishing touches on a commercial Super8 Forth compiler, and also on a Super8-based multiprocessor lighting control system. He prefers to be contacted as B.RODRIGUEZ@GEInc, but will accept email as bradford@maccs.dcss.mcmaster.ca on the Internet, or paper mail at T-Recursive Technology, 231 King St. E., Suite 32, Hamilton, Ontario L8N 1B5 Canada.

Brad and Doug have collaborated on several Super8-based projects, among them the Teatronics Producer II+, Quantum, Comstar, MD288, and Echelon. Between them, Brad and Doug claim to have used every function and feature of the Zilog Super8.

---

Letters to the editor and other readers are welcome. Submit to The Computer Journal, P.O. Box 12, South Plainfield, NJ 07080-0012. Letters may also be electronically submitted via GEInc’s to TCJS@. Submission implies permission to publish your letter unless otherwise stated. Letters may be edited as necessary.
Fuzzilology 101

What, precisely, do you think you’re doing? Fuzzy Logic may help.

By Matt Mercaldo

Fuzzy Logic! What is fuzzy logic? The Japanese seem to know. They are using it in all types of commercial goods that once were difficult to use. Now by the use of this technique of hardware and program we can shake when video taping, get in focus while filming, drive our cars easier and with more peace of mind and the list continues to go on.

Fuzzy Logic! What is fuzzy logic? As program and hardware scriveners we have to know. Is it just a way to make programming easier? Is it just "The right way of doing things that we’ve done all along anyhow"? Well, sort of.

Let’s first talk about fuzzy logic in terms of what it is and is not. Fuzzy logic is not “crisp” logic. Crisp logic means that a square peg will fit in a square hole and a round peg will fit in a round hole and that is the law of the land. For a lot of applications, Crisp logic is the right way of approaching the problem and has been for years and years. When a specific combination of switches is set (and not set) in some huge evolved automaton of the factory floor, a crisp logic based system will find a rule which matches the combination of the on’s and off’s. When the correct rule is found, the system will take the winning rule’s action. Crisp logic usually has one winner and systems tend to become hierarchical (many levels of if’s and then’s and else’s all nested together in the typical complete and confusing construct).

Fuzzy logic is not fuzzy at all! Actually it is the essence of structure; in an extensible sort of a way. Systems using fuzzy logic tend to make creation of a control system or like event driven system old hat. With the proper fuzzy logic system creation tools, complex process control systems can be constructed and simulated in a very short time. Examples of this technique even exist where a fuzzy system can teach itself by adapting its membership sets to a new environment (Membership sets will be explained shortly). (This sort of thing is critical when the six legged explorer you have spent billions of dollars creating needs to relearn how to walk when it reaches the moon with the moon’s lower gravity!)

Fuzzy logic systems are not neural networks. Trust me on this one! We do not have time to enter a treatise on Neural nets. Fuzzy logic is closer to a production system (similar to that found in an earlier article of my authorship on stepper motor control) than neural nets.

Let us come up with a simple working definition for Fuzzy Logic. Fuzzy logic is a technique of associating a degree of truth to the relationship between a set of monitored data and a rule’s antecedent. Unlike crisp logic, all rules participate in the output result.

“Right%#!!!!” you say. Maybe a deeper look into an actual example may help. "Johnny, if I’ve told you once I’ve told you a thousand times!! Some day you are going to break your head open and I’ll have to pick up the pieces!! Get off of the swings only when the swing has stopped swinging—I mean completely stopped."

Ah, the carefree days of childhood! The mother, in this little remembrance, has laid down the law of the land in quite a crisp fashion. But later the day crawled onward for Mommy, and soon she wished to go home and relax.

"Ok Johnny you can get off of the swing. It is slow enough for you to get off now". Interesting! Slow Enough—not quite the crisp answer. If Johnny were driven by a PLC all sorts of interesting things would happen. Good thing Johnny is just a red blooded American boy. There’s the jump, and off the swing Johnny flies!

So is Mommy double talking? Well not really, actually she is using fuzzy logic to make a decision as to the law of the land. (Fuzzy Logic in the Practice of Law?...Hum) Let us get really clinical about swings and pendulums. Swings are a lot like pendulums if you really think about it. There is a distance from the center point (Center point being where the law of the land said Johnny could get off the swing the first time the law was spoken forth), and there is a momentum or speed at which the swing is swinging (This must be zero—no swinging—in the crisp law of the land as laid down by the Queen of the land; Mommy). We will call the angle of the swing to the center point THETA, and the momentum or speed of the swing dTHETA. When Johnny is swinging with all of his might (in order to reach the moon or any near planet) his dTHETA is highest.
when his THETA is lowest and likewise his dTHETA is lowest as his THETA is highest. Gravity does wonders at keeping little boys feet on the Earth and swing fast and high and not necessarily all at the same time. We will use THETA to help the Queen determine the Fuzzy law of the land, because the law of gravity will be in magical proportion to the THETA and the law of the land.

We will assume THETA to be feet between the center point and the seat of the swing. By careful judgment the Queen (Mommy) has decided that when THETA is between one and two feet from the center it is safe for Johnny to get off of the swing. We could even draw a little graph to illustrate this as you see in figure 1.

The careful reader will note that it is very safe to jump when THETA is zero and the degree of membership in Safe is 1. The reader will also note that it is not safe to jump when THETA is three and the degree of membership of Safe is 0. So when Johnny’s THETA is 1 foot it is 50% safe to jump. As the speed increases from 1 to 2 THETA, jumping becomes more dangerous, more exhilarating, and altogether more fun; Johnny wants to optimize his exit for a THETA of 1 foot, 11.99 inches. Johnny will still be within the current limits of the law and having the most fun! This my friends is the very essence of Fuzziology!

Let us make a simple fuzzy rule base for the laws of the swinging within and without the limits of the law.

\[
\text{IF} \quad \text{THETA IS ZERO} \\
\text{THEN} \quad \text{EXIT IS MOST_SAFE} \\
\text{END} \\
\text{IF} \quad \text{THETA IS LOW} \\
\text{THEN} \quad \text{EXIT IS MOST_EXHILARATING} \\
\text{END} \\
\text{IF} \quad \text{THETA IS HIGH} \\
\text{THEN} \quad \text{EXIT IS MOST_DANGEROUS} \\
\text{END}
\]

Well, ok. ZERO seems tangible enough, but what about LOW, HIGH, and MOST_SAFE, MOST_EXHILARATING, and MOST_DANGEROUS? Another graph may illustrate the point. Each fuzzy term such as ZERO, LOW, and HIGH, has a set associated with it. In high and scholarly mathematical circles this means a function with long descriptive symbols and numbers with meaningful descriptions attached. For the Hardware Hack this means a lookup table. However and for whomever the membership set is used, it determines an input’s degree of membership in the given class. The output membership set can be either an output function or what is called a Singleton. A singleton is a value that represents the desired non-fuzzified output. We will investigate this more closely a little later. Take a gander at Figure 2.

In light of the new set graphs let us look at the rules again and think of how this would work in a system. First the THETA value would be sampled, and held. Each rule antecedent would fire with the new THETA value.

Let us make a little techie decision here: The value will be an eight bit value for THETA. With this bit of coercion, we assume that each membership set has been defined in a 256 byte table. Let us assume that THETA when sampled was what would equivocate 1.4 feet for THETA (somewhere around 7C in our 8 bit hex understanding).

\[
\text{RULE one's antecedent states IF} \quad \text{THETA IS ZERO} \\
\text{The value for 1.4 is looked up in the membership table for ZERO and found to have a degree of membership of around 10%}
\]

\[
\text{RULE two's antecedent states IF} \quad \text{THETA IS LOW} \\
\text{The value for 1.4 is looked up in the membership table for LOW and found to have a degree of membership of around 60%}
\]

\[
\text{RULE three's antecedent states IF} \quad \text{THETA IS HIGH} \\
\text{The value for 1.4 is looked up in the membership table for HIGH and found to have a degree of membership of around 0%}
\]

The percent of membership are remembered for each antecedent for each rule as the rule’s Fuzzy Output. Fuzzy Output is a value that indicates a degree of truth for a rule’s antecedent. Fuzzy Output is an intermediary value between the portion of the rule which declares a verdict and that portion of the rule which carries out the judgment. In fuzzy systems with more than one antecedent component, the Fuzzy MIN rule is applied to the antecedents subparts. The fuzzy min rule states that the lowest percent of membership of the antecedent’s parts will be the Fuzzy Output or degree of truth of the antecedent of the fuzzy rule under scrutiny. The reader can think of the antecedent of a fuzzy rule as a chain. Each antecedental component is a link in the chain. Just as the strength of the chain is determined by its weakest link, so the degree of truth of a fuzzy rule is determined by the rule’s weakest antecedental component. The above process is called Defuzzification.

After the fuzzy outputs are determined for all of the antecedent components, they work together to calculate a value for the system output or system outputs. The process of getting a meaningful output is called Defuzzification. A standard way of defuzzifying is by the Center of Gravity defuzzification method. The defuzzified outputs are looked up in the output membership set tables MOST_SAFE, MOST_EXHILARATING, and MOST_DANGEROUS or if Singletons are used, the singleton values for MOST_SAFE, MOST_EXHILARATING and MOST_DANGEROUS are used. Singletons are like a Tone setting on a stereo. A tone knob sets what the tonal quality of the stereo will be. Imagine the notches of HIGH, MEDIUM, and LOW on the tone control as singletons. There are three positions given. Any setting can be described in relationship to one of those settings. In fuzzy rule systems, singletons are used as starting points to determine the output, or in our example, the Tone level of the stereo. Singletons working together with Fuzzy Outputs (used in the center of gravity formula), determine a final setting that will be within a system output’s allowable range of outputs. In the tone control example, the system output will be the Tone setting on the tone knob. The tone knob can only go so far to the LOW or...
to the HIGH. Also the output value may not necessarily be the same as any singleton value either. Once again, the tone knob may not find itself on LOW or MED or HIGH after all is fuzzily inferred and done.

If output membership sets are used the output membership set takes a degree of truth and use it to look up or find a specific value in a range of values. In the above singleton example illustrated with a stereo’s tone control knob, output membership sets give us an equalizer. Each membership set would equate a frequency range slider. Assume that instead of the pre-set positions on a tone knob we have an equalizer with three sliders adjusting each range of HIGH, MEDIUM and LOW. The LOW slider would not have values in the HIGH range and so on. The antecedents Fuzzy Output value would “move” the slider within the Targeted range of HIGH or MED or LOW as appropriate to the consequent of the fuzzy rule. Note that the consequent of a fuzzy rule is specific to an output and a range. In the above rules we see:

THEN? EXIT IS? MOST_SAFE

EXIT is the fuzzy output and MOST_SAFE qualifies the output.

Ultimately we would get something very close to the singleton value for that range. Output membership sets are kind of like a fine tuning over Singletons just as an equalizer on a stereo lets the audiophile adjust the stereo’s response more resolutely than a tone control knob could. When an output memberships value is ascertained then, it is used the same as if it were a singleton. The Singleton will be used in the below example for ease of explanation.

For each consequent of each rule the fuzzy outputs (degree of truth of the antecedent as captured in the Fuzzy Output variable for each rule) will be combined with the Singleton or output membership set value in the following center of gravity formula.

For each Fuzzy Rule do

\[
F_1 \cap \text{Singleton} = (S_1 \cdot F_1) + F_1 \cap \text{Singleton}
\]

\[
F_1 \cap \text{Singleton} = F_1 + F_1 \cap \text{Singleton}
\]

Where \(F_1\) is the fuzzy output value of the \(i\)th rule, where \(S_i\) is the Singleton value of the \(i\)th rule and where \(F_1 \cap \text{Singleton}\) is used to hold the sum of \(S_i \cdot F_i\) accumulated over all of the fuzzy rules, and \(F_i \cap \text{Singleton}\) is used to hold the sum of the fuzzy output values accumulated over all of the fuzzy rules.

In our example the formula would look like the following assuming Singletons or output membership values of \(.1\) for MOST_SAFE, \(.5\) for MOST_EXHILARATING, and \(.3\) for MOST_DANGEROUS.

\[
(1.1 \cdot 1) + (1.6 \cdot 1.5) + (10 \cdot 1) \\
.1 + .6 + 0 \\
.7
\]

\[
0.1 + .6 + 0 \\
.7
\]

\[
1.3 = \text{System Output}
\]

It is a rare enterprise that can assume it will be serving exactly the same market with the same products in ten years time.

—Jesse Werner

So 1.3 is the system output of EXIT which means that Johnny will have a most exhilarating jump completely within the limits of the law. We can see that ZERO’s fuzzy result had an impact on the output, that HIGH had no impact on the output and that MED had the most impact on the output. Membership functions are determined by an intuitive guess initially. The Queen of the land in our swing example knew that when the swing was about two feet from its centerpoint then the jump became dangerous for a boy of Johnny’s size and weight. In a similar way an engineer would determine the initial values for the membership set. The membership set would then get “tweaked” into acceptable values. Our fearless Queen Mommy may see Johnny jump from a THETA of three feet, see the excitement of her boy, and see that maybe three feet wasn’t so bad and alter the membership sets accordingly to allow safe jumping to include jumping from a THETA of three feet. Yes, this can tend toward the more “black magic” arts of our profession such as analog system designs if attempted without the proper tools and simulation software.

This technique becomes more exciting when doing problems where the output actually drives a motor or some like device in servo applications (The infamous and almost classical inverted pendulum problem). When viewed deeper Fuzzy logic opens new doors to autonomous systems development. Code was actually developed on the F68HC11 New Micros chip; but after long contemplation it is the author’s belief that effective fuzzy control will be better done by professional packages that support custom ASC Fuzzy controller chips. If the general TC readership wishes, I will write an another article around the fuzzy production systems internals and tools that I have developed.
The Cyclic Redundancy Check in Forth

By Walter J. Rottenkolber

This study of the Cyclic Redundancy Check (CRC) grew out of a desire to upgrade my faithful modem program, a patchwork of public domain and homespun 8080 assembly code. The thought of tackling 128K of code daunted me and I decided to recast the program, with enhancements, into Forth. Since the source code of the few Forth modem programs I had dated way back and only used the original checksum, this seemed the ideal time to review CRC's in general, to explore the algorithms available to calculate the CRC, and to develop some useful Forth routines.

I searched my library, and fortunately unearthed some articles written in the days when articles routinely included source code (though not often in Forth). T. Ritter’s article proved most helpful, though I’d never before considered Pascal to be a write once, read never language.

In transferring data, a change of even one bit can result in great problems if that data is a program. The Cyclic Redundancy Check is designed to detect even minute changes (errors) in a block of data after a transfer, especially burst errors shorter than the CRC polynomial, and errors of three or less bits. The CRC will detect 99.998% of all errors, which is more than 460 times better than the original xmodem checksum. Though it can’t correct the error, the CRC can at least sound the alert, and perhaps even initiate a retransmission of the data block.

How Does a CRC Do It?

The CRC works by concatenating all the data into one huge number, and appending a number of zeros to the end equal to one less than the degree of the CRC polynomial. It is then divided by the CRC polynomial using modulo-2 (exclusive-or) arithmetic. The quotient is thrown away and the remainder kept as the CRC value. The CRC polynomial, itself, is a number specially selected to provide (hopefully) unique remainder values.

A polynomial is an algebraic expression of the form

$$ax^n + ax^{n-1} + ... + ax^1 + ax^0$$

and it describes the class of algebraic numbers, to which the integers belong. Note that the power (n) begins with zero and goes to n, the degree of the polynomial.

By substituting the radic (number base) for the x, and a number from 0 to x-1 for the ‘a’, an integer is generated. For example, the decimal number:

$$2*10^3 + 5*10^2 + 7*10^1 + 3*10^0 = 2000 + 500 + 70 + 3 = 2573$$

Several polynomials are known and used (see Table 1) to deal with different size data blocks. The maximum block size a polynomial can accurately handle is given by: \((2^n-1)\). For a CRC of 16 degrees, this works out to \((2^{15}-1)\) bits, or 4095 bytes. Larger blocks require larger polynomials, and this is why Z-Modem uses a 32 bit CRC.

The polynomial used by XModem, XModem-1K, and YModem, is the well-known CCITT CRC polynomial: \(x^{16} + x^{12} + x^{5} + 1\). It’s a bit hard to visualize, because this is actually a cryptic summary that only notes the non-zero values in a binary number. But if we flesh it out with nulls, we get:

1 0001 0000 0010 0001

If you keep your eye on the ball, you will notice that a CRC-16 has 17 bits. So how do we handle the division simply, in real time, with a CPU having 16 bit registers? Easier than you think, thanks to the fact that CRC is the remainder, and the quotient is thrown away.

Let’s walk through a simplified CRC calculation as using a four bit polynomial to generate a three bit CRC:

$$\begin{array}{c|c}
0010 & \\
1001 & 10110000 \\
1001 & 0001 \\
1001 & 0000 \\
1001 & 0100 \\
1001 & 0000 \\
1001 & 0010 \\
1001 & 0000 \\
1001 & 010 = 
\end{array}$$

Note that the dividend is XOR’d with the polynomial only when a data segment has a one in the most significant bit (MSBit), and that this bit in the remainder is always reset to zero in the XOR. Since all we need is the remainder, the MSBit of the accumulating data can be used as a flag to indicate when to XOR, allowing us to eliminate the MSBit of the polynomial from the calculation.

Using the bit shift method with the same 3-bit CRC, 23-bit data, and an abbreviated polynomial we get:

$$\begin{array}{c|c}
100 110 000 & \\
001 & 001 \\
000 & 100 \\
000 & 000 \\
000 & 010 \\
000 & 000 \\
000 & 001 \\
000 & 000 \\
000 & 010 = 
\end{array}$$

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The data is shifted a bit at a time into the CRC register MSBit first, while at the same time the MSBit of the CRC is shifted into the carry flag [x]. If the carry flag is set, the CRC is XOR’d with the shortened polynomial number, otherwise just the shift is done. The CRC ends up the same. Note that the pattern of the carries, reading from top down is the same as quotient in the prior example.

The CRC as done in Modern 7 is a three step process. First the CRC register is reset to zero. Next the data block is fed through the CRC generating routine. Finally, on send, null data the size of the CRC data type (16bits) is fed through. The value remaining in the CRC register is then tacked onto the end of the data block.
On receive, the same procedure is done, except that at the end of the data block, it is the CRC bytes that are fed through. If all goes well, the value in the CRC register ends up as zero.

Although this CRC is a standard, it is not perfect. It is not compatible with hardware generated CRC's because the data is passed to the CRC routine beginning with the MSBit. Normally, serial data is sent least significant bit (LSBit) first, and processed by the hardware in that order. Also the use of nulls to begin and end the CRC reduces the ability to detect extraneous leading nulls, or errors in long strings of null data.

For this reason, the SDLC, HDLC, and CCITT synchronous protocols use a variant of the CRC, the Frame Check Sequence (FCS). This begins with the FCS register set zeroes. The data is fed in LSBit first using routines otherwise similar to that for the Modem-7 CRC, including the same polynomial. At the end, the FCS register is flushed by entering data composed of ones. The resulting checksum value is then ones-complemented before being transmitted. The receive process is similar except that at the end, the checksum is fed in. The error-free remainder is a non-zero constant, whose value depends not on the data, but on the polynomial used. (Or so my references say. But when I tried it out the error-free remainder was zero, just as with the CRC.)

However, don’t panic! Line noise still causes most of my modem transmission problems. This tends to generate ones, not nulls, and to change the block length to boot. Whatever defects the Modem-7 CRC has in theory don’t seem to show up in the real world.

### A Cornucopia of CRCS

Screens 2-9 show three different methods of generating the Modem-7 CRC’s—bit-shift, byte-shift, and table lookup. Both high level Fort and assembly versions are given. Screens 10-12 provide words to test and compare CRC routines.

In the bit-shift and byte-shift assembler routines, the BC Register is saved early on and later restored. Don’t change this in a misbegotten attempt to increase speed. In the CP/M version of Fort-83, the BC Register holds the Interpreting Pointer (IP), which refers to the parameter field of the currently executing Fort word. If you trash this register, you trash the system. So assembly routines that use the BC Register must also preserve and restore its contents.

### The Bit Shift CRC

The bit-shift CRC method is a scaled up version of the second example given. The assembly version is just a Fort translation of the original Modem-7 assembly code. Data is shifted into the CRC register through the carry-bit. The operating scheme is shift, test, and ?XOR with the polynomial (1021 hex). The high level version is less elegant because there is no ready way to test the carry-bit. So it checks if the MSBit is a one with 0<, since negative numbers have the MSBit set. The method here is to test first, save the flag, shift, and then XOR. The data bit also has to be 'shifted' into the CRC indirectly.

### The Byte-shift CRC

The byte-shift method is more properly called the bit-block shift method. As the bits are shifted out of the CRC register, the MSBit acts as a trigger to activate the XOR at the other polynomial XOR points. So the bits to the left of a polynomial point behave as a pattern for those bits located to the right of it.

<table>
<thead>
<tr>
<th>Polynomial XOR Points</th>
</tr>
</thead>
<tbody>
<tr>
<td>01010100 01010011</td>
</tr>
</tbody>
</table>

We can take this block of bits left of a polynomial point, and XOR the affected bitblock to the right of it. Of course it has to be done for each point, and that is where the algorithm gets tricky.

The following is what happens with BYTE2-CRC16.

<table>
<thead>
<tr>
<th>10011001 01010011 old CRC</th>
</tr>
</thead>
<tbody>
<tr>
<td>10010100 01001011 AND, SHR+4, FF00 AND, XOR</td>
</tr>
</tbody>
</table>

Consider what happens as the CRC shifts to the left and the data byte is fed in. As the leftmost four bits (nibble) exits, the next nibble passes through the XOR point at Bit-12. For every ‘1’ in the first nibble, a corresponding bit in the second nibble is XOR’d. Instead of proceeding at a bit at a time, we could accomplish the same changes if we take the first nibble, shift it under the second nibble, and use it as a mask to XOR the bits as a block.

Since four more bits get shifted, we need to repeat this procedure with the second and third nibble, but for the moment we just shift the nibble to form mask#1, and hold it.

Now as the eight bits in the MSB shift out, the XOR point at Bit-5 will effect the five bits to the left of it as well as the first three bits of the data. By shifting the MSB three bits to the left, we get a XOR mask spread over two bytes (mask#2) that reflects the changes that would occur. The two masks are XOR’d to form an XOR template.

Lastly we need to consider what happens to the data as it passes the XOR point at Bit-0. Since every bit in the MSB effects the data, the entire MSB is the mask for the data. Moreover, after the shift, the LSB of the old-CRC must end up as the MSB of the new-CRC. The easiest way to get these two bytes in their proper order is by flipping them. The XOR template is already properly positioned.

So you now have a sandwich of XOR template, flipped old CRC, and data-byte. When these are all XOR’d together you get the new-CRC.

Like a camel, this algorithm looks strange but it works.

The two CRC methods just discussed use Fort words for binary shifts. The shift left (2<) is straightforward, and is accomplished not by using the bitshift opcodes, but by simply adding the number to itself. This is an old assembler trick that does the same thing but is actually faster. The shift right is more complicated as there are two of them. The first (2>) is the arithmetic shift
and is used with signed integers. As the numbers are shifted right it copies the MSBit, which preserves the sign of the number; e.g. 100111102 becomes 11001111, not 01001111. The second (U2) is the logical shift and is used with unsigned integers. As the bits shift right, the MSBit is set to zero. It's amazing how obscure a bug can be if you mix up these two right shifts.

The Table Look-up CRC

The table lookup method makes use of the fact that the most significant byte merely acts as a trigger for the CRC polynomial, and is then discarded. Therefore, this byte uniquely defines what happens to the least significant byte and the data byte. If we set these latter bytes to zero and calculate a CRC, we form an XOR template that can be used to generate the new CRC.

First you must set up a table of 256 templates calculated on a most significant byte incremented from 0 to 255, and using this byte as an index into the template table.

<table>
<thead>
<tr>
<th>index</th>
<th>0</th>
<th>0</th>
<th>Generate CRC for Table</th>
</tr>
</thead>
</table>

To calculate the new-CRC, you use the MSB of the old-CRC as an index into the CRC Table and get the template. Then XOR the LSB of the old-CRC with the MSB of the template, and the data byte with the LSB of the template. Voila! Instant new-CRC.

(index)  
LSB -- old-CRC  
MSB -- template  
LSB-old CRC data byte -- XOR  
MSB -- new-CRC

CRC How They Run

Screens 10-12 provide words to test the CRCs. I made UPDCRC a deferred word so that the switching from one CRC method to another is easy. TBIT1 switches in BIT1-CRC16 into the test suite, and the remainder of the list does the same for the other CRCs.

To check the accuracy of the CRC, I used GENCRC and CHKCRC. GENCRC acts as a send routine and generates the CRC from data placed at TADR. CHKCRC behaves as a receive routine and calculates a CRC from the data and the check sum passed in GENVAL. The two CRC values calculated are then displayed, along with any error messages. The CRCVAL from CHKCRC has to be zero, or you have a problem.

Time tests are done by TCRC. This does a CRC on several blocks so that a reasonable time elapses for accuracy with hand timing (my Kaypro has no internal clock). I began with #BLKS set at 10 to get a rough estimate, and then increased it to 30 to detect finer differences in performance. Since some time is taken up by the loop itself, OLOOP defines a null loop whose time is subtracted from the raw CRC times. This allows for more accurate comparisons among the CRC methods.

DCH contains the data used by ITB to fill the block pointed to by TADR. If you want more random data, you can point TADR to the Forth system and do a CRC on parts of it instead.

I performed the time tests of the CRC routines on my 5 MHz Kaypro II, and summarized them in Table 2. Realize, though, that the speed of the routine is not the speed of the file transfer program, but it does give you a starting point for program design.

The table lookup method proved fastest of the group in both the high level and assembler versions. The only disadvantage is

See CRC, page 12
The Internetwork Protocol (IP)

By Wayne Sung

There is a very large and well-connected data network which covers nearly thirty countries and encompasses tens, perhaps hundreds, of thousands of computers. This network is called the Internet.

The Internetwork Protocol, commonly called IP, is perhaps the most popular protocol in wide-area networking. It also functions quite well in local area networks. It has been used in amateur packet radio networks at speeds of 1200 bps and in supercomputer networks up to hundreds of megabits per second, without modification.

"an IP implementation should be conservative in what it sends, liberal in what it receives."

There are several advantages to using IP rather than another protocol. The most important of these is that IP is not owned by any one company. It was developed by the US Department of Defense and therefore belongs to all taxpayers. This means any company is free to implement IP. It also means that there are several implementations that can be considered reference models against which a new one can be tested.

IP was designed specifically for survivability. Although this was originally meant to insure communications in battle situations, the robustness built into IP makes it particularly able to handle poorly designed networks. For example, there is a rule that an IP implementation should be conservative in what it sends, liberal in what it receives.

This means: do as good a job as possible in making your implementation correct, but try to process incoming packets even if they are slightly malformed. This robustness principle has often been neglected, particularly in local area network situations, because the environment is so sterile compared to what IP was designed for originally.

I have noted earlier that all networks tend to get bigger with time. Starting with a well-built IP means that no software changes will be necessary when the network expands.

I will not attempt to describe everything there is to know about IP here. Entire textbooks have been written for that purpose. In particular, IP is normally used with other protocols, and indeed may have started the whole idea of layered protocols. These other protocols provide functions beyond what IP itself provides, which is primarily addressing.

A minimum IP header is 20 bytes long, of which 11 bytes are involved in addressing. It has been said that IP was not designed by committee, and therefore all the fields in the header are actually necessary. This is certainly true in the minimum header, which is used in by far the majority of situations.

Every IP-capable machine has at least one IP address, which is a 32-bit integer. The way this address is interpreted is what distinguishes IP's wide-area capabilities from other protocols. The most significant bits of the IP address are called the Network Number, and the other bits the Host Number. The exact division point depends on three classes of addresses: A, B, and C.

Class A networks are considered 'big' networks and have eight bits of network number followed by 24 bits of host number. Class B networks are considered 'medium' size and have 16 bits each of network and host number. Class C networks are considered 'small' and have 24 bits of network number and eight bits of host number.

The size designation is based only on the address space available for host addresses, not how large an organization might be. For example, a company that supplies communication services might have switches located throughout the country. These might be hundreds of these switches, making it easier to use one

"Often a company will bring up a network with an arbitrary network number only to find that when they have to connect to the Internet everything has to be renumbered."

Wayne Sung has been working with microprocessor hardware and software for over ten years. His job involves pushing the limits of networking hardware in attempting to gain as much performance as possible. In the last three years he has developed the Cag-a-matic series of testbeds, which are meant to see if manufacturers meet their specs.

class B network rather than several class C networks. The company itself might not be very large at all.

All IP network numbers are assigned by the Defense Data Network's Network Information Center, commonly called the NIC. An organization with requirements for IP networking requests one or more network number assignments from the NIC. This registration process is what guarantees IP internetworking, because IP packets are switched from one place to another based on the network addresses.

Often a company will bring up a network with an arbitrary network number only to find that when they have to connect to the Internet everything has to be renumbered. This is why companies
should consider applying for a network number assignment even if they have no immediate plans to connect to the Internet.

To make the 32-bit number a little easier to handle, it is expressed in terms of four eight-bit numbers. Thus Internet addresses are generally seen in the form W.X.Y.Z, where each of W, X, Y, Z takes on values from 0 to 255. The class distinctions fall on eight-bit boundaries. Class A networks use only W for the network number; class B networks use W.X, and class C networks use W.X.Y.

“Some systems have exploited the ability of Ethernet controllers to be given a user-defined address”

Class A networks have numbers in the range 1 to 126. The values 0 and 127 are reserved for special functions. Class B networks have W values in the range 128 to 191. Class C networks use W values starting at 192. Notice that since class B networks have 16 bits of network address, there can be many more class B addresses than class A addresses. Similarly, since class C has 24 bits of network address, there can be many more class C addresses than class B.

When a network address is assigned, the network portion is filled out for you and the host fields are zeroes. Thus 10.0.0.0 is called Net 10, and 128.1.0.0 is called Net 128.1 (this also shows why a host should not be numbered 0, because this could be confused with the network number).

Certain network numbers are special cases and will not be assigned to anyone. For example, the address 255.255.255.255 is considered a broadcast just as the Ethernet broadcast address is all ones. Net 127 is called the ‘loopback’ network and is used internally by many IP implementations. There are also host numbers which should not be assigned. The address on any network which is all ones is also considered a broadcast, so a host should not be assigned that address.

In comparison, when you and I each buy an Ethernet controller from a certain company, the controllers will have 48 bit Ethernet addresses which would seem to be usable for routing purposes. The reason they are not is that there is no guarantee that each controller’s address falls in a particular range. If we both went to the store on the same day, the addresses might very well be adjacent.

Without a part of the address guaranteed to be distinct across organizations, routers cannot be used. In essence, the Ethernet address is a degenerate case of routing where only the entire address can be guaranteed unique. This also means that the only way to send messages is by the entire Ethernet address, limiting the application to one Ethernet.

Some systems have exploited the ability of Ethernet controllers to be given a user-defined address by programming addresses with more carefully defined network and host portions. Without a central address authority, however, there is still no guarantee that any two companies can connect together. Each may have chosen the same network portion, because many people set up computers using the default supplied by the manufacturer.

Thus 8 bytes of an IP header are the source and destination IP addresses. Every IP packet is considered distinct from every other, and normally routers treat them that way. However, there is a sequence number (16 bits) in each IP packet. The sequence number does not imply that any packet is related to any other, but does supply an additional value which may be used for identification purposes.

It is also possible that two hosts may be sending IP packets to each other, but for different reasons. There is an eight bit number called the protocol field which identifies what higher-layer protocol is being used in this particular packet.

The remaining nine bytes of a minimum header include things such as a checksum (which applies to the header only), a total message length (which applies to the IP message itself and does not include the Ethernet overhead) and other control functions (which are usually not used).

Since IP systems are well-connected, many point-to-point applications are being moved from dedicated lines to using IP as a universal transport. The protocol field of IP makes this quite simple. Note that protocol numbers in IP are also assigned by the NIC, as are most values in header control fields.

I was once shown an Ethernet analyzer which did not do a very good job of capturing packets based on IP addresses (or any protocol-specific address). The manufacturer had some trouble understanding that once a packet passes through a router it loses its original Ethernet address but retains its protocol address.

In my case, seven Ethernet addresses represent several thousand IP addresses, as three of those seven are routers that concentrate traffic from many others. And that’s only machines inside North Carolina. Two more Ethernet addresses (the external routers) represent the rest of the whole Internet. I could not possibly pick out an exchange between two machines based on the Ethernet addresses alone.

Obviously, there are shortcomings to IP, but there aren’t many. In addition, most of these are implementation issues and not bad design in the protocol. The biggest operational problem is with poorly done systems. IP has so many features for robustness that for local-area work it’s tempting to bypass many of them. This is particularly true for PCs, which don’t have enough cycles to spare anyway. Fortunately, as more and more manufacturers enter the field, the bad versions are retired as obsolete or are fixed.

Even though there are 16,000 class B addresses and millions of class C addresses, networks tend to be sparsely populated. Thus there is a problem with exhausting network numbers even though almost no networks are at a point where all possible addresses in it are assigned. This is the tradeoff for guaranteeing internetworking. Even class C addresses are going fast, as people tend to ask for several at a time.

IP has a broadcast address, and system designers tend not to be very careful about what they broadcast. There have now been established class D and class E addresses which are multicast addresses. Obviously, in Ethernets there is an inherent multicast mechanism, but IP should not be thought of only in local-area terms.

It has been difficult to establish multicast protocols over IP as a result. For example, newsfeeds could be multicast similarly to how radio does it. There you have prearranged times when the news is sent, and interested parties take it. In IP, a separate newsfeed has to be sent to each interested party.
There is a problem with routing information updates in the system of routers. Consider that over 3000 networks are presently connected to the Internet. If you only enumerate each network's number with one more byte to indicate whether it is available, that is over 15,000 bytes of information. At 56 kbps, this takes over two seconds of transmission, which is rather wasteful.

The problem is being handled in two ways. First, line speeds are getting higher, so the transmission time is reduced and the proportion wasted is smaller. Second, update systems are being modified so that nothing is sent unless some change actually happens. This greatly reduces the amount of data to be sent.

A somewhat more serious problem is known as the ARP-cache problem. Recall that in a local area network everybody is available through one port. It then becomes necessary to have a lookup table referencing IP addresses to Ethernet addresses. This is because the Ethernet system switches using Ethernet addresses, even if the application uses IP addresses.

The mechanism that provides this cross reference is called ARP, the Address Resolution Protocol. The initial exchange of ARP is a broadcast, asking the question "does anybody on this network have the IP address so and so?" If that machine does exist, it will send a reply directly to the asking machine.

Some designers thought it desirable to retain knowledge of this exchange even if the original requirement is finished. They reasoned that on a local area network, machines access each other quite often and there really is no reason to ask every time, especially since broadcasts should be used sparingly.

Unfortunately, the design drops address only if it has not been used for any reason during a fairly long period of time. If the destination disappeared for any reason but the source machine kept trying to reach that destination, the entry would never go away.

This is particularly painful if the destination is the external router, and there is a backup router available. Due to the ARP-cache design, the backup is essentially useless because the source keeps trying the original router which has failed for some reason.

The solution seems to be to drop an entry after so much time whether or not it has been used recently. This forces a new exchange every so often, so even if an address changes, there will only be a short outage.

All in all, IP is a very capable protocol and is still gaining popularity. Extensions to the protocol are still being done and generally do not require everyone to upgrade, showing that the original design was well done.

The Internet in the United States is operated under the auspices of the National Science Foundation. The 'backbone', that is, the set of lines connecting major areas in the country to one another, has been operating at T1 speeds for some years now and is actively moving to T3 speeds. Next time we'll look at how exactly T1 lines work.

**Conclusion**

I hope that this selection of CRC routines will expand the options in designing your next homebrew project. I doubt that this exhausts all the algorithms I got a whiff of or two more in my explorations, but following the trail is difficult in a non-University setting. Meanwhile, I follow Charles Moore's dictum—share the code.

References

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Z-System Corner

Type-3 and Type-4 Programs
Some New Applications of Type-4 Programs

By Jay Sage

Hors d’Oeuvres

Before starting on the main material for this column, I have two subjects to discuss very briefly. First, for those waiting for the CPU280 to become available, your wait will almost surely be over by the time you are reading this. Ralph Becker just became the first American with a working CPU280, and he knows where to get all the parts. Between the two of us, we will be offering CPU280 kits.

Second, I have just started using 4DOS, a command processor to replace those that come with MS-DOS and DR DOS. I am extremely impressed. [The name of the principal author of 4DOS, by the way, is Rex Conn, uncannily similar to that of the principal author of ZCPR, Rick Conn!] Like PCED, which I have used for several years and about which I have already written in TQJ, 4DOS offers almost (but still not quite) everything that Z-System does. I will be talking about it in the future, and it has already been added to the Sage Microsystems East product line (the retail price is $69, but SME will have an introductory price of $59). The manual alone is worth the money. It is written in a Z-System style and has lots of good, basic information about MS-DOS-style computers.

I got started with 4DOS because, for reasons that are still not clear, I have not been able to get PCED to work in a DESQview window under DR DOS 6. It works outside DESQview with DR DOS 6 and inside a DV window with MS-DOS 3.3 (and, I am told, MS-DOS 5). But the combination of DR DOS 6 and DESQview just won’t go. The problem will probably be solved, but I don’t have the solution yet. There are still some things that PCED offers that 4DOS does not, but the reverse is also true.

Some time we should also talk about ZSIM12, a true CP/M emulator for IBM-PC-compatible computers. ZSIM provides so complete an emulation—that I won’t go away more complete than 22NICE and Z80MU—that NZCOM runs perfectly under it. PCED, 4DOS, and ZSIM give us three ways to have Z-System-like functionality on a PC platform.

The Main Topic

In my last column, which recounted the historical development of ZCPR, I mentioned that in version 3.31 I had introduced a revolutionary concept for CP/M—programs that would be loaded and run at a fixed address other than the standard 100H. These programs were called, for reasons that will be explained a little later, type-3 programs.

In ZCPR version 3.4, with Joe Wright leading the way, he and I introduced a further extension of this concept, the type-4 program. Joe envisaged this kind of program as loading itself automatically as high in memory as it could possibly run given the current system configuration at load time. However, by moving the special loader code out of the command processor (CCP) and into the program header, I not only saved code space in the CCP but also made the type-4 loader concept more general.

Until recently, however, no one had developed any type-4 loaders other than the one, released with ZCPR34, that performed the task Joe wanted to achieve. This column will present several new examples that I hope will promote some creative thought on the part of readers.

The Type-3 Program

Programs written specifically for ZCPR version 3.0 began with special header code having the following form:

```
org 100h
jp start
db 'Z3ENV'
db prottype
dw envaddr
start:
```

The program begins with a jump instruction to make execution skip over the header material. Right after that comes an ASCII string, 'Z3ENV', which can be used by other programs (including the command processor) to determine that this is a Z-specific program.

Next comes a byte that contains a program-type value. A value of 1 (binary, not ASCII) indicates that the program references an external environment module (ENV), which is a virtually universal component of a ZCPR3 system. This module contains information about how the ZCPR3 system is configured, such as module addresses and sizes.

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### Listing 1

```assembly
com: ; Process transient command
ld hl,tmpa ; Set default execution/load address
ld a,3 ; Dynamically load type-3 and above ENVs
call mload ; Load memory with file specified
in c,rml ; Next two lines added by Bruce Morgan
jr nc,comrml ; If not special Type 4, carry is clear
ld (execadr),hl ; Reserve load address, special Type 4 b/n
comrml:
.... ; Some code omitted here

; Copy command tail into TBUFF

call progl:
tails:
equ $41 ; Pointer for in-the-code modification
ld hl,0 ; Address of first character of
; command tail
ld de,tbbuf ; Point to TBUFF
push de ; Save pointer
ld bc,7f00h ; C60 (byte counter) and B=7F (max bytes)
tail:
.... ; Loop to copy tail
.... ; Some code omitted here

; Run loaded transient program

call defltdma ; Set DMA to 0080h standard value

; Perform automatic installation of 23 programs (unless
; type-2 environment)
```

### Listing 2

```assembly
ld (envtype),a ; Set up in-the-code modification below
ld (execadr),hl ; Set up execution/load address
call defltdma ; Set DMA address to 800h for file searches
.... ; Code for searching path omitted
.... ; Code for extended command
.... ; processing omitted

call opencmd ; Open file for input
.... ; Some code omitted here

call readcmd ; Read first record into default
; DMA address
jr nz,mload5 ; Branch if zero-length file
ld (cmdfcb+32),a ; Set file current record back to zero
ld hl,tbufh ; Pointer to start of code
call scheck
ld hl,(execadr) ; Get initial loading address
jr ns,mload4 ; If not 33 file, branch

; The following test is modified by earlier code. For normal
; COM file loading, a 3 is inserted for the minimum
; environment type for dynamic load address determination.
; For the QB command, where the user-specified address
; should be used, a value of OFFH is put in here so that
; carry flag will always be set.

envtype equ $41 ; Pointer for in-the-code modification
cp 3 ; See if no higher than a type-2
jr c,mload4 ; If lower than type 3 (or 255), branch
ld hl,(tbufh+11) ; Load address in case type-3
jr z,mload3b ; Type 3 command, do that

; As not 1, 2 or 3, assume Type 4 command
.... ; Some code omitted

; Type 4 header does its own calculations
ld hl,cmdfcb+32 ; Make HL point to record count byte
```
A PROGTYPE value of 2 (though I don't believe I ever actually saw it used) would indicate that the ENV data block was included (as an extended header) within the program code itself. This was a vestige from ZCPR2, with which Z programs had to have the environment information configured into the program.

With ZCPR331 introduced programs with a PROGTYPE value of 3 and a slightly extended header. Its form became the following:

```
org entry
jp start ; Programs start at ANY ADDRESS
        ; Jump past the header
db 'I3ENV' ; ID to identify a Z program
db 3      ; Type of Z program
dw envaddr ; Address of ENV module
dw entry  ; Load address for program
start:    ; remainder of program code
```

There is an extra word (i.e., two bytes) following the program-type byte. This word contains the address to which the program was assembled/linked and to which the ZCPR3 command processor was to load and execute the program.

As a quick aside, there was one thing that I didn't think of when I created this kind of program. If one tried to run it under either CP/M or ZCPR version 3.0, the command processor would not know about type-3 programs. It would load the type-3 program to the standard 100H address and then start to run it. The "JP START" instruction would still go to the place where it would have gone had the program been loaded to the specified ENTRY address. Since the code was not in fact loaded there, very strange—and almost always unpleasant—behavior would result.

Others later developed a fix for this. The "JP START" was replaced by "JR START", a relative jump. This would work no matter where the program was loaded. Special lead-in code at the START address would determine the actual load address and compare it to the proper type-3 load address stored in the header. If the addresses did not match, an error message would be displayed, and execution would terminate before any damage was done. This entire piece of protection code must, of course, use only location-independent instructions.

The Type-4 Program

The loading of a type-3 program presents no special challenges to the command processor. It simply copies the contents of the program's COM file into memory starting at the specified address rather than the standard address of 100H. A type-4 program, on the other hand, is going to be loaded and run at different addresses at different times; the COM file cannot, therefore, contain the actual code as it is to be run.

The problem of storing code in a form that permits it to run at arbitrary addresses had been solved long ago using what is called a PRL file, where PRL stands for "Page ReLocatable". This file comprises two major parts. The first part is the actual code assembled for a starting address of 100H. This is followed by what is called a bitmap. The bitmap tells which bytes in the 100H-address code have to be adjusted in order for the code to run at another address. Each byte in the bitmap has 8 bits and can cover 8 bytes of the program code. Thus, the bitmap is one-eighth the length of the code.

A PRL file has one other component, a one-page (= two records = 256 bytes) header in front of the two parts I described above. This header is almost completely empty (i.e., filled with zeros). The only data it contains is in bytes 1 and 2 (where the bytes are numbered starting with 0). There it stores the length of the code portion of the file. This value allows whatever routine carries out the relocation to determine where the code ends and the bitmap begins.

Another quick aside. The first byte, byte 0, is filled with a "RST 0" instruction, a one-byte opcode that performs a call to address 0000H. This initiates a warmboot. Thus, if an attempt is made to execute a type-4 program under any version of the command processor other than ZCPR34 or later, the program will simply reboot. This is not as nice as displaying an error message, but it is a lot better than trying to execute a raw type-4 file! To allow this same protection to be used with type-3 programs, some extra code was added to ZCPR34 to replace a leading "RST 0" instruction with a "JP" opcode at load time.

Now back to the matter of how ZCPR34 handles type-4 programs. ZCPR34 needs to accomplish two tasks in connection with loading a type-4 program. First, it has to determine the address to which the code should be loaded. Second, it has to perform the address relocation to permit it to run at that address. To do this, it makes use of code in the CCP together with code placed into the available space in the PRL header. How it does this is really quite tricky, and I doubt that anyone other than Joe Wright could have come up with the code to do it!

Since we don't want the type-4 program to interfere with any user code currently residing in memory, we have a problem figuring out where to execute the loader code. Had it been placed entirely in the command processor, there would have been no problem, but a lot of valuable code space would have been taken up.

```
Listing 3
; Program: TYP4LDR.Z80
; Authors: Joe Wright, Bridger Mitchell, Jay Sage
; Contributors: Bruce Morgen

;=================================================================================
; Record 0 Routine - Load Address Calculator
org 100h ; ORG HEX file at 100h
phasetbuff ; Program actually runs at 80h
recl: rst 0 ; Anything but ZCPR34 will warmboot
length: ds 2 ; Length of the code module (SPR or PRL)
db 'I3ENV' ; Z program ID
        ; Type of program
db 4      ; A Type 4 program
start:    ; CCP calls the code at this point
        ; stack and register manipulations
        ; calculation of room needed for program, including bitmap
        ; adjustment for flag required
        ; choose larger of load size and memory size as space required
                ; calculate load address as if NSX defines top of TPA
                ; calculate load address as if CCP defines top of TPA
                ; keep the lower of those two values
                ; optionally force page alignment
                ; set up some data on stack for second part of loader
                ; return to CCP with load address in HL

;=================================================================================
; Record 1 Routine - Code Relocator
phasetbuff ; This code also runs at 80H
        ; stack and register manipulations
        ; make sure header of loaded code has type 4 set
        ; perform relocation of the code
        ; return to CCP
.dephase ; Good Housekeeping
        ; End of TYP4LDR.Z80 Relocator
```

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Listing 4

; Now calculate possible load address assuming CP defines top of TPA

    pop  hl ; CCP address (+4)
    call  adjaddr ; Calculate address and keep lowest

; HERE IS THE NEW CODE!

; Finally, calculate the possible load address using the value
; specified in the program header. If this value is lower than
; the highest possible address, then it will be used. Otherwise,
; the highest possible value will be used.

    ld  de,(ldaddr) ; Get specified load address
    xor  a ; Make sure carry flag is clear
    call  adjaddr ; Keep lower address

; Get ready to return to CCP

    loadaddr equ  $+1

    ld  de,-1 ; Get final value of load address
    if align
        ld  e,a ; Force page alignment (A=0)
    endif

    pop  hl ; Get file size ;(+2)
    push  de ; Pass load address to record-1 routine
             ;(+4)
    push  de ; Hold a copy on the stack for now
             ;(+6)

    ld  hl,thuff ; Set for for CCP to call second record
    ex  (sp),hl ; load address to HL, thuff to top of stack
    if test
        rst  30h ; D07 breakpoint
    endif

    load: jp  0 ; Return to CCP (hot-patched above)
               ; Command processor loads record 1 to
               ; ..thuff and records 2+ to load
               ; ..addresses, then 'returns' to thuff
               ; ..to finish loading

; This subroutine takes an address for the top of TPA in HL and
; the amount of memory required in DE and computes the proper
; load address. It then compares it to the value stored at
; LOADADDR and replaces the value there if the new value is lower.

    adjaddr:
        xor  a ; Clear carry flag
        sbc  hl,de ; Compute new possible load address
        ex  de,hl ; ..and put it in DE
        adjaddr1: ; THIS IS A NEW LABEL!

    ld  hl,(loadaddr) ; Get previously computed load address
    sbc  hl,de ; Compare HL and DE
    ret  c ; HL is lower, nothing to do
    ld  (loadaddr),de ; New lower address
    ret

There is one area in memory that is available as a scratch buffer:
the second half of the base page from 0080H to 00FFH. This area
is used to store the command tail when a program is run, and it
is the default buffer used by many programs for transferring data
to and from disk. We will now describe in very general terms how
the ZCPR34 command processor uses this space.

It begins by loading the first record of the header (record 0) into
the buffer. After placing some important information into regis-
ters in the CPU (the microprocessor Central Processing Unit), the
CCP calls the code there (but not at the very beginning, as we will
see later). This code computes the address to which the program
should be loaded and puts it into the HL register pair. It then
pushes the address of the default buffer onto the stack and jumps
back to the command processor.

The command processor now loads the second record of the
PRL header file (record 1) into the default buffer and then
continues with its standard loading code, just as if it were dealing
with a type-1 program (in which case HL would have been set to
100H) or a type-3 program (in which case HL would have been set
to the load address stored in the type-3 header). As a result, all of
the file from record 2 to the end, including both the code and
the bitmap, is loaded into memory at the address specified by the first
PRL header routine.

Once the CCP loader subroutine (MLOAD) has completed its
work, it executes a RET instruction. This would normally return
to the CCP code after the call to MLOAD. At that point the CCP
transfers execution to the beginning of the program that was just
loaded. In the case of a type-4 program, however, the stack has had
the address of the default buffer, 80H, pushed onto it, and so
execution resumes instead with the second routine from the PRL
header. This code carries out the relocation of the program code
so that it can be executed at the address to which it has been
loaded. When that operation is finished, a RET instruction finally
returns control to the CCP after the "CALL MLOAD" instruction.
The type-4 program is now executed.

For those who may be interested, I have included some
fragments from the ZCPR34 source code in Listings 1 and 2.

Listing 1 contains the code that ZCPR34 calls to load transient
programs. It starts with a call to MLOAD after setting the HL
register pair to the default load address of 100H.

MLOAD is an incredibly hard-working subroutine, excerpts
of which are shown in Listing 2. If you look at the code, you will
see how it loads the first record into the default buffer and then
systematically determines what type program it is. It first identi-
ifies standard CP/M programs and branches to the file-loading
code with HL set to 100H. Next it identifies Z programs of types
less than 3 and again branches to the code with HL set to 100H.

Then, if the program is type 3, it fetches the load address from
the header at an offset of 11 bytes, puts that value into HL, and
proceeds with the loading code. If things have not been taken care
of by now, the code assumes that it has a type-4 program. If you
look at the code carefully, you will see that there is an additional
complexity that I have not described (and will not). Suffice it to
to say that it requires a good bit of juggling of the records loaded into
the default buffer.

You can see where the ZCPR34 code makes a call to TBUFF+9.
This starts the execution of the code in the first record of the type-
4 header. On return from that code, the second record is read in,
and the load address in HL is stored as the execution address. The
rest of the program file is loaded just as other programs are (but
starting with record 2 instead of record 0), and then the code jumps
to the LOGDE routine. When that routine is finished, its RET
instruction is what starts execution of the second record of the
type-4 loader.

The Standard Type-4 Header

The latest version of the standard type-4 header used in all
type-4 programs distributed to date is available in the file
T4LDR11.Z80. Listing 3 contains a pseudo-code version of the
source code.

The first record begins with the standard ID header for a Z
program. That is followed by code to calculate the proper load
address taking into account a considerable number of different
possibilities (for example, various ways to determine the space needed by the program and the top of available memory). All this functionality has to be accomplished in only 119 bytes. Joe Wright and others who helped him (including Bruce Morgen) have had to be very careful and clever in the coding.

All I will say additionally about the second record is that it uses some clever relocation routines developed by Bridger Mitchell. I have not looked to be sure, but I believe these routines were described in one of Bridger’s columns here in TCAJ a while back.

A Type-3-Like Type-4 Loader

For my first example of a new type-4 loader, I am going to show you one that makes a type-4 program act like a type-3 program, but with the fixed load address determined not at assembly time but simply by patching in the address. In this way, it would be possible to distribute a program that acts like a type-3 program but where the user could choose his/her own load address without having to know anything about assembling and linking code.

Why would one ever want to use a type-3 program instead of the standard type-4 that automatically loads itself as high as possible? Well, I can think of one situation for sure. Suppose one wants to use the JUMP command to rerun it? It is true that many type-4 programs display a signon message that reports the actual load address, and this address could then be used with the JUMP command. However, this requires that one pay careful attention to the signon message, and it rules out using a JUMP command in an alias, where the address has to be fixed and known in advance.

I will be distributing this loader in the file T4T3LDR1.Z80. Its header is modified to the following form:

```
ret 0 ; Warmup if executed
dw length ; Code length
db '3IENV' ; ID to identify a 3 program
db 4 ; Type-4 program
dw envaddr ; Address of ENV module ; Entry point of loader code jr start ; Jump past extra jr header db 'ADDR=' ; String to identify patch point dw loadaddr ; Patch fixed load address here start: T4LDRR1.Z80 code
```

There is a place for the user to patch in a fixed load address to be used. This location is made easy to find by the ASCII string in front of it.

```
Listing 5
; Program: T4PLDR.R280
; Authors: Jay Sage
; Date: December 17, 1988

This type-4 loader prompts the user for the desired load address. A single digit between 0 and 9 is entered. If 0, the program is loaded to 100H. For any other digit, the load address is that digit followed by "00H". Thus '4' causes the program to load at 400H. There is no checking to make sure that the specified address is safe; thus, the system can be crashed if too high a load address is specified.

vers equ 10
	buff equ 80h ; Always executes from default buffer

; Macros for printing space free have been omitted here, and their ; invocations later in the code have been stripped out. The ; entire second record has also been omitted, since it is the same ; as the standard one in T4LDR.L280.

; Record 0 Routine -- Load Address Calculator
;
; On entry, we have:
;   HL = 3IENV, environment descriptor address
;   DE = ENTRY, address of beginning of CCP
;   BC = PROGSIZE, program size from program header
;   in record 2
;   A = FULLGET flag
;
org 100h ; ORG HEX file at 100h .phase buff ; Program actually runs at 80h rec0: ret 0 ; Only a BCPR34-compatible CCP ; ...can execute this file length: da 2 ; Length of the code db '3IENV' db 4 ; A Type 4 program start: ex (sp),hl ; Get return address from stack ; ...and put 3IENV on the stack
```

```
ld (load+1),hl ; Set in-line jump to the return addresses
ld hl,(length); Length of this PRL/SPR code
push hl ; Save on stack for sector 1 routine ;(42)

; Now we need to get the load address.
ld (stack),sp ; Save stack pointer
ld sp,stack ; Set up local stack pointer
ld c,9 ; BOSI string output routine
ld de,message
call 5
ld c,1 ; BOSI conin function
call 5
ld sp,(stack) ; Restore original stack pointer
ld hl,100h ; Default load address
cp '1'; See if less than '1'
jr c,resume ; If so, use default address
cp '9'+1 ; See if between '1' and '9'
jr nc,resume ; If not, use default address
sub '0' ; Convert to binary
add a,a ; Multiply by 16 (10H)
add a,a
add a,a
add a,a
ld b,a ; Use as load address
resume:
push hl ; Pass load address to record-1 routine
;jr
push hl
ld hl,buff ; Set for CCP to call second record
ex (sp),hl ; Make BCPRA4 go to buffer, and return
; ...with load address in HL
load: jp 0 ; Return to CCP (hot-patched above)
; Command processor loads record 1 to buffer
; ...and records 2+ to load address, then
; ...'returns' to buffer
message:
    db 'Digit (0-9) for load address: $'
da 2*13 ; Space for local stack
stack: da 2 ; Place to keep original stack pointer
.dephase
```
The rest of the code is the same as that in T4LDR11.Z80 except that at the very end, after the highest possible load address has been calculated, it is compared to the fixed load address specified. If the fixed address is lower than the highest allowed, then its value is put into HL. If the fixed address specified is too high, then the highest possible value is used instead. Very little additional code is required because the comparison code is already available in an existing subroutine. The new code is shown in Listing 4.

## Installing a New Type-4 Loader

Before going on to the second example of a new type-4 loader, I would like to describe how these new loaders can be installed into an existing type-4 program so that you can experiment. One of the nice things about the way type-4 programs are implemented in ZCPU34 is that you do not need source code for the program. A new loader can be installed at any time. You need only the loader code in the form of a HEX file, which you can either generate yourself from the loader source code or get from someone else who has done the assembly.

To make the HEX file, you assemble the loader source with the appropriate assembler switch on the command line. For example, with ZMAC or the SLR Z80ASM assemblers the command lines would be

```
ZMAC T4T3LDR1/H
Z80ASM T4T3LDR1/H
```

Once you have the HEX file (e.g., T4T3LDR1.HEX), you install it onto a type-4 program (let’s call it PROG.COM) using MLOAD or MYLOAD, public-domain loader utilities available through the ZSYS service or from Z-Nodes and, in the case of MLOAD, many RCPM systems. Here is the command line to make a new version of PROG.COM with the new loader:

```
MLOAD PROG.COM-PROG.COM,T4T3LDR1.HEX
```

## A More Elegant Type-3-Like Loader

Well, now we have a type-4 program that can be patched easily to load the program to any address we like. How about making life even nicer by having the loader ask us — at the time of loading—where we would like the code loaded? We can then easily load the program to different addresses each time we run it without the nuisance of having to patch it. [Here is an exercise for the reader: why can’t we use the GET/POKE/GO or GET/POKE/JUMP techniques to hot patch the address into the type-4 program (or do any hot patching at all)? Hint: will the GO or JUMP commands work right?]

This second new loader contains none of the code for calculating the load address that T4LDR11 has. Instead, it puts up a prompt and waits for the user to press a digit key between ‘1’ and ‘9’. If an illegal key is pressed, the code is loaded to address 100H. For legal digits, the value is multiplied by 1000H, and that value

```
; Report load address to user.
ld (stack),sp ; Save stack pointer
ld sp,stack ; Set up local stack pointer
ld c,9 ; BDOS string output routine
ld de,message ; Call bdos
ld sp,(stack) ; Restore original stack pointer
ld hl,(ldaddr) ; Get load address from header
push hl ; Pass load address to record-1 routine ;(+4)
push hl ; Fill another stack entry ;(+6)
ld hl,tbuff ; Set for for CCP to call second record
ex (sp),hl ; Make ZCPU34 go to tbuff, and return with...
;load address in HL
load: jp 0 ; Return to CCP (hot-patched above)
; Command processor loads record 1 to...
;...tbuff and records 2+ to load ...
;...address, then ‘returns’ to tbuff
```

```
; Record 0 Routine -- Load Address Calculator
org 100h ; ORG HEX file at 100h
phase tbuff ; Program actually runs at 80h
rec0: ret 0 ; Only a ZCPU34-compatible CCP...
;...can execute this file
length: ds 2 ; Length of the code
db '33EH' ; 'E3EH'
db 4 ; A Type 4 program
jr start ; Jump past load address
```

```
; Record 1 Routine -- Code Relocator
```

```
; Standard code from T4LDR11.Z80 omitted. We pick up with...
; the new code right after the relocation is complete and...
; interrupts are reenabled.
ld hl,0 ; Force warm boot
scf ; Set carry flag so HL will be used
ret ; Return to MLOAD3’s caller in ZCPU34
```

```
; End of T4WBLDR.280 Relocator
```
is used as the load address. No checking is performed to ensure that the code can safely be loaded to the requested address. The user must accept that responsibility. It would be nice if the code could check the address, but the basic code barely fits as it is in the space allowed.

The code for the second record (the relocation routine) is the same as in T4LDR1. The new code for the first record is shown in Listing 5. You will notice that an internal stack is provided. When I tested this code, I found that the CCP stack could not hold everything that XBIOS pushed onto the stack during the BDOS function calls. As I recall, Howard Goldstein did not have this problem when he tested the code on a different computer. Including the local stack in the code seemed to be prudent.

**ZCPR34 Release E**

Howard Goldstein recently finished implementing a number of minor bug fixes in the ZCPR34D code, which had been the standard production version for some time. At the same time, he also added a new feature invented by Bruce Morgen. The result is version 3.4E.

I will not go into Bruce’s reasons for introducing this innovation, partly because this column is already long enough and partly because I don’t really remember right now exactly what all of his reasons were. However, my final example will make use of this new feature. Please bear in mind, however, that unless you have ZCPR version 3.4E (which few people have), this final type-4 loader will not work. If anyone owns a copy of ZCPR34 wants to experiment with this new feature, please contact me about getting the updated version.

In the previous versions of ZCPR34, as we described above, the first record in the type-4 loader calculates the load address and passes it back to the command processor. The command processor then loads the code to that address, adjusts any addresses in the code (that’s the relocation), and then—here is the crucial point—executes the code at that load address. Bruce’s change allows the execution address to be determined independently of the load address.

Here is the essence of Bruce’s observation. The second loader routine normally just performs the code relocation and then returns to the command processor, which proceeds to execute the code. However, some interesting possibilities can be introduced by allowing this second routine to decide that the execution address should be changed from the load address that was calculated by the first loader routine. Bruce observed that the carry flag happened to have been left clear (reset) by all existing type-4 loaders and by the internal CCP code used to load all other types of programs. Bruce added a tiny bit of code to ZCPR34 (you can see it near the beginning of Listing 3) to have it check the carry flag. If the flag is set, then the contents of the HL register pair are copied into the execution address stored in the CCP.

Our final example of a new loader, T4WBLDR1, is a further variation suggested by TCJ editor/publisher Chris McEwen. When I showed him T4T3LDR, he noted that it could be used to install code as a kind of TSR (this is an MS-DOS term for Terminate-and-Stay-Resident, code that loads itself and remains in place for further use) in the NZCOM user buffer area. T4WBLDR1 can be used that way.

The one essential change is a small addition to the code in the second header record to load the HL register pair with the address 0000H and set the carry flag before returning. This causes ZCPR34 to perform a warmboot (whose entry point is at address zero) instead of executing the newly loaded and relocated type-4 program code. The code is now available for execution by the JUMP command at a later time.

Since the NZCOM user buffer area is above the CCP entry address, the usual address verification code in the first record of the header in T4T3LDR would refuse to use the specified address. To get around that, we simply remove all of that code and accept the user-specified address without questioning. Listing 6 shows the code for T4WBLDR1.Z80.

**Conclusion**

The implementation of the type-4 program follows the tradition of modularity and flexibility that is the hallmark of the Z-System. Because of those two characteristics, there are always more ways to use any Z-System facility than its authors envisioned when they created it, and this allows for and encourages a steady stream of interesting new developments. I hope my examples here will inspire more innovation in the area of type-4 programs.

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of contents, and then select one section and home in on it. If that section meets their muster it is a buy, if not, sale lost.

**FORTH DAY**

That overly thick manual was up for sale at the November FORTH DAY in the San Francisco bay meeting. I saw lots of people look at it and put it back down quickly. Time is far too short for most people these days. Buying any new project that requires tons of reading to master it, just doesn’t cut it. Don’t get me wrong, if I need to use the product, I will wade through all the pages to find out what I need. However don’t ask me to be happy about it.

Well I would say being happy about FORTH was not on the agenda at FORTH Day. It seems people are still concerned about where FORTH is going, if it is going anywhere at all. There were some good speakers and a few good products for sale. About the only real news item was SUN’s and Bradley’s pushing for a standard FORTH ROM BASED DEBUGGER. As some of you know the SUN’s SPARC based computers boot from a FORTH based ROM. Also the expansion cards all have FORTH based routines that load their drivers.

Well SUN is so happy with this operation that they are pushing to get a standard word set and operational structure established. It sounded like it will stay rather closely to what the SUNS’ ROM does now, but soon all manufacturers may start changing their ROM BIOS’S to FORTH. From a maintenance stand point I can not support it strong enough. I hate how each vendors debugger works differently as well as always having just too few options to solve my problem.

On FORTH itself, things look rather flat. Some more chips are scheduled to come out from Chuck Moore. These will be 200 MHz machines running a form of FORTH. Chuck designs the chips with his own FORTH based CAD system. He does this because none of the chip making CAD systems on the market can do what his does. It also means he can add features as he sees a need for them. Will these new machines make any big inroads, I doubt it as well as Chuck doubts it. Seems nobody believes he can make a 200

*See Computer Corner, page 21*
Back Again?

Well, curses on you all! Well not really. I wrote the first article just to let off some steam. Unfortunately someone must of liked it because I was asked to write some more. In some ways I was kind of hoping someone would like it, but I had hoped that enough people would say thumbs down so I could spend my afternoons smoking chips instead of typing at my desk. So after a few hours of sniffing solder fumes here I am with Hardware Heaven number two.

Now, first let me say that this was not my pick for a title for this column. My first choice I rejected myself to avoid a liable suit from another column. My second choice, TCG turned down probably because they wanted to avoid a liable suit. So here we are with Hardware Heaven. Or is it hell? Some days I wonder. Anyway I'm on my way to Trenton for the big computer festival, or "How to spend $600 on air fare to drink beer eat pizza and talk weird stuff with other Hackers." Hope to meet some of you there.

Trade Mags

As for the column I thought I should dive right in and scare the Editor by talking about other magazines. Not the one sold by the pound, or the PC mags that live in their own little biospheres but the "trade" magazines. Trade magazines are little corners of guru worship all their own. Now what do I mean by a trade magazine? Well those who know what I'm talking about know that TCG has nothing to fear from these guys. A trade mag is basically a glossy professional magazine full of expensive looking ads aimed at ivory tower engineers and R&D managers. The ads are only for the latest greatest toy, no doubt better than last week's toy. The articles are much the same since they are usually written by tech writers from the same companies that placed the ads. These mags are also very focused, aiming for a specific audience and therefore they are also very narrow minded. For example, you might find one called Component Mounting dedicated to "pick & place" machines capable of auto mounting components on your PCB. Now don't laugh, that's how focused they can be. So why would anyone be interested in them? Well they are a tool. (You know, like a hammer, saw, IBM-PC, etcetera). Like any tool, what they can do for you depends on how well you use them. I skim read every one that passes my desk. I use those cute little markers to flag any article or ad that caught my interest. I use them as a learning tool to keep me up to date with trends in the electronics industry. Sometimes I find new neat little chips that are actually useful (Dallas' DS1233). Then I file them away.

Now why would I pay good money to see the latest available 32-bit embedded controllers to ever add A1 to a soda ma-

chine? [Soda machines use 68HC11 'Ed] Answer: I don't. The ones I read are free. The only catch is that you are "qualified" to be a free subscriber, otherwise they want a few hundred a year. So what is a "qualified" subscriber? Someone that can fill in the form with the correct answers to the questions. These magazines survive on the high fees they charge to advertisers. They can do this because they show the advertisers that their readers are exactly the kind of people the advertiser is trying to reach. If you know what that is and fill out the form accordingly then they will add you to their list. As before you don't lie, but you do answer with what they want to hear.

Now where do you find such mags? Well the public library is a start but not likely a successful one. Try the library of your local electronics college or university. Try a friend who works in the electronics trade. Our library at work has over 50 titles available. Once you find a few, photocopy or tear out (without permission) the subscription card, fill it out, and send it in. The worst that will happen is that you never get a reply, but with luck you can add several pounds a month to the local letter carrier's bag.

Dallas Semiconductor DS1233

Well here's my chip of the month. (Now before you write to the editor, yes I know that TCG is every second month, I actually pick a chip each month but only write about every second one). It should be pointed out that I do not work for Dallas Semiconductor, they just happen to make some of my favorite chips. The DS1233 is known as the EconoReset. Its features are listed on the data sheet as:

- Automatically restarts the microprocessor after power failure
- Monitors push-button for external override
- Internal circuitry debounces push-button switch
- Maintains reset for 350μS after Vcc returns to an in-tolerance condition or push-button released
- Accurate 10% or 15% microprocessor powersupply monitoring
- Reduces need for discrete components
- Precision temperature-compensated voltage reference and voltage sensor
- Low-cost TO-92 package
- Internal 5K ohm pull-up resistor

Paul Chidley is a senior technologist at NowAte, an Alberta based cellular phone company. He is a nophyle ZCPR user, but has been active in homebrewed hardware and software design for many years, primarily in the Ohio Scientific and 6502/816 area. Paul can be reached on GEnie (email address: P.CHIDLEY), by regular mail at 162 Hunterhorn Drive NE, Calgary, Alberta, Canada T2K 6H5, or by telephone at (403) 274-8891 during reasonable MST hours.
In other words this is the equivalent of your standard reset circuit. The Yasbec has such a circuit. An RC to provide the power-on delay and switch debounce. The switch is in parallel to the cap, this signal is fed to a HCl4 schmitt trigger inverter. This provides a nice clean logic signal rather than the RC curve but it is the wrong polarity so a second inverter is needed. This circuit performs fine unless the power is cycled faster than the cap can discharge so a diode is needed to discharge the cap at power off. Purists would also say the series resistor is needed to limit the discharge current through the diode. Our simple little reset circuit now has seven parts and still only does half of what the DS1233 does. So what does this neat little part look like? A 84pin PLCC? A 16pin dip? Sorry, it only has three leads and comes packaged in your standard TO-92 (like a transistor) or SOT-223 surface mount packages.

For the TO-92 package:

- Pin 1 — GROUND
- Pin 2 — RESET
- Pin 3 — Vcc

A normally open optional reset button and a capacitor are connected between _RESET and GROUND, the _RESET also going to your microprocessors reset input. That’s it. You now have all those features listed above on your reset line. So why didn’t I use one on the Yasbec? I wish I had but it wasn’t out back then. So next time your circuit needs a reset reach for a DS1233. Contact your local Dallas Semiconductor dealer or rep for a data sheet.

New News

Speaking of new chips, a manufacturer of PC chips has announced an XT in a chip. Not a new processor but an XT. Complete with CGA, bus interface, floppy interface, and such. Why would anyone want an XT/PC in a chip? Well if you’re writing code on a PC for an embedded controller why not make that embedded controller a PC. So if the idea takes off, your next ATM transaction could be handled by a XT running MeSeyDOS. Scary stuff.

References

PADS Software, Inc.
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MHz machine. As us Forth people know, they said the same things about the Novix and RTX 2000.

Allen Freeman gave the meeting commentary at the end of the day. Chuck gave his fireside chat at dinner and was rather interesting as always. Allen’s talk focused mostly on what or how we might change the direction of Forth. The most important point he made was how Forth lacked integration with existing source and libraries of code. As we all know C has taken over for the most part. The why of that is the large and included C libraries. When someone buys Forth they do not get any libraries. However what they do get is usually all the source code for the Forth and as such no need for the libraries.

For new users buying into Forth however, it seems like they are not getting as much as if they bought one of the new C compilers with it’s many megabytes of libraries. If you want to talk about manuals that are over an inch thick, talk C. Where I think this issue really becomes important is accessing new cards and devices. Allen rightly pointed out how most hardware vendors are giving free C code or libraries with their products. If you want to hook Forth into the new product you will have to code it all yourself. In some cases the code is a linkable module without any source to translate to Forth.

What the vendors of Forth need to do is make means of linking in C object modules to their code. It seems to me that might open up applications in Windows and embedded systems that have been going to C. The libraries and linking to object modules are two items Forth people have been passing over as not needed. But are they really not needed?

In discussing this topic with friends it has been pointed out that PolyForth does support libraries. The problem then is just letting people know about it. What I really want right now is a windows based Forth. I am actually looking at using Visual Basic as a means of developing a few quick and simple windows programs. What I would rather be doing is developing them using Forth. I want a F-PC like windows based system where I could take Forth code and add the windows features. Basically what I am talking about is upgrading existing programs to work with windows.

That’s not a big request, but then it seems the vendors have not yet moved their products to windows. My question to them is what happened to the old statement that Forth is always the first
Earth-Shattering Discovery

Time magazine recently announced: "Why are men and women different? New studies show that they are born that way." Who did these new studies, The Obvious, Inc.? (See TCJ 48.)

Of a similar mindset, there are those who say (with a straight face, too) that you should not have Caller ID because the caller's right to remain anonymous is more important than your right to know who's calling. Sometimes it seems that this great mission to protect the rights of the deranged, obscene and criminal elements goes a little too far in trampling upon the rights of the would-be normal.

Anyway, if you live in an area in which Caller ID is available, there is a really simple device available from Bell Atlantic which transmits the data in RS-232 form. It costs about $50. Now this device, it seems to me, would be a natural for BBS systems. The BBS software could maintain (or just print) a log of all the callers and the time they called. Then if any irregularity should occur, the number would be noted. Another possibility is comparing the telephone number against that used by a user before. However, the user could be calling from a friend's computer or from his office. Remember, too, that Caller ID will only work for local (that is, intra-LATA) calls. However, this could change in the future.

Of course, the greatest present threat to BBSs is the RBOCs, most notably Southwestern Bell and US West, who are attempting to force BBSs to pay business line rates. In fact, they have plans afoot to impose surcharges above business rates. This is because they are already offering free BBSs as competition to their as-yet unavailable information services. Monopolies cannot compete on a level playing ground.

Where are all the APIs?

Let's say you've just invented a fantastic new computer peripheral. What makes this device really neat is the way it could be integrated into other software applications running on a personal computer. This means software—you so you have to develop an Application Programming Interface, or API, for the device and provide some software drivers for it. What do you do now?

Well, if you're like most manufacturers of such devices, like fax boards and hand scanners, you keep the APIs a deep secret. After all, aren't they part of your competitive edge? Then you provide some shlock software with the device that can't be integrated into any software applications. Eventually, you have a small market consisting of clumsy devices that are impossible to integrate.

If it was me, I'd give the APIs away. I'd try to make sure that every programmer in the country had those APIs. Just think—your device could be directly supported from WordPerfect or Microsoft Windows. This is how standards are made—because most manufacturers hold their APIs too close to their chest, the ones who dare to give them away become the standards.

As for some companies who will provide APIs (in the guise of "development toolkits") at very high prices so that only "major players" can participate in the party, remember that virtually all innovation in this industry takes place in small companies—where people design things because they want to, not because they're paid to.

Everyone who does any system integration out there is constantly running into these problems. Hey, you manufacturers out there: If you send me your APIs in machine-readable form, I'll be pleased to put them on a BBS wherever everyone can access them. Let's put them on a CD-ROM! (By the way, where's the CD-ROM API?)

Minix News

Some Minix users out there have successfully ported the Bellcore MGR graphical user interface to Minix. This means that Minix now has its own GUI and it can join the big leagues. No longer will people have to keep on asking, "But when will we get X Windows?"

A couple of caveats apply. I'm told that in 16-bit (read: standard PC Minix), the 64K code/64K data limitation is so severe that only two windows can be opened. In 32-bit (Minix 386), this limitation goes away. Presumably under ST or Amiga Minix, these limitations wouldn't apply in the first place.

Since Minix is not public domain, of course, all of these additions are distributed in "context diff" form, as I discussed before. So, first you apply the virtual console patches, then the patches to those patches; then you take the MGR files and apply patches to them, then you concoct the whole mass together. Oh, but before you get started on that, if you're running PC Minix, you have to build Minix 386 first. Set aside a week for that first.

I didn't mention, either, that there's no compatibility between the 16-bit and the 32-bit executables. You need to build all new 32-bit executables. It's especially handy to have executables to log in, list files, copy files, and so on.

This whole pyramid scheme of context diffs depends on people being able to "edit" against a standard configuration. A common problem is people considering a particular patch combinations "standard"—for example, the virtual console patches mentioned above are fairly common—but this means that people without those patches, or with some other patches, may not be able to use a given patch file.

Another word of caution here: It's very easy to get carried away and make your own one-of-a-kind operating system that's incompatible with everyone else's.

As a, I hadn't received MGR in time for this column. I'll have my experiences with it next time. I'm planning to implement
MGR on the PC-532 using an OS/2 window as a "graphics terminal". The PC-532 has an annoyingly narrow umbilical to the universe—a single 9600-baud serial channel is the only way data can get in or out. Then, due to some unknown problem, I haven’t been able to get either Zmodem or Umodem to work. What I really need is a SCSI floppy drive or controller. (It’s got to come with an API.)

Linux

Linux Torvalds of Finland has written a Unix clone, which he calls Linux, and is giving away. This OS is a pretty good clone of BSD, with 36 dependencies (such as the MMU) coded right in. Now as this column has stated before, the 36 Ethernet is a blatant rip-off copy of the 2532’s, which in turn is a simplified version of the VAX’s, so some work is underway to port Linux to the PC-532.

Linux has been causing a sensation on the Internet, for several good reasons. The main reason is, of course, it’s completely free. Linux wrote it completely for fun, on his own time. He has no objection to people giving it away or enhancing it in whatever way they see fit. And, it’s a more Unix-like design than Minix, which means that porting tools to it has proven easier (for those who have it).

Andy Tanenbaum argued recently that Linux is an "obsolete design", because it is "monolithic"; that, among OS designers, the microkernel design is ascendant. In a microkernel, the kernel does nothing but switch tasks and message traffic; memory management, file systems, et al. are outside the kernel. The most well-known microkernel is Mach. At any rate, he said that "Minix is a microkernel-based OS" but it’s "only a hobby" for him.

Of course, it’s evident that, because of Minix’s original design around the 8088 processor, Minix is a poor implementation of the microkernel concept. And I’m sure many people wish they could have hobbies as remunerative as Minix has been for Andy.

One reason that Minix is a poor implementation of the microkernel concept is that memory managers and file systems cannot be dynamically loaded and unloaded. The kernel and the file system are actually tied together by several knotty strands of code. One of my design features for Bare Metal (mentioned in TCJ 41) was separate "managers" which could be loaded to support different directory formats, such as MS-DOS, CP/M, et al.

While I agree that Linux will be difficult to port to different environments, it should be pointed out that porting Minix isn’t a piece of cake, either. Unlike a true microkernel, no part of the OS can be brought up without all the others.

What with Mach being released in AT&T-free form, MGR, and Linux all happening, one wonders whether the Free Software Foundation will ever get around to releasing their OS, which they reportedly now call "Hurd". (Presumably, a "hurd" is a group of "gnus")

More C sickness

Consider this statement (x and i are ints):

\[ x = ((i - 10000) \cdot 10); \]

The variable "i" varies between 10000 and 10020, let’s say. Since the subtraction is in parentheses, the maximum value which should be multiplied by 10 is 20, right? Well, that’s not the way C 6.00a sees it. No, Microsoft reports reports an "overflow in constant arithmetic"—as though the parentheses weren’t there. No excuse this time—this is a bug.

Put this in your unofficial Microsoft bug list. If you want to get an official Microsoft bug list, you have to pay $300 for access to a bulletin board. Personally, I think they’re a bunch of Stalinists. At least they haven’t started threatening people who reveal their bugs to the public. Yet.

Other software vendors are pretty Stalinist, too. Oracle, for example, prohibits any database benchmarks from being published, besides their own (laughable) figures. I am free to tell you Oracle is slower than molasses in January—but I can’t tell you how much slower.

That’s why you should just your Linux version of Z-system. You can pick up your phone and talk to Jay Sage. You can ask about bugs and performance all you want, and you can get honest information in the pages of TCJ. Yet another advantage of Z-system over Microsoft Windows—support!

Next time

Well, I didn’t get to the image compression/decompression stuff yet. But, looking back, I haven’t been too accurate in predicting the next column anyway.

Next time I hope to have more facts on MGR and, hopefully, Linux. If you’re interested in experimenting with these, or with other items discussed, drop me a line and we’ll see how we can fix you up.

When people ask me, “What one factor do you believe has contributed most to the growth and influence of your organization?” I don’t have to stop and think about an answer. Unquestionably it has been the emphasis laid from the very beginning upon human relationships—toward the public on the one hand, through careful service, and giving the utmost in values; toward our associates on the other hand.

—J. C. Penney
Remapping Disk Drives through the Virtual BIOS

By Roger Warren

INTRODUCTION

As a Z-Node sysop and believer in both Murphy’s Law and the concept of the self-fulfilling prophecy, I’ve resigned myself to the monthly task of performing a full backup of my system’s hard disk. This task consists largely of sitting in front of the machine for hours at a time listening to the floppy drive spin in and out (between the directory and the storage area) with occasional breaks during which fresh disks must be inserted into the drive.

During one such monthly labor of love (read paranoia), I reasoned that if I relocated the disk directory of my backup floppy to a central track location, less time (on the average) would be spent stepping to and from the directory. Simple arithmetic convinced me that I could complete my 40 Meg backup in significantly less time—by as much as an hour—even with step rates of a few milliseconds per track.

With that inspiration to motivate me, I set about designing and implementing a few simple changes to my Amprosoft BIOS that allowed me to selectively enable or disable the relocation of disk directory on individual floppies. I was quite pleased with the results. These changes were documented and released to the public several years ago.

Recently, I was asked to discuss what I had done in an article for TCJ. I was not too certain that such an article would be helpful to more than a few people—those who have their BIOS code and aren’t intimidated by the prospect of making and installing a new BIOS. However, in the same issue of TCJ that my future article was announced, Jay Sage’s column covered the NZCOM Virtual BIOS and ways of using it. I was struck with the simplicity of being able to incorporate the general scheme of my disk track remapping into a loadable module and, most importantly, one that was not machine-specific. Such an implementation would be useful to many and painless to install and use.

This article documents this NZCOM track remapping approach. There is sufficient discussion about the technique and detail in the listings to allow anyone having the wherewithal to modify his or her BIOS (if that is preferred or if NZCOM is not being used) to do so, too.

THE BOTTLENECK

Floppy disks on CP/M machines are logically partitioned into three (and sometimes four) areas:

- Reserved tracks (also called System or Boot tracks)
- Directory tracks
- Storage tracks
- Spare tracks (the ‘sometimes’ category)

These logical areas are arranged physically in the order in which they’re presented above. The System tracks are at the outer tracks of the diskette (the tracks having the lowest physical address), the Directory tracks are next, and the Storage area builds inward (toward higher numbered tracks) from the end of the directory. The spare tracks, if provided, occupy the innermost track area. They’re a hold-over from the IBM 3740 (8 inch) disk format specification used in the older CP/M machines. These tracks were set aside to be swapped in as replacements for tracks that went ‘bad’ in the storage area. I’m not aware of any CP/M implementation that ever used them. Spare tracks are not set aside by any machine I’ve run into that uses 5 1/4 inch drives.

It is the physical location of the directory tracks that is a burden on disk system performance. When writing files to disk, every time the current disk allocation block becomes full, the BDOS must read the directory, allocate another storage block, update the directory, then seek the newly allocated block. When reading a file, the directory must be referenced to locate the file’s next allocation block once the end of the current block is reached. As the disk becomes full and data for files are placed in tracks further ‘inboard’ on the disk, it’s a longer and longer trip between the storage tracks being used and the directory. Even with track-to-track step rates of a few milliseconds, the round trip is time consuming. The activity is quite noticeable if you’re listening to the disk drive!

If one were to “fake out” CP/M by swapping the directory tracks with a couple of tracks in the middle of the disk, this bottleneck would be eliminated. With the directory location swapped in this way, the directory would never be further away from the current track position than half-way across the disk. But which tracks should be swapped?

Arbitrarily choosing tracks wouldn’t be optimal for all cases. Of course, 48 TPI and 96 TPI disks have different numbers of tracks. Some BIOSes treat double sided disks as having twice the number of tracks as a single sided disk, while other BIOSes handle double sided diskettes by doubling the number of sectors per track. Clearly, the track number(s) of tracks to be swapped with the directory are system dependent.

Roger Warren is a former metallurgical engineer who has been making a living as a system software and hardware engineer since being introduced to computing in the early 70’s. He’s been in the aerospace and defense fields for a majority of that time, working primarily with embedded controls and radiation-hardened memory systems.

Roger has been active in the CP/M and ZCPR communities for several years, having developed and released several enhancements to the Ampro BIOS and, more recently, LZH compression for CP/M (CR/LZH and UNCR/LZH). He can be reached for comment on his Z-Node, “The Elephant’s Graveyard” at 619-270-3148 (PCP: CASAD).
Listing 1  BIOS label and modified vector table

```
; Beginning of Header........
start:  jp  boot    ; Cold boot
whoos:  jp  whoot
        jp  const
        jp  comin
        jp  comout
        jp  list
        jp  punch
        jp  reader
        jp  chioe+24  ; Home
        jp  swapeld   ; Seldon is performed below
        jp  swptrk    ; Settrak is performed below
        jp  chioe+33
        jp  chioe+36
        jp  chioe+39
        jp  chioe+42
        jp  listst
        jp  chioe+48
        ds  (30-17)+3 ; Room for 10 jumps
```

; Beginning of NIBIO. The header structure is absolutely
; crucial to the correct operation of NI-COM.
; DON'T CHANGE IT.

Listing 2  Data definition and SELECT DISK routine

```
; TRACK SWAPPING begins here. First, various equates, offsets, and storage definitions.
dbpctr equ 10    ; DBP ptr is 10 bytes
        ; into DPH
; DBP offsets:
  spt equ 0     ; Sectors per track
  bh  equ 2     ; Block shift factor
  ds  equ 5     ; Storage block max
  cks equ 11    ; Check vector size
  off equ 13    ; Offset
swapfl:  db 0  ; Flags whether this disk
          ; has tracks swapped
offset:  ds 2  ; Holds offset (# reserved
              ; tracks)
halfrax: ds 2  ; Holds computed half-way
          ; track
lastdrive: db 0ffh ; Holds last drive selected
; An ID string so that a support utility which wants to
; manipulate SWAPVEC can determine that the BIOS is
; installed.
  db  'SWAPVEC'
swapvec: dw 0000h ; Swap Vector LSB is drive
               ; A, MSB drive F.
; Swapping code begins with disk selection. If the drive
; being selected is the same as the last one and there has
; not been a warm boot since its last access, then the
; current swapfl, offset, halfrax, are valid.
swapeld: ld  a,(lastdrive) ; last drive selected
          cp c       ; Same as last drive?
          ld a,c     ; Move to A
          ld (lastdrive),a ; Save
jr ns,mwel ; If not zero, new drive
ld a,e      ; Same drive, test
            ; new mount
            ; Flip bits
bit 0,a     ; flag is set if
            ; old mount
swell: push af ; Save flag
            call chioe+27 ; Invoke the BIOS, get
            ; the pointer (to H/L)
        ; Check for bad disk select
        dec a      ; Was 0, becomes 0FFh
        ld (lastdrive),a ; Swap lastdrive
        pop af     ; Tidy stack
        jp swapvec ; Was bad select!
        ; Skip it!
ocisel: pop af ; Get flag from stack
          jp s,swapvec ; Zero if same drive and
                        ; old mount—just exit
          push hl    ; Save for exit
          push ix    ; Save the IX register
          xor a      ; Assume disk isn't
                      ; swapped, get a zero
          ld (swapfl),a ; and Clear the flag
; Determine whether we're swapping this disk
        ld a,(lastdrive) ; last drive
        neg         ; Make -(lastdrive)
        add a,16    ; There are 16 drives.
        ; 16-lastdrive is number
        ; of bits to shift in
        ; swapvec
        ld b,a      ; Copy to counting
        push hl     ; register
        push ix     ; Get the swap vector
        add ix,ix    ; Move bit to carry
        djns filgloc ; Continue shifting till
                      ; count done
        jp nc,exitix ; No carry, drive not
                      ; track swapped
        ; Check for fixed drive (check size will be 0 for fixed
        ; drives)
```

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A SOLUTION

If one were to divide the Storage tracks of a disk roughly in half and reverse the track numbers on the first half, the directory would be roughly at the center of the disk. Furthermore, the disk would fill up from the center outward until the outer bound of the Storage area was reached, then continue filling from the center inward until the storage limit of the disk was reached.

Although CP/M* "thinks" in terms of logical tracks which, for diskettes, originally corresponded to physical tracks, the logical-to-physical mapping is, really, up to the BIOS. The differences in how BIOSes treat dual sided diskettes, mentioned above, are examples of this BIOS-dependent mapping (and the freedom the BIOS has in track assignment).

The reversing of the track numbers of the first half of the diskette is merely a logical-to-physical mapping. There is a precedent for this: The BIOS sector translation via which CP/M allows for a logical-to-physical sector number remapping to improve disk performance. There is even a specific BIOS entry point that BDOS uses to perform the sector translation.

Since the NZCOM virtual BIOS resides between the BDOS and the system's BIOS, it can provide the two necessary portions of the track re-mapping proposed above. These portions are:

1. Determination of the track number of the center of the diskette (a system-dependent number) and,
2. Translation of track numbers for the tracks in the first half of the diskette.

When a disk is selected, the BIOS returns the BDOS a pointer to a table of information. Through this table (and tables the table points to) all of the information necessary to determine the track number of the 'center' of the selected disk is available. The NZCOM virtual BIOS can use this information to compute this track number and leave it behind for subsequent use by the NZCOM virtual BIOS track selection routine.

```
ld a,(ix+cks) ; Get low of check size
or (ix+ckx+1)   ; And the high
jr ns,nothardi  ; Not zero if this is a
                ; floppy

; Now if we got here, the guy has specified that a hard disk
; is swapped. Turn off the bit in the vector that selects
; this disk.

ld a,(lastdrive) ; last drive
neg              ; Make -(lastdrive)
add a,a,16       ; There are 16 drives.
                ; 16-lastdrive is number
                ; of bits to shift in
                ; swapvec
ld b,a           ; Copy to counting
                ; register
ld ix,(swapvec)  ; Get the swap vector
ld hl,0          ; Clear hl
scf              ; Set carry so a bit is
                ; shifted into the HL

figlc2:         ; Shift bit into HL
    adc hl,hl     ; Shift bit into HL
    add ix,ix
    djns figlc2    ; Continue shifting till
                    ; count done

; Now offending bit is in carry

ccf              ; So...reset it

; Continue shifting from IX to HL until the original bit set
; in HL pops out. This will signal completion of all bits.

figlc3:         ; Continue on
    jr c,figlc4    ; Jump if done
    add ix,ix
    jr figlc1     ; Get another bit
    jr exitix      ; And exit

figlc4:         ; Here to continue calculations for a floppy
                ; storage area
    ld (swapvec),hl ; Save new vector
    jr exitix      ; And exit

nothardi         ; Get offset low
    ld l,(ix+off) ; Get offset low
    ld h,(ix+off+1); Get offset high
    ld (offset),hl ; Save offset

; Now setup for computation of # tracks in this disk's
; storage area

ld e,(ix+apt) ; Low of sectors/track
```
When a track is selected, the NZCOM virtual BIOS can use the previously computed "center" track number to translate the track number before presenting it to the BIOS.

The NZCOM virtual BIOS must supply three other important functions:

1. It must determine whether or not track remapping is desired for a particular drive.
2. It must provide for the presence of the System tracks (they shouldn’t be remapped), and
3. It must protect against the inadvertent selection of remapping for hard disk partitions. **THE TRACK SWAPPING VIRTUAL BIOS**

While the concept the track swapping virtual BIOS is not too hard to follow, it winds up that the implementation requires more than just a handful of instructions. This stems primarily from the fact that while all of the information required to determine the number of tracks in a disk’s Storage area is available via the pointer returned by the select disk routine, the data must be massaged to yield the number(s) required to perform the swapping. There is also a fair amount of code required to determine whether swapping is enabled for a disk and to protect against inadvertent selection of remapping for hard disks.

The code, itself, is rather straightforward. The comments in the code include sufficient detail so as to make any "blow-by-blow" description here redundant. However, there are some points I’d like to stress. There is also some general information about the calculations and the BDOS/BIOS interface that isn’t presented in gory detail in the listings that should be presented here. This material will be helpful to those wishing to fine-tune the track swapping for their machines.

**Listing 1** presents some of the front matter of the virtual BIOS code and the virtual BIOS jump table as modified for the track swapping code. The changes from the "stock" virtual BIOS code are few: only the module name and jumps for the Select Disk and Select Track routines are modified. However, the listing is included for completeness’ sake.

**Listing 2** presents the track swapping Select Disk routine and related constants and variables. The Select Disk routine performs most of the work in the track swapping BIOS. It intercepts calls to the actual BIOS and determines whether swapping is enabled for the disk being selected. If so, the number of tracks in the storage area of the disk is computed and, from that, the track address of the "half-way" point on the disk. This value (HALFTRAX), the number of system tracks (OFFSET), and the swapping enabled/disabled flag (SWAPFL) are left behind for the Select Track routine.

Track swapping is enabled on an individual CP/M drive basis. A 16-bit quantity, SWAPVEC, is employed to indicate which drives have swapping enabled. The least significant bit of SWAPVEC corresponds to drive A, and the most significant to drive P. SWAPVEC is located immediately before the Select Disk code. This allows it to be located by a separate utility program, listed below, which manipulates the bits in SWAPVEC. The character string "SWAPVEC" precedes SWAPVEC in memory. The utility program checks for the presence of this string (to assure that the track swapping BIOS is loaded) before attempting to modify memory. This program has simple command line operation and can be incorporated into your STARTZCM start-up alias. Optionally, SWAPVEC can have an assembled-in default value.

I’d like to call attention to the use of NEW MOUNT flag passed to the BIOS from the BDOS at Select Disk time. When BDOS calls the BIOS’s Select Disk routine, the least significant bit of the E register is 0 if the drive hasn’t been selected since the last warm boot, and 1 if it has. This item of the BDOS/BIOS interface is not well documented in most of the CP/M manuals I’ve run across, which is why I’m calling so much attention to it here. Indeed, some manuals don’t mention it at all. It is, however, faithfully duplicated in the various BDOS replacements I’ve examined. BIOSes that permit the user to read diskettes of different formats in the same drive use this flag to determine whether the rather lengthy process of determining the format of the diskette should be performed. The virtual BIOS uses the flag to help decide whether the number of tracks on the drive needs to be determined.

To minimize the impact of the additional code in the track swapping virtual BIOS on system performance, the Select Disk routine first checks to see if the drive being selected is the same as the last one selected. If so, the disk sizing calculations need not be redone. However, if this is the first selection of this drive since a warm boot, the disk parameters could change if the disk has been swapped. Therefore, when the NEW MOUNT flag indicates that this is the first selection since a warm boot, the calculations are performed even if the drive is the same as the previously selected one.

If the BIOS Select Disk routine returns an error, the virtual BIOS’s previous drive variable (LASTDRIVE) is set to OFFH. This is done to protect against true I/O errors on otherwise valid drives. If the drive is valid but the user left the drive door open, an I/O error would occur and the disk sizing calculations would be aborted. If he then closed the door and continued the operation, the next Select Disk call would likely be for the same drive. By forcing LASTDRIVE to OFFH when an error occurs, the code

```
; (round up) This is done since the last track of disk
; may only be partially used. No need to test IX since
; >16 shifts will cause IX to be 0:
ld a,h ; high
or l ; continue test
jr n, evenmul ; Zero if was even
multiple
inc iy ; Add 1 to round up

evenmul:

; Now IX is # of tracks in storage area. Divide by 2 to get
; half-way point. First half will have reversed track #’s.
; First add 1 to make even if quotient is odd.
push iy ; Transfer...
pop hl ; Quotient to EL
inc hl ; Add 1

srl h ; Shift right
rr l ; Finish shift of H/L

; Finally, we want to FAVOR the directory track(s). Add 1
; to the computed ‘halfway’ point. However, there is need
; to decrement the computed halfway point to make the math
; to the track re-mapping now, so a +1-1 is a net change
; of 0.
ld (halftrax), hl ; Save # tracks at
; half-way point
pop iy ; “restore” IX
ld a, l ; Get swapped flag
ld (swapfl), a ; Into memory

exitix: pop ix ; Restore IX
pop hl ; Get saved DPH pointer
swapex: rxt ; Return to sender
```
assures that the disk sizing calculations will be performed for the drive if it’s the next drive selected.

To protect against inadvertently enabling of swapping for hard disk drive partitions, a separate trap for hard drives is included. Swapping tracks is possible on hard drives, but to do so on an existing drive would wreak havoc. When the code detects that the drive is performing calculations for a hard drive (signaled by the fact that the directory checksum vector size is 0), the trap code resets the enable flag in SWAPVEC for that drive. By doing so, subsequent selections of the drive will not waste time making the same discovery over and over again.

The real ‘work’ in the Select Disk routine is the calculation of the number of tracks in the diskette’s storage area. This is done by dividing the number of sectors per track into the number of sectors in the storage area of the disk. The number of sectors per track (SPT) is available in the disk parameter block (DPB). The number of sectors in the storage area is not directly available and must be computed by multiplying the number of storage blocks in the drive by the number of sectors per storage block. The number of sectors in the storage area is determined by adding 1 to the maximum storage block number in the DPB (DSM+1). The number of sectors per block is determined from the block shift count (BSH) in the DPB. BSH is power to which 2 must be raised to yield the number of sectors per block. Shifting (DSM+1) left BSH times yields the number of sectors in the storage area. By adding BSH to the loop counter of the division routine (normally 16), this shift operation is incorporated into the division. Note that the last track in the disk’s storage area may be only partially used. Code must be added to ‘round up’ the computed number of tracks if the division leaves a remainder.

Next, the “half-way point” track number for the disk is calculated. The number of tracks in the storage area is incremented by 1 and divided by 2. If the number of tracks is odd, the increment operation will assure that the extra track will be placed in the “lower” half of the disk. This will be slightly more favorable, since it will more ‘centrally’ locate the directory.

Finally, the “half-way point” is adjusted to favor the location of the directory. The directory (usually 1 to 2 tracks in size) is accessed a lot. If there are X tracks in the storage area of the disk, X-2 are actual storage (assuming 2 directory tracks). So, we add 1 to the computed half-way point. However, there is need to decrement the computed half-way point to make the math at the track re-mapping nice, so there’s a net change of 0. The reasoning behind this adjustment might be counter-intuitive, so consider this example:

For 100 storage tracks and 2 directory tracks, the half-way point is 50. By adding 1, the new half-way is 51. Tracks 50-59 are reversed, 51-99 are normal. Considering the nature of the storage area use, this means there are 49 tracks of data, 2 tracks of (centrally located) directory, the 49 more tracks of data.

Listing 3 presents the track swapping Select Track routine and related constants and variables. The Select Track routine merely adjusts the track number (if swapping is enabled for the current drive) and passes the new number on to the BIOS.

THE SUPPORT UTILITY

Listing 4 presents a support utility to manipulate SWAPVEC. The help screen in the program listing details program operation, so no additional detail will be supplied here. However, the statement that calculates the address of the “SWAPVEC” character string preceding SWAPVEC:

```c
swapvec = (* (char **) ((*(char **) 1)+25))-9;
```
can be a very obtuse line for those unfamiliar with C. An explanation is in order:

The value 1 is cast as a pointer to a character pointer. Taking what it points to [*char **] gets the contents of location 1 - the address of the BIOS warm boot location - as a character pointer. Adding 25 to the pointer yields the address of the location that holds the address of the select disk BIOS routine. By casting this value as a pointer to a character pointer and taking what it points to, we finally wind up with the address of the first instruction of the select disk routine. If the SWBIOS is installed, the select disk routine is immediately preceded by the characters ‘SWAPVEC’ and the 2 byte swap sector. Subtracting 9 from the address of the select disk routine will yield the address of the first character of the string.

<table>
<thead>
<tr>
<th>Listing 3</th>
<th>Track selection and remapping code</th>
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<tbody>
<tr>
<td>; Swapping code is completed with the track select. All of ; the important work has been done by the SELECT DISK code. ; Here, we only need to remap the track. ; ; If swapping is enabled, the track is compared to the offset ; (# reserved tracks). If the track is in the reserved area, ; nothing is done. Next, the track is compared to the value ; of ‘halftrack’, computed during the disk select. If the ; track is in that area, the track number is altered. If the ; track is higher than ‘halftrack’, it is not altered. swaptkr: ld a,(swapfl) ; get flag and 01 ; Swapping? jr s,trakok ; Jump if not push bc ; Transfer track pop hl ; ...to HL ld de,(offset) ; Get offset or a ; Clear carry... sbc hl,de ; Track less offset... jr c,trakok ; If carry, then accessing</td>
<td>; reserved area</td>
</tr>
</tbody>
</table>

; Now, track is normalized, having a value from 0...highest ; track. Subtract this from halftrack, stored above. This ; will result in an input value of 0 yielding a value of ; ‘halftrack’, 1 yielding halftrack-1, etc. A value of halftrack ; yields 0. If carry is set as a result of this operation, ; then we’re accessing the upper half, so original track was ; ok.

| | ; New track number in H/L. Add back in offset and transfer ; to B/C |

```c
swapvec = (* (char **) ((*(char **) 1)+25))-9;
```
CARE AND FEEDING OF TRACK-SWAPPED DISKS

I’ll not detail how to prepare and load NZCOM virtual BIOSes. That information is present well enough in the NZCOM manuals and does not need to be presented here. Suffice it to say that the track swapping BIOS can be made an integral part of your system, and that one can set, reset, or view the track remapping enable flags for the system drives via the utility discussed above. This utility can be run by your STARTZCM alias, so that your system can ‘load’ with track remapping enabled for selected drives.

With the track swapping virtual BIOS installed, one is free to disable and enable the feature for any floppy on the system. The following tips will help keep you out of trouble:

Track swapping has nothing to do with system’s disk formatting. However, to avoid any unforeseen problems, it’s probably better to not enable any swapping when using your system’s disk formatter or disk test. (They may not work with NZCOM installed, anyway!)

The BDOS won’t gracefully handle what it considers GAR- BAGE in the disk directory, so don’t try to turn a ‘used’ disk into a track-swapped disk without preparing it first (old data on the disk will garbage-up the track-swapped directory). To prepare the disk, merely reformat it. I’ve also included a utility in the support library (see PARTING SHOTS, below) that will perform the necessary directory area initialization.

Track swapping selected on a CP/M logical drive basis - not on a physical drive basis. If your system supports drive swapping or reassignment, be aware of that fact. If your system has the ability to read ‘foreign format’ disks, track remapping shouldn’t be enabled for the drive used for foreign format disks.

FINE-TUNING FOR SPECIFIC SYSTEMS

The track remapping scheme I chose is probably the most simple-minded one, but it is very good choice for my system and purposes. A variety of remapping schemes can exist. The only real requirement is that there be a one-to-one mapping of logical and physical track. Some schemes may be better than others for specific machines and/or specific applications. Some may be worse.

Recently, Jay Sage asked why I hadn’t mapped things so that the directory was in the center of the drive with even numbered tracks mapped ‘inward’ from the center and odd numbered tracks mapped outward. With that kind of scheme, data tracks would be closer to the directory as the disk filled up, giving an even better performance enhancement (my mapping scheme only improves performance on disks that are more than half full.) Frankly, this hadn’t occurred to me. It seemed like a wonderful idea, and I quickly tried it.

See Virtual BIOS, page 32
The Bumbling Mathematician—Part 1

Big Numbers

By Frank C. Sergeant

I have an urge to write about math. When I use the word “mathematician,” I use it very loosely: I want to do big math things with small computer resources. Since Forth is my favorite language, I want to use Forth, particularly my Pygmy Forth, for the examples. Pygmy is available for MS-DOS, but not yet for CP/M. So, the first thing I want to do, which I absolutely cannot do now, is to prepare a version of Pygmy for you that runs under CP/M. If I could do that first, more of you could run the examples I wish to present. However, perhaps, if I present the code and explanations clearly enough, even if you don’t have access to Pygmy, you will be able to use these ideas in assembly language or whatever other language you prefer. Unfortunately, I am not going to be able to present code that is as pretty as I’d like.

Why Big Numbers?

By big numbers I mean numbers with arbitrarily high precision. Would like to do your calculations with 50 digits to the left of the decimal point and 400 digits to the right of the decimal point? Well, this big number approach will let you. Why would you want to do this? I don’t know. Because it is possible? Because you want higher precision than any of your other math packages give you? Because you object to the price of math co-processors, and you object to buying a PC into which to plug the co-processor?

Some months ago I wanted to calculate logarithms to 40 decimal places. So, I dashed off the enclosed code to let me handle big numbers. I had the choice of building a floating point or a fixed point package. I picked fixed point. It is not fast, it is not pretty, but it allows you to set the number of digits to each side of the decimal point to just about any size that will fit in your computer’s memory.

The Details

This package allows you to create “registers” and double “registers” named whatever you wish. For general purpose registers I usually name them X, Y, Z, etc. I usually name the double registers A, B, C, etc. to remind me that they are double. These registers are really strings of bytes in memory. Let’s assume you decide you want 10 places to the left and 20 places to the right of the decimal point.

30 CONSTANT #DIGITS ( set total number of digits)
20 CONSTANT #FRAC ( set number of digits to right) (of decimal)

The above code sets the total number of digits to 30 and the number to the right to 20 (thus the number to the left is 10).

Then we’ll set up some registers and double registers.

X: X Y: Y W: W (make some registers)
D: D AA BB (make some double registers)

X, for example, is 30 bytes long. Each byte holds a single decimal digit. Wasteful, you say? After all, we could stuff 2 decimal digits into each byte. The reason for using a full byte for each digit is it simplifies handling carries and borrows. Since each byte holds a digit no greater than 9, each byte will also hold the sum or product of any two digits. Thus, when we add two registers, we first add corresponding bytes together, without worrying about carries. Then we “normalize” the destination register so that each byte contains a number (digit) no greater than 9. The word ADD does both of these steps. Since the procedure for borrows is different than for carries, two words are available: NORMALIZE+ and NORMALIZE-. SUB uses NORMALIZE-. Suppose you want to add the contents of register X to the contents of register Y.

\[
\begin{align*}
X & \quad Y \\
\text{ADD} & \quad \text{does just that, leaving } X \text{ unchanged and leaving the sum in } Y. \\
Y & \quad X \\
\text{SUB} & \quad \text{Subtracts } X \text{ from } Y, \text{ leaving the difference in } Y \text{ and leaving } X \text{ unchanged.}
\end{align*}
\]

Multiplication and division are a little trickier. This is where the double registers become necessary.

Y X AA MUL will multiply Y times X and place the product into AA. It will leave Y and X unchanged.

\[
\begin{align*}
Y & \quad X \\
\text{DIV} & \quad \text{divides } Y \text{ by } X, \text{ leaving } Y \text{ and } X \text{ unchanged, and always placing the quotient into the double register named QUOTIENT.}
\end{align*}
\]

In addition to adding, subtracting, multiplying, and dividing two registers, we need the ability to initialize the registers, compare them, copy them to one another, and print their values. The word X1 (pronounced "x store") initializes a register. While we might like to do something like

75 X1

Many years ago Frank saw a proof that the square root of two was irrational, and, while he may never be a mathematician, he has developed a great deal of respect for those who are mathematicians.
this would only work for small numbers (16-bit numbers). What if we want to initialize the register to something like 1,392,459,667.000000000112397? So, X1 gets the initialization value from a string, as follows:

```
1,392,459,667.000000000112397
```

The Pygmy Forth Code

```
30 CONSTANT #DIGITS
20 CONSTANT #FRACS

'; CONSTANT PT (decimal point character)
#DIGITS 2* CONSTANT #DIGITS
#DIGITS 1- CONSTANT #DIGITS-1
#DIGITS constant #DIGITS-1
#FRACS 1- constant #FRACS

N: dup #DIGITS constant #DIGITS
M: dup #FRACS constant #FRACS

M: create (-) (- reg) #DIGITS allot
M: dup create (-) (- dreg) #DIGITS allot
M: u h v: w: n: k: i: j: x: (make some "registers")
M: i: du (double accumulator for multi & div)
M: zero (reg) #DIGITS 0 fill
M: dero (reg) #DIGITS 0 fill

; XI ( $ reg -)
( e.g. "12345.678" X1: )
( number must be positive number, with a decimal point)
DUP #ERO
PUSHiture 2DUP ( a @ a #)
PT -LEADING- 2DUP 1+UNDER 1-
#FRACS #DIGITS + SWAP CMOVE (move in fractional part)
SWAP DROP - (a @ a #)
#DIGITS OVER - #FRACS + SWAP CMOVE ( )
POP #DIGITS
FOR (a) DUP C8 DUP NOT NOT $30 AND - OVER C1 1+ NEXT DROP
; ;
; ; L: (a @ - a') FOR DUP C8 $30 + SWAP 1+ NEXT (a s ;
; ; L: (dreg - creg) #DIGITS .X PT EMIT #FRACS .X DROP ;
; ; DX (dreg - creg) #DIGITS .x 44 EMIT .X ;

; (scale number left or right - this can only be done to or
; from a double precision accumulator)
; REG1 (reg reg2 -) #DIGITS CMOVE
; DREG1 (reg dreg -) DUP DERO REG1 ;
; DREG8 (dreg dreg -) REG1 ;
; NORMALIZE (reg -) #DIGITS-1 0 (is initial-carry)
; #DIGITS FOR (a cy)
; OVER C8 + (a v-cy) 10 UMOD (a new-v new-cy)
; PUSH OVER C1 1- POP NEXT ("ABORT" overflow! "1") 2DROP ;
; NORMALIZE- (reg -) #DIGITS-1 0 (is initial-carry)
; #DIGITS FOR (a cy)
; OVER C8 + (a v-cy) 245 OVER U<< DUP PUSH 10 AND 10+
; (a new-v)
; OVER C1 1- POP NEXT ("ABORT" underflow! "1") 2DROP ;
; RIPPLE+ (reg n pos -) FOR OVER I DUP PUSH C8 +
; DUP 9 > WHILE 10 - POP C1 1 NEXT ELSE POP C1 POP
; THEN 2DROP ;
; RIPPLE+ (reg n pos -) FOR OVER I DUP PUSH C8 OVER * POP C1 NEXT DROP (reg)
; NORMALIZE+ ;
; (SCOMPLEMENT (reg @ -)
; FOR DUP I + OVER C8 - SWAP C1 NEXT DROP ;
; 9COMP (reg -) #DIGITS (SCOMPLEMENT)
; 9COMP (dreg -) #DIGITS (SCOMPLEMENT)
; ENDIGAITE (reg -) DUP 9COMP 1 #DIGITS RIPPLE+ ;
; ADD (reg reg -) #DIGITS FOR OVER I C8 OVER I DUP PUSH C8 +
; POP C1 NEXT NORMALIZE- DROP ;
; SUB (a b -) (a-b+ - a) SWAP (b a)
; #DIGITS FOR OVER I C8 (PV) OVER I +
; DUP PUSH C8 (b by sv) SWAP - POP C1 NEXT NORMALIZE- DROP ;
; XCOMP (reg reg2 - f) XCOMP -1 =
; X> (reg reg2 - f) XCOMP 1 =
; X> (reg reg2 - f) XCOMP 0 =
; X+ (reg - f) C8 4 SWAP UC ;

; LEFT-JUST (reg ! #places-shifted) PUSH 1+ DUP POP
1- 0 -LEADING- (a @ a +3 S) PUSH
(a @ a +3) DUP (a @ a +3) CMOVE (a @ a +3) OVER -
(a @ a) POP +UNDER (a @ a +3) DUP PUSH 0 FILL POP ;

; EOR (n reg -) SWAP (n reg n)
; @ #FRACS FOR '0 HOLD NEXT PT HOLD @ #6 DROP DUP DUP PAD C1
; PAD 1+ SWAP SWAP OVER C1 1+ NEXT DROP PAD SWAP R10 ;
; DREG10 (dreg -)
; DUP DUP 1+ #DIGITS-1 CMOVE> (dreg) 0 SWAP C1 ;
; MUL-STEP (reg dreg -)
; (reg dreg) DUP #DIGITS + C8 (is multiplier) #DIGITS IF
; #DIGITS FOR PUSH OVER C8 R8 + OVER C8 OVER C1
; -1 UNDER 1- POP NEXT SWAP 1+ NORMALIZE+ THEN 2DROP ;
; MUL+ (reg reg2 dreg -) (accumulating) DUP PUSH SWAP OVER
; (reg1 dup reg2 dup dreg)
; #DIGITS +UNDER CMOVE (reg1 dreg)
; #DIGITS-1 UNDER CMOVE (reg1 - dreg)
; #DIGITS 2DUP MUL-STEP POP R8/10 DUP NEXT 2DROP
; #FRACS FOR (dreg) DUP DREG10/10 NEXT DROP ;
; MUL (reg reg2 dreg -) (non-accumulating)
; DUP DERO MUL+ ;

M: DIVISOR M: TEMP1
M: DIVIDED M: DTEMP M: QUOTIENT

1x08 (a @ -)
(shift left 1 place; forces sign-digit to zero)
2DROP OVER 1- UNDER NOT CMOVE (a @ a)
+ 0 SWAP C1 DROP ;

REG10 (reg -) DUP #DIGITS-1 1X0 0 SWAP C1 ;

DREG10 (dreg -) DUP #DIGITS-1 1X0 0 SWAP C1 ;

ENDREG10 (dreg -) #DIGITS-1 1X0 ;

; REGS (-) DIVIDED .DX " by " DIVISOR .X
" . " -> " QUOTIENT .DX 8RROLL C1 ;

; (division divide r1 by r2 and put quotient into dreg)
; (both operands must be non-negative)
; DIV-INIT (r1 r2 -) @DIVISOR-shifts @DIVidend-shifts
; DIVISOR REG1 DIVIDED DUP DERO REG1 ( )
; DIVISOR @DIVISOR LEFT-JUST DIVIDED @DIGITS LEFT-JUST
; INITIALIZE DIVISOR ;

; DIV-STEP (-) DIVISOR @DIVIDED RREG 1@DIVIDED DTEMP (reg)
; DIVIDED DUP 14 C8 SNAP C8 10 + DIVISOR 14 C8 U/ (reg tquot)
; DUP QUOTIENT DUP DREG10 @DIGITS-1 C1 (reg tquot)
; @DIGITS RIPPLE- (is multiply diviser & trial quotient)
; ( ) DIVIDED DTEMP SUB ( )
; BEGIN DIVIDED 1X4 WHILE DIVISOR DIVIDED ADD
; QUOTIENT @DIGITS-1 1+ DUP C8 1- SNAP C1 INIT
; REPEAT DIVIDED 1X4DREG10+ ;

; DIV (dividend divisor -) DIV-INIT (a ! -)
; = @1FRACT + 2 + (for rounding)
; FOR DIV-STEP NEXT
; QUOTIENT DUP 5 @DIGITS RIPPLE+ DREG10/10 (round) ;

; TREP ($ - ) X1 X1 Y1 X Y X DIV .(" -> " QUOTIENT .DX ;
```

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To copy one register to another use REGI (pronounced "reg
store"), e.g.

X Y REGI: ( copy X to Y, leaving X unchanged)

The words ZERO and DZERO zero out a register or double
register, e.g.

X ZERO
AA DZERO

Comparison is accomplished by X<, X>, X=, and X0<, e.g.

X Y X< returns true if X is less than Y
X Y X> returns true if X is greater than Y
X Y X= returns true if X is equal to Y
X Y X0< returns true if X is less than zero

Printing registers is accomplished by X and .DX, e.g.

X .X prints the contents of register X
QUOTIENT .DX prints the contents of double register
QUOTIENT

How To Read The Source Code

In the stack comments a dollar sign represents an address of a
string, where the first byte contains a count and the following
bytes contain the string. Pronounce $ as "string."

FOR ... NEXT must be preceded by a <count>. In Pygmy,
the loop will be done <count> times. Within the loop, I is the
down-counting index. For example,

; TEST 10 FOR I. NEXT ;
TST
will print
9 8 7 6 5 4 3 2 1 0

Possible Enhancements

The names should be improved. The clarity of the code and
comments should be improved. Additional words are needed to
drop non-significant leading and trailing zeros when printing
registers. Furthermore, these large numbers are kept in fixed
locations. This is still very useful, but it might be more Forth-like
if they were kept on a stack.

References

I was encouraged in doing this after seeing John Wavrick's
polynomial math package; after all, a base 10 number *is* a
polynomial, i.e. a(10^0) + b(10^1) + c(10^2) + d(10^3) + ... +
z(10^25), if we keep 26 digits.

What's Next?

I titled this Part 1 in hopes there might be a Part 2 sometime.
Perhaps now that we can handle large numbers even on a little
micro we might do something useful with them. Suggestions and
very gentle criticisms are welcome.

Virtual BIOS, from page 29

It didn't improve things. In fact, it decreased performance. In
retrospect, the reason is obvious: it was not a good mapping
scheme for my system because the tracks on my Ampro do not
contain an even number of allocation blocks.

Double sided 96 TPI disks on the Ampro have 40 sectors per
track (5k bytes/track). The allocation block for those disks is 2k.
Thus, the last block on all even tracks is completed on the next odd
track. Normally, the next track is actually the next track (or
the other head on the same track). This is the case, too, with the "first
half reversed" system—with the single exception of the two tracks
on opposite sides of the halfway point. Not too much time is
spent getting to an adjacent track.

With the "even in—odd out" scheme, the next track is on the
other side of the disk—and gets further away as the disk fills. To
make things worse, after the "split" allocation block is read or
written, a trip to the directory is required to find the next allocation
block. Thus, the scheme actually causes more time to be spent
stepping the heads around the disk! The obvious solution would be to
map tracks in "pairs"—two tracks inward, two outward, etc.

Each system is different in it's use of the floppies. As I
mentioned above, different schemes exist for how tracks are
numbered on two-sided disks. Different systems also use differ-
ent physical sector sizes, resulting in differing number of CP/M
128 byte sectors per track. With proper attention to a machine's
disk system architecture, the mapping scheme can be quickly fine-
tuned for a system. Variations of the "odd in—even out" scheme
appropriate for the host machine should produce noticeable
improvement over what I've presented here.

PARTING SHOTS

What I've presented here is a NZCOM Virtual BIOS solution
that will produce a noticeable disk system performance increase
on any machine. This specific mapping scheme has worked well
for me in both sequential disk operations (system backups) and
random operations (normal use). Running time for application
programs that do a great deal of disk accesses—both sequential
and random—can be greatly reduced when their data files are on
disks with remapping enabled (try running FATCAT with the
data files on remapped disks!)

Remapping can be fine-tuned for a specific system. What I've
presented here will serve as a basis for system-specific schemes.
As a companion to this article, I've prepared a library named
SWBIO10.LBR which contains ready-to-load ZRL versions of the
virtual BIOS presented above, a compiled version of the SWAPV2C
manipulation utility, and a utility to initialize disk directories. This
file is likely to be available on your local Z-Node. If it isn't, you can
get copy from my system, The Elephant's Graveyard, at 619-270-
3184.

Moving?
Don't Leave Us Behind!
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YASMEM
(Yet Another Static Memory Expansion Module)

By Paul Chidley

Before I get into the Yasmem board let me update you on the Yaspect (Yaspect is the Yet Another Single Board Eight-bit Computer discussed in TCJ issues 51 and 52, "When eight bits is enough"). The monitor ROM for the Yaspect has been finished and running bug free for some time now. Wayne did an excellent job on the ROM and the documentation, the ROM is well suited to running the Z180 without any formal operating system. A non-banked BIOS starter disk is available from Cam Cottrill (see TCJ54 title?) and the banked version is under testing and may be ready by the time this is in print. I had a limited number of Eurocard backplanes for the Yaspect cards and can have more made if interest warrants it. We have a strong Yaspect topic going in the CF/M section of GEnie, over 140 messages since July 1980, as well as the occasional Yaspect Round Table (real time conference) night, so if you want the most up-to-date information I suggest looking into GEnie. It is the only place I regularly check my Email, usually every day. Anyway on to the Yasmem.

The Yaspect CPU card supports up to 1 Megabyte of SRAM on board, so why would anyone need a memory expansion board? Well the Yaspect has two 32 pin sockets for RAM so two 512K x 8 SRAM chips would provide the 1MB but monolithic versions of this chip do not commercially exist yet. There are modules available, at the time I wrote this article a 512K x 8 SRAM module, 32 pin 600 mil dip, 100ns, commercial temperature range, cost around $185 US in small quantities. On the other hand the 128K x 8 SRAM chips are around $22 so the 512Kx8 module is still twice the price of four 128Kx8 chips. This means that eight 128Kx8 SRAM chips and a memory expansion board are currently a cost effective solution until the 512Kx8 monolithic chips become a reality. The Yasmem was designed to provide my prototype system the full 1MB of SRAM and to test running programs in external RAM across the I/O connector and backplane. With eight 32 pin dip sockets on the Eurocard there was lots of space for a battery backup controller and two lithium batteries. Figure 1 shows the general layout of the board.

Figure 2 shows a partial schematic of the Yasmem board, the SRAMs were left off to save space. The backplane signals are fully buffered by U9, U10, U11 and U12. U12 driving the bi-directional data bus is a 74act245 while the other three buffers can be 74act245 or 74act541. The 541 is the logical choice for uni-directional signals but since a 245 is required for the data bus these buffers can optionally also be 74act245 by changing the R1 and R2 jumpers as indicated. The buffered address and data lines go directly to the SRAMs as required. Address lines A15-A19 and the control lines go to the 16L8 pal U13. Using a pal gives the flexibility to change the hardware address decoding as required depending on how the Yasmem is to be configured in your system. The pal does not do absolute address decoding, instead it decodes the desired board address down to three lines, these lines are then passed to the DS1211 (U14) which does a 1-of-8 decode to get the individual chips selects. In other words, when using 128Kx8 chips the address lines A17 through A19 are passed straight through but should you desire to make a 256K SRAM board using 32Kx8 chips only a new pal is needed.

The Dallas Semiconductor DS1211 is used on the Yasmem to give us battery backup control of the SRAMs. The features listed in the data sheet are;

- Converts full CMOS SRAMs into nonvolatile memories
- Unconditionally write protects when Vcc is out of tolerance
- Automatically switches to battery when power fails occurs
- 3 to 8 decoder provides control for up to eight CMOS SRAMs
- Consumes less than 100mA of battery current
- Tests battery condition on power up
- Provides for redundant batteries
- "Powerfail" signal can be used to interrupt processor on power failure
- Optional 5% or 10% power fail detection
- Available in 20 pin dip (DS1211) or 20 pin SOIC (DS1211S)

The DS1211 provides a 3 to 8 decoder to provide an active low chip select signal to one of 8 SRAMs. Input voltage (Vcc1) is monitored by comparing it to 4.75V or 4.5V depending on the level of the TOL pin (tolerance GND=4.75 Vcc=4.5). If Vcc drops below the tolerance level then write protection is accomplished by ensuring that all chip select outputs are held high to the SRAMs' Vcc (Vcc0). Vcc0 to the SRAM chips is switched from Vcc1 or the battery supply depending on which is greater. This provides constant power to the SRAM since the switch is transparent and with only a 0.2V drop. An internal switch also selects the battery voltage input that is greater, should a battery fail voltage input is transparently switched to the other battery. Battery voltage is also tested on power up, if the battery voltage is less than 2.0 volts then the SECOND access to memory is inhibited. A simply battery test can be done by the processor by reading a memory location, writing a different value to that memory location and then reading that memory location again. If the values read are equal then the battery voltage is too low since the write cycle was inhibited. This makes a great bug for people that forget about this feature and have a dead battery. If using one battery the other input must be grounded.

The flip flops of U15 provide an optional Wait state on opcode fetches, something that is not supported on the Yaspect. The Z180 has programmable wait states so why add hardware to do it here? Well I'm thinking of the day I install my 20MHz Z180 and 45ns expensive SRAMs. The Yaspect can have its fast CPU and fast SRAM running full speed with no wait states but the Yasmem will add one if its slower SRAM is accessed. So someday this will prove useful, for now I jumper mine to disabled so everything runs at full speed. (no need to slow down to access our bus) (yet)
Figure 1: YASMEM board layout
Photo 1: The YASBEC motherboard. This and all other YASBEC boards may be mounted on the Eurocard backplane.

Photo 2: The YASMEM memory expansion board.

Photo 3: YASBEC color graphics board.
Now that we have an external memory board we must configure memory in our Yasbec system. Like many things there are many ways to do this so here's my suggestion but I'm sure people will dream up other ways to do it. Use up to seven 128Kx8 chips on the Yasmem leaving the first 128K of physical space empty on the Yasmem. This would provide for a maximum of 896K of battery backed up memory for a RAM disk. On the Yasbec CPU the first 32K of physical memory is occupied by the monitor ROM. If using 32Kx8 chips, two would provide the 64K of system RAM needed for a non-banked system. If using a single 128Kx8 SRAM 32K would be missing due to the overlap with the monitor ROM leaving 96K free for a banked system.

I hope Yasbec users and others have found this article interesting. There are a good number of Yasbec systems out there up and running and installing their software. Enough people that a few of them should take the time to write an article for TCO. You know, "Yasbec from the Outside World" , "How I built my Yasbec", or the now infamous "How I let the Smoke Out". I'm sure inquiring TCO minds want to know.

As before, contact me by voice, GEmail, postal snail, et cetera, if you are interested in the Yasmem and/or Yasbec boards. I'm always available to answer questions but I am on Calgary (MST) time so give me a chance to get home from work before you call and be warned, if you wake me up it will be a very short answer.

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Figure 3: EuroCard backplane

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ZBest Software

By Bill Tishey

ZSUS News

Z3LBR Package: This package was completed last October and is the third in a series of "toolkits" which I have planned to organize the many Z utilities according to function. The first was Z3PROG (The Programmer's Toolkit) and the second was Z3WORD (The Z-System Text/Word Processing Toolkit). These packages are not just a dump of every utility available, but a careful selection with advice from others of the "latest and greatest" of tools in each category, including not only Z utilities, but (still essential!) CP/M programs. How do I decide what to include? Well, I have a few simple guidelines. Programs are generally not included if their functions are felt to be duplicated or improved upon in more recent or "modernized" tools. Tools with the same function are included if one is felt to have some unique, valuable feature. Some programs which perform the same function, however, are worth including simply because they are styled a bit differently (it's good sometimes to have alternatives). Let's look at Z3LBR.

Z3LBR contains Z-System and general CP/M programs useful in library and archive operations. It consists of three general groupings:

* LBR-member handling utilities (directory lists, file finders, typer, extractors, etc.)
* utilities for handling ARC, ARK, ZIP, and ZOO files
* major library shells and miscellaneous programs.

See Figure 1 for a list of the programs selected. Those with an asterisk are general CP/M programs.

Comments: This package contains plenty of tools and documentation for anyone interested in library/archive management. You'll note that LLF is included along with LDIRB. This is because, as we noted in TCI 51, LLF has the added ability to report member-file CRCs and member-file indices (both LDIRB and LLF, however, have been outdone by a new tool, LD—see the review below). Among unZIPpers, UNZIP099 is included along with UNZIP15 because of its unique ability to extract from SFX (self-extracting) ZIP files. And, while ZLT15 is the preferred library "typer", LT30 (now LT31) is also included for its ability to extract a file to a specified DU. VLU108 is included even though many complain of its limitations and, in particular, problems in preserving datestamps. The development of VLU was never fully completed and, depending on one's system, it may or may not work reliably as a LBR shell. Still, there are those who like its ZFILER-like interface and other features (for example, its handy way of making CRUNCH comments). For building LBRs, LPUT is a more reliable tool, is lightning fast, versatile and command-line oriented. LPUT and LBREXT, used either from the command line or in a combination of ZFILER macros and ARUNC scripts, are probably the safest Z-System tools to use in building and dissolving LBR files. Some programs not included in the package are: ZLDIR, EXL12, TYPETZ22, LRUNZ302, LCRC, and UNARC16. These were felt to be superseded by, respectively, LDIRB, LRREXT34, ZLT31, LX22, LREPORT, and UNARCZ13.

Other "toolkits" which I hope to make available in the future are ones dedicated to "file", "system", "disk/directory", and "date/time" management. If readers have other ideas, I'd be happy to hear them.

Z3COM Package Update: The ZSUS set of program executables (.COM files) was updated in November to include the latest versions of ZCPR3 and Z-System programs. This package now contains 641 files, totaling 2,696K and is bundled on 10 5.25 DDS disks for $50. Configuration files (.CFG), if available, are included in a separate CONFIG.LBR for convenient usage with ALHawley's new ZCNFG tool which recognizes .CFG files from within LBRs. The package also contains vital CP/

![Figure 1](image-url)

**Figure 1**

<table>
<thead>
<tr>
<th>Group #1</th>
<th>Group #2</th>
<th>Group #3</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL10 .LBR 25k</td>
<td>ARC-FILE.LIB* 5k</td>
<td>LJZ10 .LBR* 47k</td>
</tr>
<tr>
<td>LBREXT34 .LBR 37K</td>
<td>ARC20 .ARK 69k</td>
<td>LDIRB12 .LBR 24k</td>
</tr>
<tr>
<td>LBRHELP20 .LBR 45K</td>
<td>ARC20COM .LBR* 24k</td>
<td>LIBFILE .DOC* 8K</td>
</tr>
<tr>
<td>LDIRB22 .LBR 25k</td>
<td>ARK11 .ARK 16k</td>
<td>LFL22 .LBR 40K</td>
</tr>
<tr>
<td>LFIN3 .LBR 6K</td>
<td>BOSS4CPM .ARK* 34K</td>
<td>NULU152A .LAR* 55K</td>
</tr>
<tr>
<td>LFINDPAK .LBR 2k</td>
<td>UNARC13 .LBR 86K</td>
<td>VLU108 .LBR 46K</td>
</tr>
<tr>
<td>LIGT11 .LBR 5k</td>
<td>UNZIP099 .LBR* 16X</td>
<td>SLK27 .LBR 74K</td>
</tr>
<tr>
<td>LLF1 .LBR 10k</td>
<td>UNZIP15 .LBR 23K</td>
<td>UNZIP15 .LBR 23K</td>
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<td>LLFPAPAK .LBR 2k</td>
<td>ZIP-APP .LBR* 7K</td>
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<tr>
<td>LPUT22 .LBR 35K</td>
<td>ZIPDIR12 .LBR 21K</td>
<td>UNZIP15 .LBR 23K</td>
</tr>
<tr>
<td>LREPORT .LBR 9K</td>
<td>UNZIP15 .LBR 23K</td>
<td>UNZIP15 .LBR 23K</td>
</tr>
<tr>
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<td>UNZIP15 .LBR 23K</td>
<td>UNZIP15 .LBR 23K</td>
</tr>
<tr>
<td>ZZT15 .LBR 39K</td>
<td>UNZIP15 .LBR 23K</td>
<td>UNZIP15 .LBR 23K</td>
</tr>
</tbody>
</table>

Bill Tishey has been a ZCPR user since 1985 when he found the right combination of ZCPR3 and Microsoft's Softcard CP/M for his three-year-old Apple II+. After graduating to ZCPR30 and PCP's Application CP/M, he did a "manual install" of ZCPR3.3 (with help from a lot of friends!), and in late 1988 switched to NZCOM and ZSDOS, all on the same vintage Apple II+. Bill is the author of the ZHELP system, a monthly-updated system of help files for Z-System programs, as well as comprehensive listings of available Z-System software and is the editor of the Z-System Software Update Service.

Bill may be contacted on CompuServe (76320,22), GENIE (WATISHE), on Jay Sage's Z-Node #3 (617-965-7259) and by regular mail at 8335 Dubs Drive, Severn MD 21144.
M programs such as CRUNCH, UNCR, and NULL.

Z3HELP System Update: I went on a blitz during the first part of November to update the Z3HELP system and by mid-month managed to bring it current with existing releases. Of course, I'm now several months behind again, but I always look forward to examining the new creations. Over 100 files were modified and an additional 50,000 was added to the last release (04/18/91) of the system. The only new format change is the use of the "y" LBR now for help for all the Libraries and related programming modules and routines. Users can update their current setups by picking up the update LBRs (Z3HELP43, 43B, 43C, 43D) on various Z-Nodes. Since these are over 400k, however, you might find it easier to acquire the entire system anew. Z3HELP sells for $30 (6 disks, now totaling 1,700k). Current ZSUS subscribers and Z-Node SYSPs get it for half the price ($15). For those not interested in source code, who want the complete complement of Z-System software, I think that the combination of the ZCOM package and the ZHELP package (for on-line documentation), is an excellent alternative to downloading or purchasing the many individual Z-System distribution LBRs.

The Value of User Input

The team of Z-System developers works hard to refine and enhance the Z utilities we use. A lot of thought is given to any changes suggested for a program and much care is taken when any improvements are implemented. Upgrades are released usually after consultation with other authors and after much testing for the problems which can surface when programs are modified.

The developers, however, can’t uncover every bug and can’t foresee every situation in which a program will be used. They also must rely on users’ input. Here is what Jay Sage had to say recently to one programmer who seemed somewhat discouraged over an undetected problem:

"Actually, I think the reason why no one else had reported the problem before is low expectations, but not with respect to you, but with respect to themselves. Many users, when they experience a problem, seem to assume that it is their fault. They think that we programmers are too good to make mistakes! I have found some pretty serious bugs in some of my own programs that could not possibly have gone unnoticed by the entire user community. What those users don’t realize, I think, is how helpful they could be by pointing out not only full-fledged bugs but also features they don’t like."

Enough said? The Z team values your comments and suggestions. They take pride in their work and like to know that their programs are meeting your and their expectations!

New Releases and Updates

Since I missed the last issue (I apologize for that), I have four months to make up in discussing Z-System program development! Listings 1 and 2 I think prove that there were warm fingers on at least some keyboards this winter. Thanks go to the editor for giving me the space this issue to bring you up to date.

Terry Hazen: EDZCM10, ENVCFG12, JTHLB12, DATEFIN11, DD19, ENVSR12, NZTIM12, PRNTXT16, REMIND15, RENAMZ19

Terry is famous for his fine line of system utilities which operate in both ZCP3 and CP/Environments (ACOPY, RENAMZ, ERA, UNERAZ, DD). He has also released some interesting tools which help to simplify making changes to the Z-System environment. (Note his article on IOPLDR in TCJ/53).

EDZCM10 (ZSUS V3 #2) is a screen-oriented editor for NZCOM "ZCM"
copy of the current environment into ENVCFG.COM's buffers, allows configuring of the contents of those buffers, saves the modified configuration to memory, then clears the contents of the buffer in ENVCFG.COM. The new ZENV can also be saved to a specified file (ENV is the default filename).

Two related tools which Terry developed some time ago are ENVSRC, which creates a commented source code file (ZENVZ80) from the Z3 environment, and TSRC, which creates a source code file (MYTERM.Z80) from a given terminal file (MYTERM.Z3T). The source code output from both of these programs can be used as a reference for patching or can be edited themselves, assembled and loaded to install changes to the environment.

Terry has also released his set of custom routines (JTHLIB12), originally developed for use in REMIND and ZF, which are modified versions of various SYSLIB, ZSLIB and VLIB routines. Vers 1.2 fixes a bug in the FNAMZ filename scanner and adds extended versions of VLIB routines GXYM5G, VPRINT and VPSTR.

Terry's other updates include:

- DAFNFIN1—fixes a hi-bit filtering problem with the help filename and adds JTHLIB filename display calls.
- REMIND5—the "upcoming month" display now highlights the current date and offers three options: C—display current month's upcoming reminders, A—display all upcoming reminders and N—no upcoming reminders.
- RENAMZ19—several new options include the ability to add or delete filename prefixes.
- DD19—now displays the status line on user abort as well as at normal exit; adds a printer init string.
- PRNXT16 (ZSUS V3 #2)—now ZCNFG configurable and includes a printer status check.

Gene Pizzetta: CONCAT16, CRCBLD14, D21, DATSTP19, ECHO14, ERASE57, FA16A, FILT81, FL10, JUST13, LCS10, LD11, PRETTY31, RCOPY21, SWZ10, UMAP18, XOR15, ZSLB34, ZTIME14

Remember the excitement over XFOR, which we covered in depth in TCJ497? Well, Gene has developed another utility based on collaboration similar to that with XFOR. While Gene was working on CPD, his "Compare Directory" utility, he noted that there was no comprehensive set of routines for reading and generating lists of disk files. None of the current directory listsers, for example, can output a single-column list of files. It became evident that some generalized routines were needed for handling file lists from within programs as well as a separate directory utility that specialized in creating disk-based file lists. Well, Gene has come up with both!

Gene describes his approach to reading disk-based file lists thus: "Filelist processing is accomplished as a stream, with the end of a filename assumed when the read routine reaches a comma or a non-printable character. This is not only efficient, but allows..."
using lists produced by the likes of dBASE and BASIC. Multiple non-printable characters are simply skipped over. This allows certain control characters to be used as markers in the list, either to tag particular files or to mark blocks of files."

Gene makes use of the new routines in RCOPY21, CPD15, and the new FL10, and other programmers are now considering their use. Rob Friefeld’s new version of ZFILER (ZF10Q) writes out tagged files to disk so that the tagging can be preserved across macro invocations. Gene’s routines raise the possibility of tagging files based on datestamps, etc., without having to add considerably to ZF’s code. Rob’s XOX utility presently uses a complex internal file list generator and might also benefit from this being handled externally to the program. Gene is also thinking of modifying WCOM to read file lists for programs that don’t otherwise handle them. He suggests that versions of CRUNCH and UNCR which handle lists might also be handy.

Now let’s look at Gene’s FILELIST (ZSUS V3 #3), a ZCPR3 utility which creates file lists on disk for use by other programs. See Figure 3 for FL’s usage screen and some sample displays.

FL allows multiple ambiguous file specs, including a negative specification (filespec preceded by a tilde). The error flag is set if no matching files are found. Matching filenames are written to a disk file, in uppercase, one name per line in standard command line format ("filenametypes"). Optionally, the DU in which the file is located can be included with the filename. As is customary with Gene’s utilities, a number of configuration options are available using ZCNFG: display of filenames in uppercase or lowercase; output of FILELIST to either the currently logged or target directory; giving FILELIST a different name; setting the error flag and invoking the error handler on abort (to allow aborting a ZEX or SUB batch operation).

Like XPOR, FL offers a lot of possibilities for enhancement and we should see a number of future upgrades. Some sophisticated negative filespecs might be possible, for example, as well as an ability to select files by attributes or combinations of attributes.

Another of Gene’s accomplishments is LD (ZSUS V3 #2), his new Library Directory tool. LD is based on LDIR-B, but is intended to be much more versatile, with numerous command line and configuration options, and making more extensive use of Z-System facilities, while remaining compatible with vanilla CP/M and Z3PLUS. See Figure 4 for LD’s help screen and several sample displays.

LD’s many options set it apart from other LIB directory listers: embedded comments can be displayed on a separate line (up to 76 characters); an alternate display provides member names, sizes, CRC’s, and indexes in two-column format; the number of matching members and free library directory entries can be stored in message registers; and printer output and wheel protection are supported. All this and more in less than 4k.

Gene’s other updates include:

- CONCAT16 (ZSUS V3 #2)—Many changes have been made since vs
1.4: CON; LST; and AUX; can be used in place of the destination file; a new "P" option page output to console or printer; a new "H" option resets hi-bits and removes control characters from the screen; the "I" option doesn’t have to be at the end of the option list; new, more specific error messages; more configuration options; ZSLIB HV routines are now used in place of larger VLIB ones.

- **CPD15 (ZUS V3 #3)—**Since version 1.0, options have been added to 1) include DU specs with filenames in the CPD1ST output file; 2) output matching filenames to a diskfile; and 3) suppress console output. More configuration options have been added, changes to the display and usage screen, bug fixes and code optimization. CFD is also much faster now that both directories to be matched are loaded into memory. D21—adds several new features; fixes some long-standing bugs; now works under vanilla CP/M.

- **DATSTP19—**VLIB references have been replaced with much shorter ZSLIB3 routines, keeping the executables to 6k and under.

- **ECHO14**—corrects a problem when running under BYE; adds matching RCPECHO, Type 3 and Type 4 versions, and ZCNPFG configuration.

- **ERASE5—**adds a Type 4 version; the Type 5 version has been made CPM-safe; the program banner is improved; some code changes help keep the size to 4k.

- **FA16A (ZUS V3 #3)—**FILEATTR is a utility to quickly set, reset, or display file attributes. It was originally distributed with ZSDOS and has since been made compatible for use under ZSDOS, ZRDSO, and CP/M 2.2. Under ZCNPFG, it allows error flag setting, error handler invocation, and an enhanced display. FA16A adds much needed documentation.

- **FILT81 (ZUS V3 #3)—**now checks for ambiguous filenames; the display of line count progress reports is now a configuration option.

- **JUST13 (ZUS V3 #2)—**same changes as made to FILT81.

- **PRETTY31—**cases of labels and opcodes are now a command line option; adds a few SLR and ZMAC pseudo-ops to the table; a bug fix, some minor code tweaks.

- **RCOPY21—**corrects a bug in the listfile parsing routine.

- **UMAP18—**corrects a problem when running under BYE; other minor changes.

- **XFOR15 (ZUS V3 #2)—**now prints the "searching" message only when a
search string is given, not after each entry during sequential FOR file displays.

- ZSLIB34—adds switchable output routines and makes some bug fixes.
- ZTIME14—rereads the clock after setting it; corrects some parser bugs; adds Type 3 and Type 4 versions.

Bruce Morgen: MNU42, PWD21, SAVNDR14, SUB35, Z33IF16

Bruce continues to bring some of the oldest but still useful Z-System utilities up to "modern" standards.

In SUB35, Bruce has made some ambitious improvements while still preserving backward compatibility with scripts written for SUBMIT, SUPERSUB, and previous versions of the ZCTR3 SUB series. Probably most significant is the ability to read SUB scripts from a standard LBR file. Like ZCNFG's CFG files, SUB files tend to be very short and quickly eat up disk space. It makes sense to bundle them into LBRs. SUB scripts can now be searched in LBRs 1) from the command line in the same manner as LX—"SUB [ D I R : ] . L B R N A M E [. T Y P ]" [or 2] by searching a user-patched library after the search for a standalone SUB script has failed.

SUBINST.COM is provided to patch the name and location of this secondary library. SUB35 also recognizes the UNIX-style "*" (entire command line) parameter, supports Z34ERR12-compatible error handling, and observes the Z3ENV quiet flag.

Bruce's other updates include:

- MNU42—adds direct support for Bridger-Mitchell's "AT" background timer and shrinks the tool back to its 1984 size of 4k.
- PWD21—adds a Type 4 version; improves the program banner; uses the new ZSLIB video highlighting routines in place of the larger VLIB routines.
- SAVNDR14—implements a Type 4 version; adds the Type and load address to the program banner; contains some minor code changes.
- Z33IF16—uses the new ZSLIB video highlighting calls in place of VLIB ones. Two other developments have to be mentioned before closing out this rather lengthy column:

Howard Goldstein has reworked the Z-System Help tool into a version which will read LH4-encoded help files (HYP). HELPLZHL.BR (ZUS V3 #3) contains HELPCH.COM, which handles standalone files, and LH.H.COM, which handles files within libraries.

HELP.COM 1.1b 4 0 3 21 69CB HELPLEH 3 01/06/92 Rob Frield HELP Help program for LH4 vs 1.1.
HLP=Y line and prompts for erase or read-only files.
CFO=Y Vs. 5.0 (05/84) by Richard Conn.

FILE.COM 8.10 0 V302 4 30 0393 FILEZ81 24 10/03/91 Gene Pizzetta
WP EP3R rework of Irv Hoff's FILEZ tool which sets or expands tabs and
HLP=Y removes several types of unwanted characters in ASCII text, WordStar
CFO=Y documents or assembler source code files.

HELM5.COM 3.10 0 0 1 12 69CB HELM5H 3 01/06/92 Rob Frield
HEL Help program for LH4 vs 1.1.
HLP=Y and processes commands from it.
CFO=Y

JUST.COM 1.10 0 V302 4 32 A6A9 JUST13 41 10/03/91 Gene Pizzetta
WP EP3R rework of Irv Hoff's tool to justify ASCII and WordStar text
HLP=Y Full command line operation, DU support, error-flag setting,
CFO=Y Quiet mode, and transfers create datestamp under ERDOS.

LF.COM 3.10 0 0 1 54 E898 LZ31 64 12/16/91 Brian Murphy
LIB Library Type can type normal, LH4-encoded, crooked or squashed file
HLP=Y whether standalone or in a .LBR. Can extract/uncrunch any/all files
CFO=Y at the same time. Adapted from Steve Holtzman's LKUTEP (06/83).

MNU42.COM 4.20 0 0 4 32 2437 MNU42 48 10/30/91 Bruce Morgen
SHIELD The EP3R menu front-end processor. Shell which reads a .MNU file
HLP=Y and processes commands from it.
CFO=Y

NETH.REL 1.20 4 0 3 24 2678 HETH12 43 01/27/92 Terry Hansen
PROorgetown Library of Date/Time subroutines which allow data or pointers to data
HLP=Y to allow utilities to do whatever necessary with Date/Time. Entirely
CFO=Y self-contained. Original (2/10/90) by Joe Wright.

POAT.REL 1.20 4 0 3 24 0001 HETH12 43 01/27/92 Terry Hansen
LIBRARY Library of runtime utilities which use NETH and SYSLIB routines to print
PROUCCEEDED various forms of Date and Time. Original (2/10/90) by Joe Wright.
CFO=Y

PRETTY.COM 3.10 0 0 5 38 CDUS PRINTY31 32 10/03/91 Gene Pizzetta
PROOOG Standardizes the case of opcodes and labels in Z80 and 8080 source
PRG=Y code. Based on Carroll Bryan's PRETTY33. Preserves create date
CFO=Y stamps under ERDOS. Compatible with ZCNFG.

PRINT.COM 1.60 0 V302 1 6 E93D PRINTED16 26 10/05/91 Terry Hansen
STS Console/printer merge utility program which creates "instant"
HLP=Y text display .COM files to the console or printer.
CFO=Y

PWD.COM 2.10 0 0 4 25 E13E PWD21 48 11/12/91 Bruce Morgen
PWD.COM 2.10 3 0 4 25 A760 PWD21 48 11/12/91 Bruce Morgen
PWD.COM 2.10 4 0 4 30 CD84 PWD21 48 11/12/91 Bruce Morgen
STS Displays the names of DU and DIR names with paging.
HLP=Y Vs 1.0 (03/84) by R. Conn.
CFO=Y

RCCRTY.COM 2.10 0 0 4 29 E445 RCCRTY21 24 01/11/92 Gene Pizzetta
FILE Copies a list of files between two directories.
HLP=Y
CFO=Y

REND.COM 1.50 0 5 39 3730 RENIND15 38 01/26/92 Terry Hansen
DATE Appointment reminder utility for EP3R and ERDOS with clock. Will
CHP=Y display and optionally print a sorted and paged list of dated appointment
CFO=Y reminder lines with optional time entries from a text datafile.

RENAME.COM 1.90 0 5 53 9F33 RENAMS19 64 11/08/91 Terry Hansen
FILE Enhanced ERDOS renaming utility for CP/W 2.2 and EP3R's CP/W's
HLP=Y running under CP/W 2.2, ERDOS, ERDOS, and ERDOS. Companion to
CFO=Y ACOPY, DD, ERA4, and UNERA. Vs 1.0 (04/87) by Terry Hansen.

SAVSNTRY.COM 1.40 0 0 2 12 5A49 SAVVDR14 12 11/22/91 Bruce Morgen
SAVSNTRY.COM 1.40 3 0 2 12 00C2 SAVVDR14 12 11/22/91 Bruce Morgen
SAVSNTRY.COM 1.40 4 0 2 16 1E97 SAVVDR14 12 11/22/91 Bruce Morgen
NDR Writes a reloadable (by LDR) copy of the resident Named Directory
HLP=Y module to a disk file.
CFO=Y

SCOPY.COM 0.80 0 4 15 120 D4DB SCOPY08 26 10/21/91 Rob Frield
FILE Screen-oriented file copy utility. Displays source and destination
HLP=Y directories in vertical windows. FP-like commands. Supports file
CFO=Y selection and copy by datestamp. Extended TCP required.

The Computer Journal / #55
Rob Friefeld has released an update to ZFILER (ZF10Q) with the following enhancements: 1) the ability to filter VIEW and PRINT output (high bits are removed, only alphanumerics, CRs, and LFs are printed, and TABs are expanded); 2) the ability to remember all the file tags on return from a Z command or macro run (mentioned above). The file list is written to a temporary disk file (ZFILER.TAG, in a configurable directory), and automatically read back. 3) The ability to set the Group Tag/Untag and Wild Tag/Untag to work on the entire ring, or just from the file pointer (Group Reverse always works on the entire ring). List macros now soft-tag files just like regular group macros.

Z Message Base

Question: What is the acceptable way of handling the quiet flag? Answer: I usually handle the quiet flag this way:

a. The program has a configuration byte that allows setting it to default to quiet mode.

b. If the quiet flag is set, the program defaults to quiet mode no matter how the configuration byte is set.

c. The command line option toggles whatever is the current default, whether the default has been set by the configuration byte or the quiet flag.

Many programs I have released use this method, including DATSTP, CONCAT, etc. (Gene Pizzetta, Z-Code #3, 2/2/92) ●

"Reading made Don Quixote a gentleman, but believing what he read made him mad." —George Bernard Shaw
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The Computer Corner

By Bill Kibler

A new year has started and with it a few new leaves are being turned over by myself. Hopefully I am getting ahead of things as I will be moving houses again soon. What I want to cover this time is some understanding about a few key words I use. They are important words and as such I feel a whole article on them is needed.

READABILITY

is my first word and is not what most users understand it to mean. To me to be readable, in the case of a manual, is not just covering all the topics, but educating the reader as well. To be readable it must have a clearly defined structure. The reader needs to be able to find items of interest quickly. The structure must be clear enough that a reader can see the structure and start using it immediately.

This topic is fresh with me as I have been spending a large amount of time with one of our technical writers. We have a new product going out and thus a new manual. They had taken an old manual and just changed a few key words and items. Well, that was until I hit my desk for review. To say the red ink flowed over many pages would be an understatement. I feel the writer had never had anybody in the company ever really review one of his manuals before.

What am I changing to make the manual more readable? The first problem was a lack of structure. The installation section ran on forever and intermixed topics and instructions. The new manual now has a clear introduction that describes terms used and how things work. That brings the reader up to the point of knowing what and why the remaining steps are needed. Those steps now are broken into separate chapters or sections that coincide with a logical grouping of needed actions.

In short, the document lacked any clear structure. It was almost impossible to find a given topic without some hunting and then the why or how of the function might not be apparent. That “how and why” is actually very important as it helps the reader weigh the information for relevance to their needs. I remember reading one section and thinking we had already covered it, when I suddenly discovered the topic was actually different. The problem was two terms that were very close to each other.

I can not complain about the use of terms enough. We all have had troubles with acronyms. Those wonderful two and three letter statements that mean nothing and are never explained. Manuals are full of them and my complaint is they do not get explained often enough. Do it once or twice a section at least. But another problem with terms is use of similar or repetitive terms. In our example was the overly used term “file”.

I am sure we all have seen the term file used 10 or 15 times in one paragraph. How many of you can keep track of which file we are talking about. In our manual it wasn’t even a file, but really a list of lists stored in a file structure. We have multiple indexes into these lists which determine which file gets sent to where (see even describing the problem gets confusing). The manual referenced the list as “XX file” and then said it loaded files from it. Not only was it confusing but inaccurate as well. The solution involved explaining that it was a list. Then explaining how the list is multiply indexed. Lastly we showed the relationship between the indexes and the file name that was ultimately loaded.

STRUCTURE

I could go on with the manual problems and pick over lots of the fine points. The objective here is to get you to save time and money when preparing your own manuals. I say this after having seen a friends manual he product for his new product. His first problem was size, over an inch of standard letter size pages. The printing cost are about $15 each and the labor cost had he paid for them are enormous. The reason I feel it was wasted was lots of extra work was performed that will not return him any buyers.

Now writing to sell is not the best way to write a manual. Writing with a clearly defined audience and structure will however produce a readable and marketable item. How so? Over the years I have used the structure that says a manual should be broken into a beginners, intermediate, and advanced section. I find that idea is sound no matter which group is using the document. Sales literature, flyers, and each section of a manual can also use this structure. We start a sales pitch with the old adages of tell them “WHO, WHAT, and WHY”.

I have changed the who, what, why, to introduce it, explain it, and show it off. These really are still my favorite structures of beginner, intermediate, and advanced. Remember that whenever you start a new topic or look at a new product your start as a beginner. You learn enough about it to then start asking questions about what it will do for me. At that point you have passed into the intermediate state where we then start asking question like “why can’t I do this or that”.

My suggestion to my friend was change his structure. Most of the information has already been written, it just needs to be restructured. I feel also that as he restructures he will see that many items and topics are covered more than once. Once the structure is clearly outlined it also makes it possible to judge the content of sections. Too often I find whole subsections that just do not belong either in that location or in the manual.

When talking about sales, I like the clear structuring as it allows for a single section (usually the beginners section) to be pulled out and shipped to would be buyers. That may also help you understand the importance of what a buyer looks for in a manual. I have my own items I check for before buying as I am sure you do to. I find however that most people check out items like indexes, table
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